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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	LINbus, SIO, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	25
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 5.5V
Data Converters	A/D 9x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f212l2sdfp-x6">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f212l2sdfp-x6</a>

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## 1. Overview

### 1.1 Features

The R8C/2K Group and R8C/2L Group of single-chip MCUs incorporates the R8C/Tiny Series CPU core, employing sophisticated instructions for a high level of efficiency. With 1 Mbyte of address space, and it is capable of executing instructions at high speed. In addition, the CPU core boasts a multiplier for high-speed operation processing.

Power consumption is low, and the supported operating modes allow additional power control. These MCUs also use an anti-noise configuration to reduce emissions of electromagnetic noise and are designed to withstand EMI.

Integration of many peripheral functions, including multifunction timer and serial interface, reduces the number of system components.

Furthermore, the R8C/2L Group has on-chip data flash (1 KB  $\times$  2 blocks).

The difference between the R8C/2K Group and R8C/2L Group is only the presence or absence of data flash. Their peripheral functions are the same.

#### 1.1.1 Applications

Electronic household appliances, office equipment, audio equipment, consumer equipment, etc.

## 1.1.2 Specifications

Tables 1.1 and 1.2 outlines the Specifications for R8C/2K Group and Tables 1.3 and 1.4 outlines the Specifications for R8C/2L Group.

**Table 1.1 Specifications for R8C/2K Group (1)**

Item	Function	Specification
CPU	Central processing unit	R8C/Tiny series core <ul style="list-style-type: none"> <li>• Number of fundamental instructions: 89</li> <li>• Minimum instruction execution time:               <ul style="list-style-type: none"> <li>50 ns (<math>f(XIN) = 20</math> MHz, <math>VCC = 3.0</math> to <math>5.5</math> V)</li> <li>100 ns (<math>f(XIN) = 10</math> MHz, <math>VCC = 2.7</math> to <math>5.5</math> V)</li> <li>200 ns (<math>f(XIN) = 5</math> MHz, <math>VCC = 2.2</math> to <math>5.5</math> V)</li> </ul> </li> <li>• Multiplier: 16 bits <math>\times</math> 16 bits <math>\rightarrow</math> 32 bits</li> <li>• Multiply-accumulate instruction: 16 bits <math>\times</math> 16 bits + 32 bits <math>\rightarrow</math> 32 bits</li> <li>• Operation mode: Single-chip mode (address space: 1 Mbyte)</li> </ul>
Memory	ROM, RAM	Refer to <b>Table 1.5 Product List for R8C/2K Group</b> .
Power Supply Voltage Detection	Voltage detection circuit	<ul style="list-style-type: none"> <li>• Power-on reset</li> <li>• Voltage detection 3</li> </ul>
I/O Ports	Programmable I/O ports	<ul style="list-style-type: none"> <li>• Input-only: 3 pins</li> <li>• CMOS I/O ports: 25, selectable pull-up resistor</li> <li>• High current drive ports: 8</li> </ul>
Clock	Clock generation circuits	2 circuits: XIN clock oscillation circuit (with on-chip feedback resistor), On-chip oscillator (high-speed, low-speed) (high-speed on-chip oscillator has a frequency adjustment function) <ul style="list-style-type: none"> <li>• Oscillation stop detection: XIN clock oscillation stop detection function</li> <li>• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16</li> <li>• Low power consumption modes:               <ul style="list-style-type: none"> <li>Standard operating mode (high-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode</li> </ul> </li> </ul>
Interrupts		<ul style="list-style-type: none"> <li>• External: 4 sources, Internal: 15 sources, Software: 4 sources</li> <li>• Priority levels: 7 levels</li> </ul>
Watchdog Timer		15 bits $\times$ 1 (with prescaler), reset start selectable
Timer	Timer RA	8 bits $\times$ 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode
	Timer RB	8 bits $\times$ 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode
	Timer RC	16 bits $\times$ 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)
	Timer RD	16 bits $\times$ 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period)

**Table 1.4 Specifications for R8C/2L Group (2)**

Item	Function	Specification
Serial Interface	UART0, UART2	Clock synchronous serial I/O/UART × 2
LIN Module		Hardware LIN: 1 (timer RA, UART0)
A/D Converter		10-bit resolution × 9 channels, includes sample and hold function
Flash Memory		<ul style="list-style-type: none"> <li>• Programming and erasure voltage: VCC = 2.7 to 5.5 V</li> <li>• Programming and erasure endurance: 10,000 times (data flash) 1,000 times (program ROM)</li> <li>• Program security: ROM code protect, ID code check</li> <li>• Debug functions: On-chip debug, on-board flash rewrite function</li> </ul>
Operating Frequency/Supply Voltage		f(XIN) = 20 MHz (VCC = 3.0 to 5.5 V) f(XIN) = 10 MHz (VCC = 2.7 to 5.5 V) f(XIN) = 5 MHz (VCC = 2.2 to 5.5 V) (VCC = 2.7 to 5.5 V for A/D converter only)
Current consumption		Typ. 10 mA (VCC = 5.0 V, f(XIN) = 20 MHz) Typ. 6 mA (VCC = 3.0 V, f(XIN) = 10 MHz) Typ. 23 μA (VCC = 3.0 V, wait mode, low-speed on-chip oscillator used) Typ. 0.7 μA (VCC = 3.0 V, stop mode)
Operating Ambient Temperature		-20 to 85°C (N version) -40 to 85°C (D version) <sup>(1)</sup> -20 to 105°C (Y version) <sup>(2)</sup>
Package		32-pin LQFP • Package code: PLQP0032GB-A (previous code: 32P6U-A)

## NOTES:

1. Specify the D version if D version functions are to be used.
2. Please contact Renesas Technology sales offices for the Y version.

