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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	LINbus, SIO, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	25
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 5.5V
Data Converters	A/D 9x10b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f212l2syfp-v2

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

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# 1.1.2 Specifications

Tables 1.1 and 1.2 outlines the Specifications for R8C/2K Group and Tables 1.3 and 1.4 outlines the Specifications for R8C/2L Group.

Table 1.1 Specifications for R8C/2K Group (1)

Item	Function	Specification
CPU	Central processing	R8C/Tiny series core
	unit	Number of fundamental instructions: 89
		Minimum instruction execution time:
		50 ns (f(XIN) = 20 MHz, VCC = 3.0 to 5.5 V)
		100 ns (f(XIN) = 10 MHz, VCC = 2.7 to 5.5 V)
		200 ns (f(XIN) = 5 MHz, VCC = 2.2 to 5.5 V)
		Multiplier: 16 bits × 16 bits → 32 bits
		<ul> <li>Multiply-accumulate instruction: 16 bits x 16 bits + 32 bits → 32 bits</li> </ul>
		Operation mode: Single-chip mode (address space: 1 Mbyte)
Memory	ROM, RAM	Refer to Table 1.5 Product List for R8C/2K Group.
Power Supply	Voltage detection	Power-on reset
Voltage	circuit	Voltage detection 3
Detection		
I/O Ports	Programmable I/O	Input-only: 3 pins
	ports	CMOS I/O ports: 25, selectable pull-up resistor
		High current drive ports: 8
Clock	Clock generation	2 circuits: XIN clock oscillation circuit (with on-chip feedback resistor),
	circuits	On-chip oscillator (high-speed, low-speed)
		(high-speed on-chip oscillator has a frequency adjustment function)
		Oscillation stop detection: XIN clock oscillation stop detection function
		• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16
		• Low power consumption modes:
		Standard operating mode (high-speed clock, high-speed on-chip oscillator,
		low-speed on-chip oscillator), wait mode, stop mode
Interrupts		External: 4 sources, Internal: 15 sources, Software: 4 sources
monapio		Priority levels: 7 levels
Watchdog Tim	er	15 bits × 1 (with prescaler), reset start selectable
Timer	Timer RA	8 bits × 1 (with 8-bit prescaler)
111101		Timer mode (period timer), pulse output mode (output level inverted every
		period), event counter mode, pulse width measurement mode, pulse period
		measurement mode
	Timer RB	8 bits x 1 (with 8-bit prescaler)
		Timer mode (period timer), programmable waveform generation mode (PWM
		output), programmable one-shot generation mode, programmable wait one-
		shot generation mode
	Timer RC	16 bits x 1 (with 4 capture/compare registers)
		Timer mode (input capture function, output compare function), PWM mode
		(output 3 pins), PWM2 mode (PWM output pin)
	Timer RD	16 bits × 2 (with 4 capture/compare registers)
		Timer mode (input capture function, output compare function), PWM mode
		(output 6 pins), reset synchronous PWM mode (output three-phase
		waveforms (6 pins), sawtooth wave modulation), complementary PWM mode
		(output three-phase waveforms (6 pins), triangular wave modulation), PWM3
		mode (PWM output 2 pins with fixed period)

Table 1.3 Specifications for R8C/2L Group (1)