## 1.2 Product List

Table 1.5 lists the Product List for R8C/2K Group, Figure 1.1 shows a Part Number, Memory Size, and Package of R8C/2K Group, Table 1.6 lists the Product List for R8C/2L Group, and Figure 1.2 shows a Part Number, Memory Size, and Package of R8C/2L Group.

**Table 1.5 Product List for R8C/2K Group**

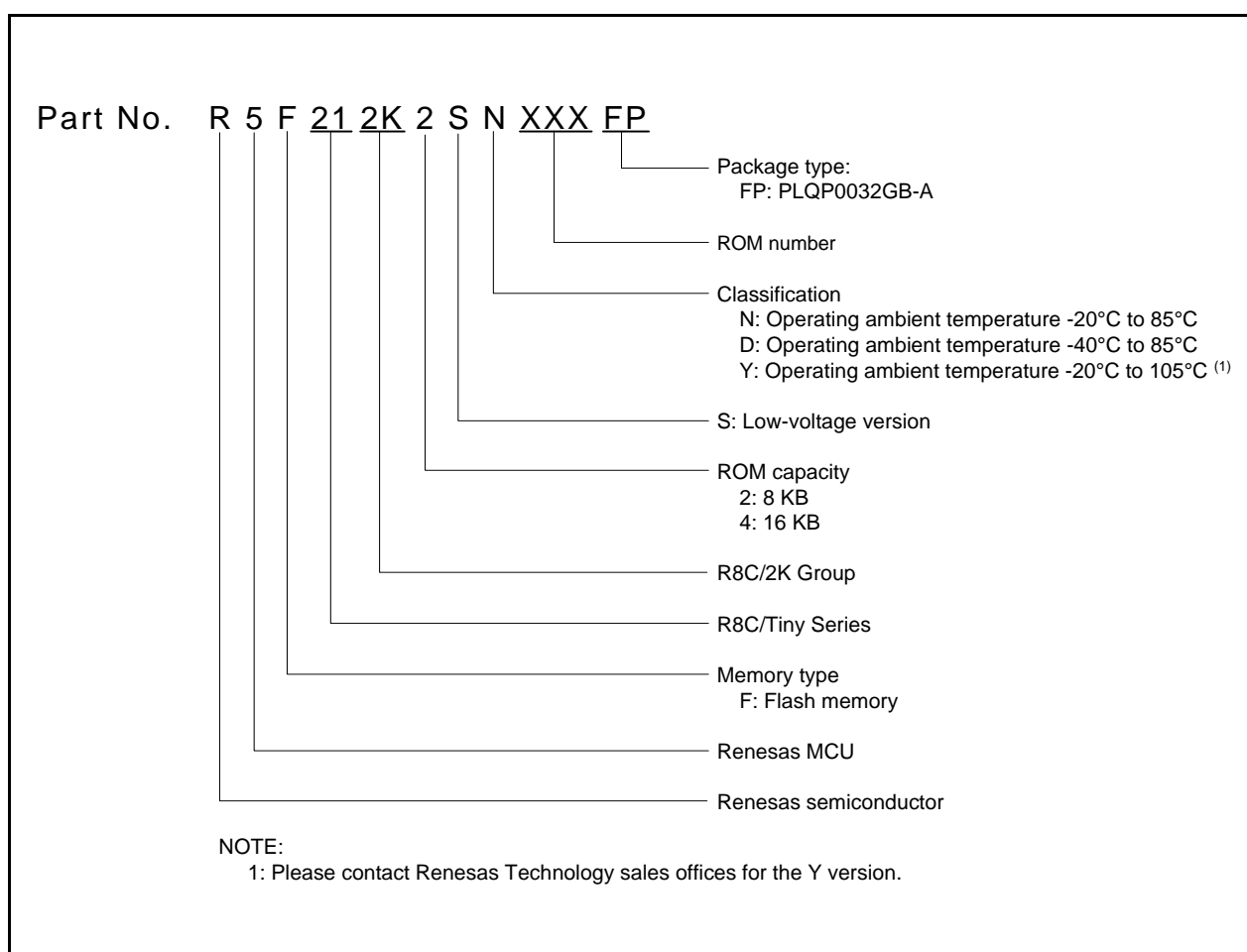
**Current of Dec. 2007**

Part No.	ROM Capacity	RAM Capacity	Package Type	Remarks
R5F212K2SNFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version
R5F212K4SNFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SDFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version
R5F212K4SDFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SNXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version Factory programming product <sup>(1)</sup>
R5F212K4SNXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SDXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version Factory programming product <sup>(1)</sup>
R5F212K4SDXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	

(D): Under development

NOTE:

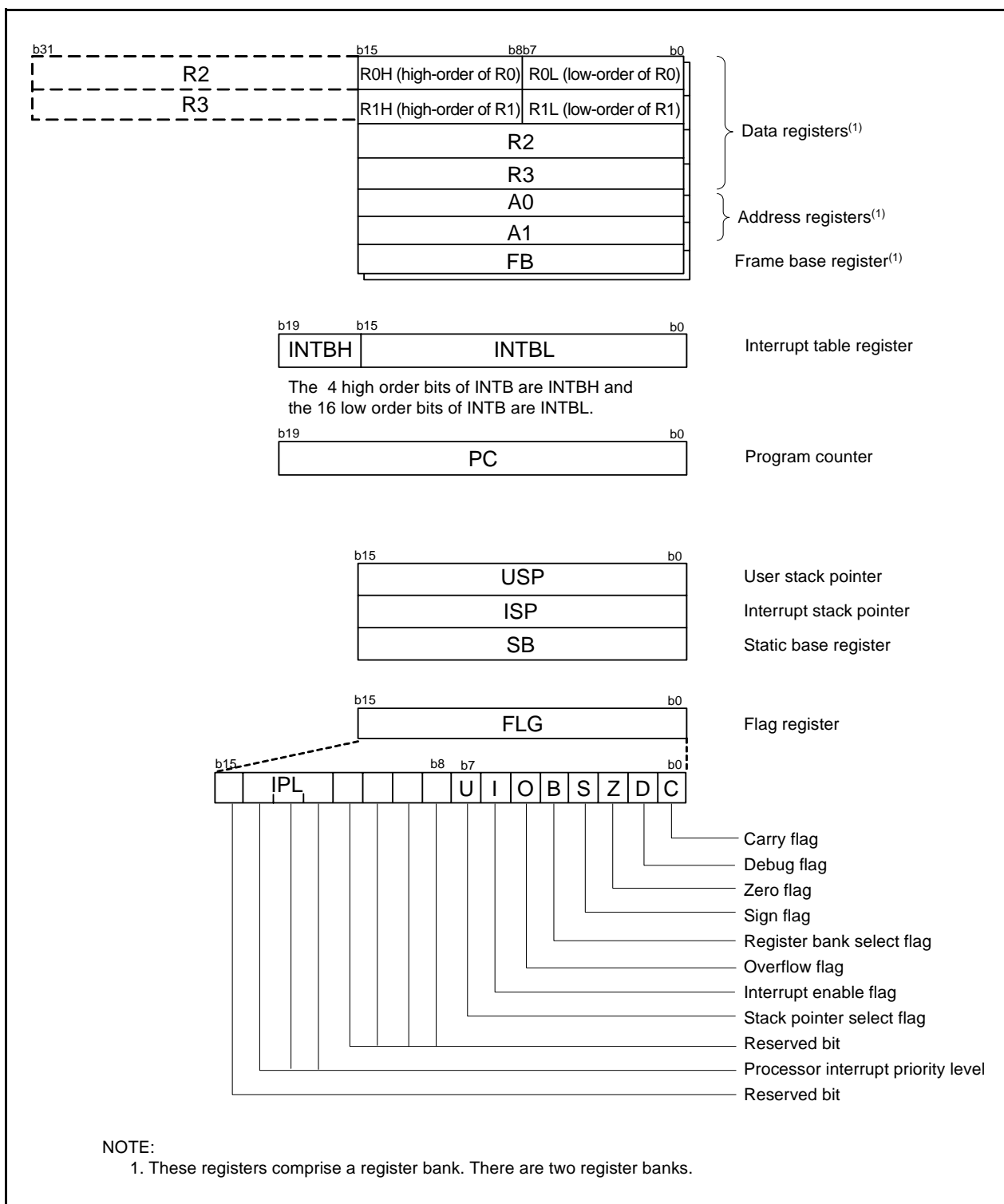
1. The user ROM is programmed before shipment.



**Figure 1.1 Part Number, Memory Size, and Package of R8C/2K Group**

## 2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register bank.



**Figure 2.1 CPU Registers**

## 2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

## 2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

## 2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

## 2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the start address of an interrupt vector table.

## 2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

## 2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP, and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

## 2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

## 2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

### 2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

### 2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

### 2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

### 2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

### 2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

### 2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.



## 4. Special Function Registers (SFRs)

An SFR (special function register) is a control register for a peripheral function. Tables 4.1 to 4.7 list the special function registers.

**Table 4.1 SFR Information (1)(1)**

Address	Register	Symbol	After reset
0000h			
0001h			
0002h			
0003h			
0004h	Processor Mode Register 0	PM0	00h
0005h	Processor Mode Register 1	PM1	00h
0006h	System Clock Control Register 0	CM0	01101000b
0007h	System Clock Control Register 1	CM1	00100000b
0008h			
0009h			
000Ah	Protect Register	PRCR	00h
000Bh			
000Ch	Oscillation Stop Detection Register	OCD	00000100b
000Dh	Watchdog Timer Reset Register	WDTR	XXh
000Eh	Watchdog Timer Start Register	WDTS	XXh
000Fh	Watchdog Timer Control Register	WDC	00X11111b
0010h	Address Match Interrupt Register 0	RMAD0	00h
0011h			00h
0012h			00h
0013h	Address Match Interrupt Enable Register	AIER	00h
0014h	Address Match Interrupt Register 1	RMAD1	00h
0015h			00h
0016h			00h
0017h			
0018h			
0019h			
001Ah			
001Bh			
001Ch	Count Source Protection Mode Register	CSPR	00h 10000000b <sup>(6)</sup>
001Dh			
001Eh			
001Fh			
0020h			
0021h			
0022h			
0023h	High-Speed On-Chip Oscillator Control Register 0	FRA0	00h
0024h	High-Speed On-Chip Oscillator Control Register 1	FRA1	When shipping
0025h	High-Speed On-Chip Oscillator Control Register 2	FRA2	00h
0026h			
0027h			
0028h			
0029h			
002Ah			
002Bh	High-Speed On-Chip Oscillator Control Register 6	FRA6	When Shipping
002Ch	High-Speed On-Chip Oscillator Control Register 7	FRA7	When Shipping
0030h			
0031h	Voltage Detection Register 1 <sup>(2)</sup>	VCA1	00001000b
0032h	Voltage Detection Register 2 <sup>(2)</sup>	VCA2	00h <sup>(3)</sup> 00100000b <sup>(4)</sup>
0033h			
0034h			
0035h			
0036h	Voltage Monitor 1 Circuit Control Register <sup>(5)</sup>	VW1C	00001000b
0037h	Voltage Monitor 2 Circuit Control Register <sup>(5)</sup>	VW2C	00h
0038h	Voltage Monitor 0 Circuit Control Register <sup>(2)</sup>	VW0C	0000X000b <sup>(3)</sup> 0100X001b <sup>(4)</sup>
0039h			
003Ah			
003Eh			
003Fh			

X: Undefined

**NOTES:**

1. The blank regions are reserved. Do not access locations in these regions.
2. Software reset, watchdog timer reset, voltage monitor 1 reset, or voltage monitor 2 reset do not affect this register.
3. The LVD0ON bit in the OFS register is set to 1 and hardware reset.
4. Power-on reset, voltage monitor 0 reset, or the LVD0ON bit in the OFS register is set to 0 and hardware reset.
5. Software reset, watchdog timer reset, voltage monitor 1 reset, or voltage monitor 2 reset do not affect b2 and b3.
6. The CSPROINI bit in the OFS register is set to 0.

**Table 4.3 SFR Information (3)<sup>(1)</sup>**

Address	Register	Symbol	After reset
0080h			
0081h			
0082h			
0083h			
0084h			
0085h			
0086h			
0087h			
0088h			
0089h			
008Ah			
008Bh			
008Ch			
008Dh			
008Eh			
008Fh			
0090h			
0091h			
0092h			
0093h			
0094h			
0095h			
0096h			
0097h			
0098h			
0099h			
009Ah			
009Bh			
009Ch			
009Dh			
009Eh			
009Fh			
00A0h	UART0 Transmit/Receive Mode Register	U0MR	00h
00A1h	UART0 Bit Rate Register	U0BRG	XXh
00A2h	UART0 Transmit Buffer Register	U0TB	XXh
00A3h			XXh
00A4h	UART0 Transmit/Receive Control Register 0	U0C0	00001000b
00A5h	UART0 Transmit/Receive Control Register 1	U0C1	00000010b
00A6h	UART0 Receive Buffer Register	U0RB	XXh
00A7h			XXh
00A8h			
00A9h			
00AAh			
00ABh			
00ACh			
00ADh			
00AEh			
00AFh			
00B0h			
00B1h			
00B2h			
00B3h			
00B4h			
00B5h			
00B6h			
00B7h			
00B8h			
00B9h			
00BAh			
00BBh			
00BCh			
00BDh			
00BEh			
00BFh			

X: Undefined

NOTE:

1. The blank regions are reserved. Do not access locations in these regions.

**Table 4.4 SFR Information (4)<sup>(1)</sup>**

Address	Register	Symbol	After reset
00C0h	A/D Register	AD	XXh
00C1h			XXh
00C2h			
00C3h			
00C4h			
00C5h			
00C6h			
00C7h			
00C8h			
00C9h			
00CAh			
00CBh			
00CCh			
00CDh			
00CEh			
00CFh			
00D0h			
00D1h			
00D2h			
00D3h			
00D4h	A/D Control Register 2	ADCON2	00h
00D5h	A/D Control Register 0	ADCON0	00h
00D6h			
00D7h	A/D Control Register 1	ADCON1	00h
00D8h			
00D9h			
00DAh			
00DBh			
00DCh			
00DDh			
00DEh			
00DFh			
00E0h	Port P0 Register	P0	XXh
00E1h	Port P1 Register	P1	XXh
00E2h	Port P0 Direction Register	PD0	00h
00E3h	Port P1 Direction Register	PD1	00h
00E4h	Port P2 Register	P2	XXh
00E5h	Port P3 Register	P3	XXh
00E6h	Port P2 Direction Register	PD2	00h
00E7h	Port P3 Direction Register	PD3	00h
00E8h	Port P4 Register	P4	XXh
00E9h			
00EAh	Port P4 Direction Register	PD4	00h
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h			
00F1h			
00F2h			
00F3h			
00F4h	Port P2 Drive Capacity Control Register	P2DRR	00h
00F5h	Pin Select Register 1	PINSR1	XXh
00F6h	Pin Select Register 2	PINSR2	XXh
00F7h	Pin Select Register 3	PINSR3	XXh
00F8h	Port Mode Register	PMR	00h
00F9h	External Input Enable Register	INTEN	00h
00FAh	INT Input Filter Select Register	INTF	00h
00FBh	Key Input Enable Register	KIEN	00h
00FCh	Pull-Up Control Register 0	PUR0	00h
00FDh	Pull-Up Control Register 1	PUR1	XX000000b
00FEh			
00FFh			

X: Undefined

NOTE:

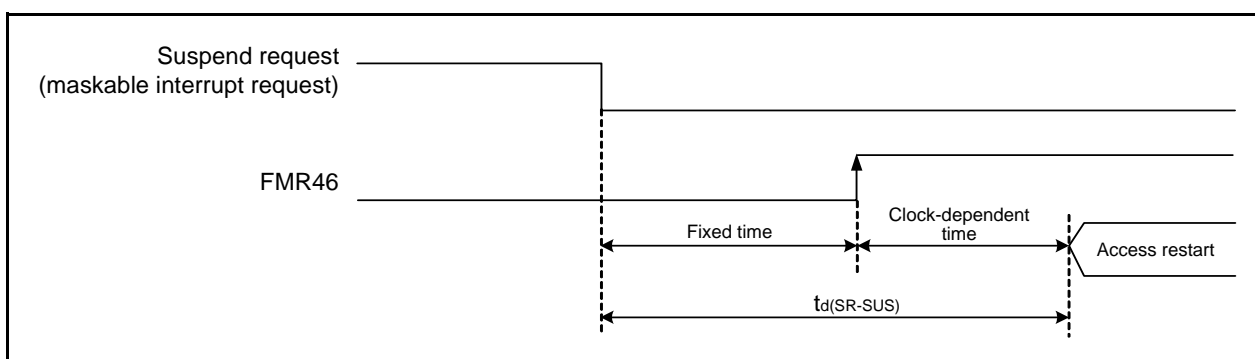
1. The blank regions are reserved. Do not access locations in these regions.

**Table 5.4 Flash Memory (Program ROM) Electrical Characteristics**

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
–	Program/erase endurance <sup>(2)</sup>	R8C/2K Group	100 <sup>(3)</sup>	–	–	times
		R8C/2L Group	1,000 <sup>(3)</sup>	–	–	times
–	Byte program time		–	50	400	μs
–	Block erase time		–	0.4	9	s
t <sub>d</sub> (SR-SUS)	Time delay from suspend request until suspend		–	–	97+CPU clock × 6 cycles	μs
–	Interval from erase start/restart until following suspend request		650	–	–	μs
–	Interval from program start/restart until following suspend request		0	–	–	ns
–	Time from suspend until program/erase restart		–	–	3+CPU clock × 4 cycles	μs
–	Program, erase voltage		2.7	–	5.5	V
–	Read voltage		2.2	–	5.5	V
–	Program, erase temperature		0	–	60	°C
–	Data hold time <sup>(7)</sup>	Ambient temperature = 55°C	20	–	–	year

**NOTES:**

1. V<sub>CC</sub> = 2.7 to 5.5 V at T<sub>opr</sub> = 0 to 60°C, unless otherwise specified.
2. Definition of programming/erasure endurance  
The programming and erasure endurance is defined on a per-block basis.  
If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.  
However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.
5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
7. The data hold time includes time that the power supply is off or the clock is not supplied.

**Figure 5.2 Time delay until Suspend****Table 5.6 Voltage Detection 0 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det0</sub>	Voltage detection level		2.2	2.3	2.4	V
—	Voltage detection circuit self power consumption	VCA25 = 1, V <sub>CC</sub> = 5.0 V	—	0.9	—	μA
t <sub>d(E-A)</sub>	Waiting time until voltage detection circuit operation starts <sup>(2)</sup>		—	—	300	μs
V <sub>ccmin</sub>	MCU operating voltage minimum value		2.2	—	—	V

**NOTES:**

1. The measurement condition is V<sub>CC</sub> = 2.2 to 5.5 V and T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version).
2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.

**Table 5.7 Voltage Detection 1 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det1</sub>	Voltage detection level <sup>(4)</sup>		2.70	2.85	3.00	V
—	Voltage monitor 1 interrupt request generation time <sup>(2)</sup>		—	40	—	μs
—	Voltage detection circuit self power consumption	VCA26 = 1, V <sub>CC</sub> = 5.0 V	—	0.6	—	μA
t <sub>d(E-A)</sub>	Waiting time until voltage detection circuit operation starts <sup>(3)</sup>		—	—	100	μs

**NOTES:**

1. The measurement condition is V<sub>CC</sub> = 2.2 to 5.5 V and T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version).
2. Time until the voltage monitor 1 interrupt request is generated after the voltage passes V<sub>det1</sub>.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.
4. This parameter shows the voltage detection level when the power supply drops.  
The voltage detection level when the power supply rises is higher than the voltage detection level when the power supply drops by approximately 0.1 V.

**Table 5.8 Voltage Detection 2 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det2</sub>	Voltage detection level		3.3	3.6	3.9	V
—	Voltage monitor 2 interrupt request generation time <sup>(2)</sup>		—	40	—	μs
—	Voltage detection circuit self power consumption	VCA27 = 1, V <sub>CC</sub> = 5.0 V	—	0.6	—	μA
t <sub>d(E-A)</sub>	Waiting time until voltage detection circuit operation starts <sup>(3)</sup>		—	—	100	μs

**NOTES:**

1. The measurement condition is V<sub>CC</sub> = 2.2 to 5.5 V and T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version).
2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes V<sub>det2</sub>.
3. Necessary time until the voltage detection circuit operates after setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.

**Table 5.10 High-speed On-Chip Oscillator Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
fOCO40M	High-speed on-chip oscillator frequency temperature • supply voltage dependence	V <sub>CC</sub> = 2.7 V to 5.5 V –20°C ≤ T <sub>opr</sub> ≤ 85°C <sup>(2)</sup>	39.2	40	40.8	MHz
		V <sub>CC</sub> = 2.7 V to 5.5 V –40°C ≤ T <sub>opr</sub> ≤ 85°C <sup>(2)</sup>	39.0	40	41.0	MHz
		V <sub>CC</sub> = 2.2 V to 5.5 V –20°C ≤ T <sub>opr</sub> ≤ 85°C <sup>(3)</sup>	35.2	40	44.8	MHz
		V <sub>CC</sub> = 2.2 V to 5.5 V –40°C ≤ T <sub>opr</sub> ≤ 85°C <sup>(3)</sup>	34.0	40	46.0	MHz
	High-speed on-chip oscillator frequency when correction value in FRA7 register is written to FRA1 register <sup>(4)</sup>	V <sub>CC</sub> = 5.0 V, T <sub>opr</sub> = 25°C	–	36.864	–	MHz
		V <sub>CC</sub> = 2.7 V to 5.5 V –20°C ≤ T <sub>opr</sub> ≤ 85°C	–3%	–	3%	%
–	Value in FRA1 register after reset		08h	–	F7h	–
–	Oscillation frequency adjustment unit of high- speed on-chip oscillator	Adjust FRA1 register (value after reset) to -1	–	+0.3	–	MHz
–	Oscillation stability time	V <sub>CC</sub> = 5.0 V, T <sub>opr</sub> = 25°C	–	10	100	μs
–	Self power consumption at oscillation	V <sub>CC</sub> = 5.0 V, T <sub>opr</sub> = 25°C	–	550	–	μA

## NOTES:

1. V<sub>CC</sub> = 2.2 to 5.5 V, T<sub>opr</sub> = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.
2. These standard values show when the FRA1 register value after reset is assumed.
3. These standard values show when the corrected value of the FRA6 register is written to the FRA1 register.
4. This enables the setting errors of bit rates such as 9600 bps and 38400 bps to be 0% when the serial interface is used in UART mode.

**Table 5.11 Low-speed On-Chip Oscillator Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
fOCO-S	Low-speed on-chip oscillator frequency		30	125	250	kHz
–	Oscillation stability time		–	10	100	μs
–	Self power consumption at oscillation	V <sub>CC</sub> = 5.0 V, T <sub>opr</sub> = 25°C	–	15	–	μA

## NOTE:

1. V<sub>CC</sub> = 2.2 to 5.5 V, T<sub>opr</sub> = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.

**Table 5.12 Power Supply Circuit Timing Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
t <sub>d</sub> (P-R)	Time for internal power supply stabilization during power-on <sup>(2)</sup>		1	–	2000	μs
t <sub>d</sub> (R-S)	STOP exit time <sup>(3)</sup>		–	–	150	μs

## NOTES:

1. The measurement condition is V<sub>CC</sub> = 2.2 to 5.5 V and T<sub>opr</sub> = 25°C.
2. Waiting time until the internal power supply generation circuit stabilizes during power-on.
3. Time until system clock supply starts after the interrupt is acknowledged to exit stop mode.

**Table 5.13 Electrical Characteristics (1) [V<sub>CC</sub> = 5 V]**

Symbol	Parameter		Condition	Standard			Unit
				Min.	Typ.	Max.	
V <sub>OH</sub>	Output "H" voltage	Except P2_0 to P2_7, XOUT	I <sub>OH</sub> = -5 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
			I <sub>OH</sub> = -200 μA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
		P2_0 to P2_7	Drive capacity HIGH I <sub>OH</sub> = -20 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
			Drive capacity LOW I <sub>OH</sub> = -5 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
		XOUT	Drive capacity HIGH I <sub>OH</sub> = -1 mA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
			Drive capacity LOW I <sub>OH</sub> = -500 μA	V <sub>CC</sub> - 2.0	—	V <sub>CC</sub>	V
V <sub>OL</sub>	Output "L" voltage	Except P2_0 to P2_7, XOUT	I <sub>OL</sub> = 5 mA	—	—	2.0	V
			I <sub>OL</sub> = 200 μA	—	—	0.45	V
		P2_0 to P2_7	Drive capacity HIGH I <sub>OL</sub> = 20 mA	—	—	2.0	V
			Drive capacity LOW I <sub>OL</sub> = 5 mA	—	—	2.0	V
		XOUT	Drive capacity HIGH I <sub>OL</sub> = 1 mA	—	—	2.0	V
			Drive capacity LOW I <sub>OL</sub> = 500 μA	—	—	2.0	V
V <sub>T+</sub> -V <sub>T-</sub>	Hysteresis	INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, RXD0, RXD2, CLK0, CLK2		0.1	0.5	—	V
		RESET		0.1	1.0	—	V
I <sub>IH</sub>	Input "H" current		V <sub>I</sub> = 5 V, V <sub>CC</sub> = 5 V	—	—	5.0	μA
I <sub>IL</sub>	Input "L" current		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 5 V	—	—	-5.0	μA
R <sub>PULLUP</sub>	Pull-up resistance		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 5 V	30	50	167	kΩ
R <sub>FXIN</sub>	Feedback resistance	XIN		—	1.0	—	MΩ
V <sub>RAM</sub>	RAM hold voltage		During stop mode	1.8	—	—	V

NOTE:

- V<sub>CC</sub> = 4.2 to 5.5 V at T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 20 MHz, unless otherwise specified.

**Table 5.15 Electrical Characteristics (3) [V<sub>CC</sub> = 5 V]**  
**(T<sub>opr</sub> = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
I <sub>CC</sub>	Power supply current (V <sub>CC</sub> = 3.3 to 5.5 V) Single-chip mode, output pins are open, other pins are V <sub>SS</sub>	Wait mode XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	–	25	75	μA
			–	23	60	μA
		Stop mode XIN clock off, T <sub>opr</sub> = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	–	0.8	3.0	μA
			–	1.2	–	μA



**Table 5.20 Electrical Characteristics (1) [V<sub>CC</sub> = 3 V]**

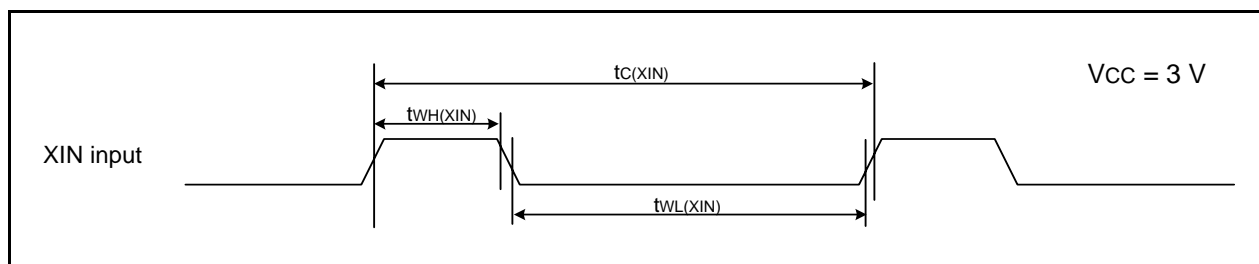
Symbol	Parameter		Condition		Standard			Unit
					Min.	Typ.	Max.	
V <sub>OH</sub>	Output "H" voltage	Except P2_0 to P2_7, XOUT	I <sub>OH</sub> = -1 mA		V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
		P2_0 to P2_7	Drive capacity HIGH	I <sub>OH</sub> = -5 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
			Drive capacity LOW	I <sub>OH</sub> = -1 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
		XOUT	Drive capacity HIGH	I <sub>OH</sub> = -0.1 mA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
			Drive capacity LOW	I <sub>OH</sub> = -50 μA	V <sub>CC</sub> - 0.5	—	V <sub>CC</sub>	V
V <sub>OL</sub>	Output "L" voltage	Except P2_0 to P2_7, XOUT	I <sub>OL</sub> = 1 mA		—	—	0.5	V
		P2_0 to P2_7	Drive capacity HIGH	I <sub>OL</sub> = 5 mA	—	—	0.5	V
			Drive capacity LOW	I <sub>OL</sub> = 1 mA	—	—	0.5	V
		XOUT	Drive capacity HIGH	I <sub>OL</sub> = 0.1 mA	—	—	0.5	V
			Drive capacity LOW	I <sub>OL</sub> = 50 μA	—	—	0.5	V
V <sub>T+</sub> -V <sub>T-</sub>	Hysteresis	INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, RXD0, RXD2, CLK0, CLK2			0.1	0.3	—	V
		RESET			0.1	0.4	—	V
I <sub>IH</sub>	Input "H" current		V <sub>I</sub> = 3 V, V <sub>CC</sub> = 3 V		—	—	4.0	μA
I <sub>IL</sub>	Input "L" current		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 3 V		—	—	-4.0	μA
R <sub>PULLUP</sub>	Pull-up resistance		V <sub>I</sub> = 0 V, V <sub>CC</sub> = 3 V		66	160	500	kΩ
R <sub>IXIN</sub>	Feedback resistance	XIN			—	3.0	—	MΩ
V <sub>RAM</sub>	RAM hold voltage		During stop mode		1.8	—	—	V

## NOTE:

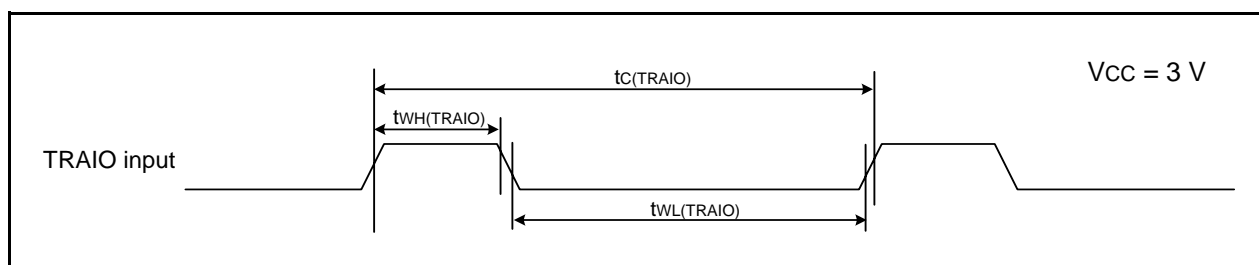
- V<sub>CC</sub> = 2.7 to 3.3 V at T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 10 MHz, unless otherwise specified.

**Timing requirements****(Unless Otherwise Specified:  $V_{CC} = 3\text{ V}$ ,  $V_{SS} = 0\text{ V}$  at  $T_{opr} = 25^{\circ}\text{C}$ ) [ $V_{CC} = 3\text{ V}$ ]****Table 5.22 XIN Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(XIN)}$	XIN input cycle time	100	–	ns
$t_{WH(XIN)}$	XIN input "H" width	40	–	ns
$t_{WL(XIN)}$	XIN input "L" width	40	–	ns

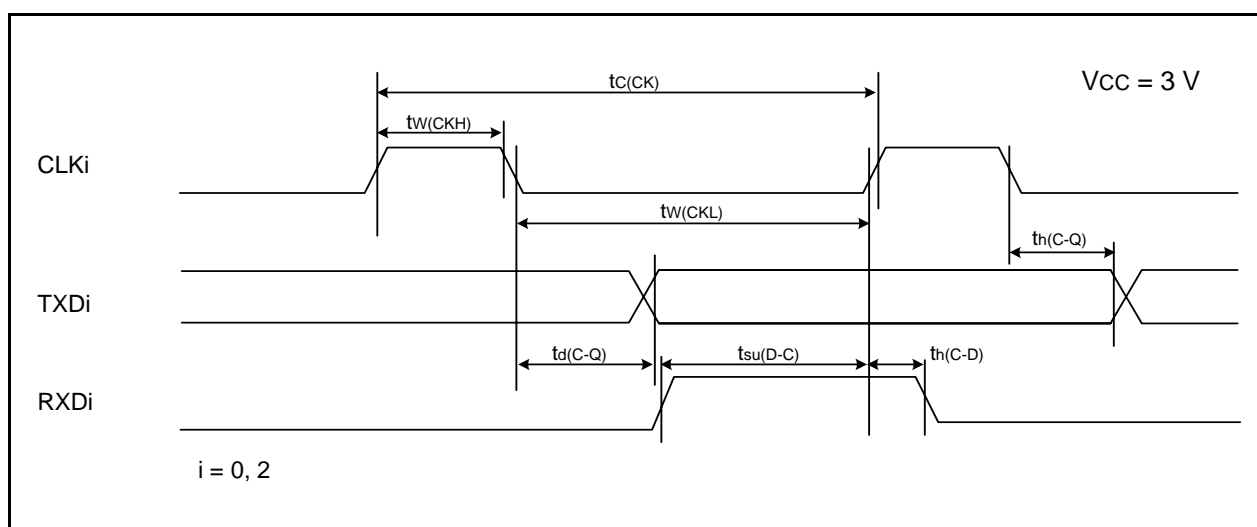
**Figure 5.8 XIN Input Timing Diagram when  $V_{CC} = 3\text{ V}$** **Table 5.23 TRAIO Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TRAIO)}$	TRAIO input cycle time	300	–	ns
$t_{WH(TRAIO)}$	TRAIO input "H" width	120	–	ns
$t_{WL(TRAIO)}$	TRAIO input "L" width	120	–	ns

**Figure 5.9 TRAIO Input Timing Diagram when  $V_{CC} = 3\text{ V}$**

**Table 5.24 Serial Interface**

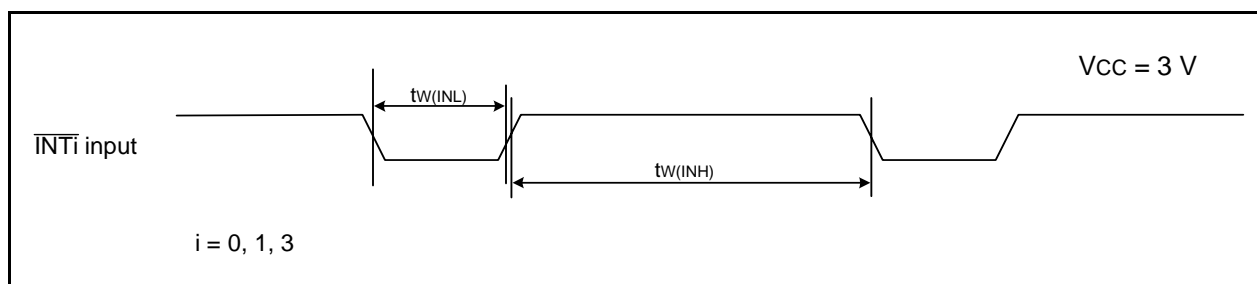
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	300	—	ns
$t_{w(CKH)}$	CLKi input "H" width	150	—	ns
$t_{w(CKL)}$	CLKi Input "L" width	150	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	80	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	70	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	ns

 $i = 0, 2$ **Figure 5.10 Serial Interface Timing Diagram when Vcc = 3 V****Table 5.25 External Interrupt  $\overline{INTi}$  ( $i = 0, 1, 3$ ) Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{INTi}$ input "H" width	380 <sup>(1)</sup>	—	ns
$t_{w(INL)}$	$\overline{INTi}$ input "L" width	380 <sup>(2)</sup>	—	ns

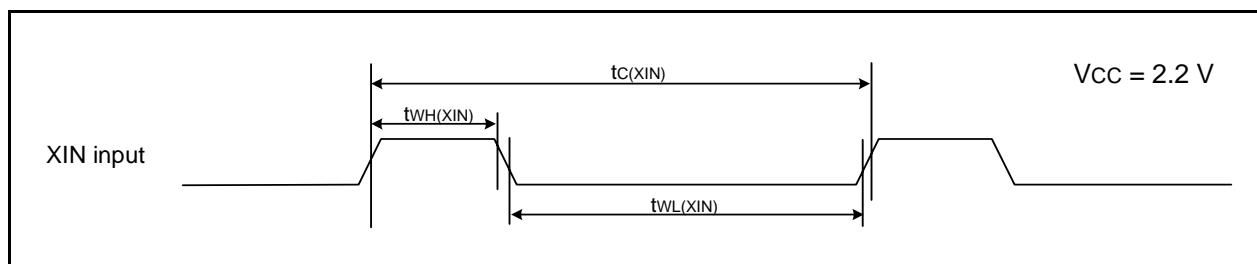
**NOTES:**

1. When selecting the digital filter by the  $\overline{INTi}$  input filter select bit, use an  $\overline{INTi}$  input HIGH width of either (1/digital filter clock frequency  $\times$  3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the  $\overline{INTi}$  input filter select bit, use an  $\overline{INTi}$  input LOW width of either (1/digital filter clock frequency  $\times$  3) or the minimum value of standard, whichever is greater.

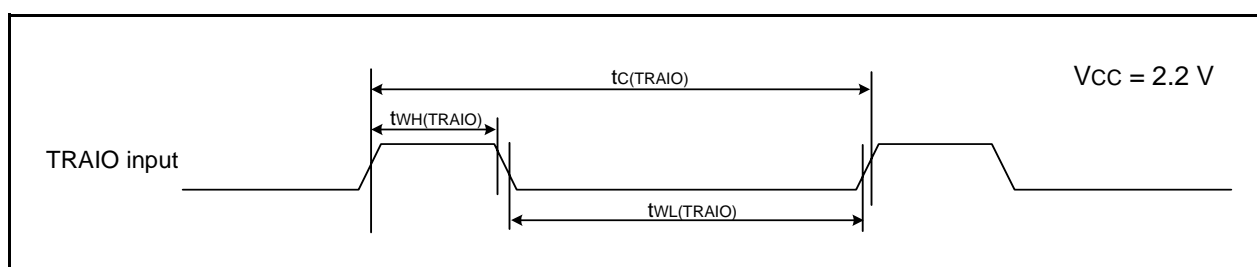
**Figure 5.11 External Interrupt  $\overline{INTi}$  Input Timing Diagram when Vcc = 3 V**

**Timing requirements****(Unless Otherwise Specified:  $V_{CC} = 2.2\text{ V}$ ,  $V_{SS} = 0\text{ V}$  at  $T_{opr} = 25^{\circ}\text{C}$ ) [ $V_{CC} = 2.2\text{ V}$ ]****Table 5.28 XIN Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(XIN)}$	XIN input cycle time	200	–	ns
$t_{WH(XIN)}$	XIN input "H" width	90	–	ns
$t_{WL(XIN)}$	XIN input "L" width	90	–	ns

**Figure 5.12 XIN Input Timing Diagram when  $V_{CC} = 2.2\text{ V}$** **Table 5.29 TRAIO Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TRAIO)}$	TRAIO input cycle time	500	–	ns
$t_{WH(TRAIO)}$	TRAIO input "H" width	200	–	ns
$t_{WL(TRAIO)}$	TRAIO input "L" width	200	–	ns

**Figure 5.13 TRAIO Input Timing Diagram when  $V_{CC} = 2.2\text{ V}$**

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Kukje Center Bldg. 18th Fl., 191, 2-ka, Hangang-ro, Yongsan-ku, Seoul 140-702, Korea  
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**Renesas Technology Malaysia Sdn. Bhd**  
Unit 906, Block B, Menara Amcorp, Amcorp Trade Centre, No.18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia  
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