Item	Function	Specification
CPU	Central processing	R8C/Tiny series core
	unit	Number of fundamental instructions: 89
		Minimum instruction execution time:
		50 ns (f(XIN) = 20 MHz, VCC = 3.0 to 5.5 V)
		100 ns (f(XIN) = 10 MHz, VCC = 2.7 to 5.5 V)
		200 ns (f(XIN) = 5 MHz, VCC = 2.2 to 5.5 V)
		Multiplier: 16 bits × 16 bits → 32 bits
		<ul> <li>Multiply-accumulate instruction: 16 bits x 16 bits + 32 bits → 32 bits</li> </ul>
		Operation mode: Single-chip mode (address space: 1 Mbyte)
Memory	ROM, RAM	Refer to Table 1.6 Product List for R8C/2L Group.
Power Supply	Voltage detection	Power-on reset
Voltage	circuit	Voltage detection 3
Detection		
I/O Ports	Programmable I/O	Input-only: 3 pins
	ports	CMOS I/O ports: 25, selectable pull-up resistor
		High current drive ports: 8
Clock	Clock generation	2 circuits: XIN clock oscillation circuit (with on-chip feedback resistor),
	circuits	On-chip oscillator (high-speed, low-speed)
		(high-speed on-chip oscillator has a frequency adjustment function)
		Oscillation stop detection: XIN clock oscillation stop detection function
		• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16
		• Low power consumption modes:
		Standard operating mode (high-speed clock, high-speed on-chip oscillator,
		low-speed on-chip oscillator), wait mode, stop mode
Interrupts		External: 4 sources, Internal: 15 sources, Software: 4 sources
into in apto		Priority levels: 7 levels
Watchdog Tim	er	15 bits × 1 (with prescaler), reset start selectable
Timer	Timer RA	8 bits × 1 (with 8-bit prescaler)
111101		Timer mode (period timer), pulse output mode (output level inverted every
		period), event counter mode, pulse width measurement mode, pulse period
		measurement mode
	Timer RB	8 bits x 1 (with 8-bit prescaler)
		Timer mode (period timer), programmable waveform generation mode (PWM
		output), programmable one-shot generation mode, programmable wait one-
		shot generation mode
	Timer RC	16 bits × 1 (with 4 capture/compare registers)
		Timer mode (input capture function, output compare function), PWM mode
		(output 3 pins), PWM2 mode (PWM output pin)
	Timer RD	16 bits × 2 (with 4 capture/compare registers)
		Timer mode (input capture function, output compare function), PWM mode
		(output 6 pins), reset synchronous PWM mode (output three-phase
		waveforms (6 pins), sawtooth wave modulation), complementary PWM mode
		(output three-phase waveforms (6 pins), triangular wave modulation), PWM3
		mode (PWM output 2 pins with fixed period)

Specifications for R8C/2L Group (2) Table 1.4

Item	Function	Specification
Serial	UARTO, UART2	Clock synchronous serial I/O/UART x 2
Interface	,	
LIN Module		Hardware LIN: 1 (timer RA, UART0)
A/D Converter		10-bit resolution × 9 channels, includes sample and hold function
Flash Memory		Programming and erasure voltage: VCC = 2.7 to 5.5 V
		<ul> <li>Programming and erasure endurance: 10,000 times (data flash)</li> </ul>
		1,000 times (program ROM)
		Program security: ROM code protect, ID code check
		Debug functions: On-chip debug, on-board flash rewrite function
Operating Frequency/Supply Voltage		f(XIN) = 20 MHz (VCC = 3.0 to 5.5 V) f(XIN) = 10 MHz (VCC = 2.7 to 5.5 V) f(XIN) = 5 MHz (VCC = 2.2 to 5.5 V) (VCC = 2.7 to 5.5 V for A/D converter only)
Current consumption		Typ. 10 mA (VCC = 5.0 V, f(XIN) = 20 MHz) Typ. 6 mA (VCC = 3.0 V, f(XIN) = 10 MHz) Typ. 23 $\mu$ A (VCC = 3.0 V, wait mode, low-speed on-chip oscillator used) Typ. 0.7 $\mu$ A (VCC = 3.0 V, stop mode)
Operating Amb	pient Temperature	-20 to 85°C (N version) -40 to 85°C (D version) <sup>(1)</sup> -20 to 105°C (Y version) <sup>(2)</sup>
Package		32-pin LQFP • Package code: PLQP0032GB-A (previous code: 32P6U-A)

- 1. Specify the D version if D version functions are to be used.
- 2. Please contact Renesas Technology sales offices for the Y version.

# 1.2 Product List

Table 1.5 lists the Product List for R8C/2K Group, Figure 1.1 shows a Part Number, Memory Size, and Package of R8C/2K Group, Table 1.6 lists the Product List for R8C/2L Group, and Figure 1.2 shows a Part Number, Memory Size, and Package of R8C/2L Group.

Table 1.5 Product List for R8C/2K Group

Current of Dec. 2007

Part No.	ROM Capacity	RAM Capacity	Package Type	Remarks
R5F212K2SNFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version
R5F212K4SNFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SDFP	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version
R5F212K4SDFP	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	
R5F212K2SNXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	N version
R5F212K4SNXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	Factory programming product <sup>(1)</sup>
R5F212K2SDXXXFP (D)	8 Kbytes	1 Kbyte	PLQP0032GB-A	D version
R5F212K4SDXXXFP (D)	16 Kbytes	1.5 Kbytes	PLQP0032GB-A	Factory programming product <sup>(1)</sup>

(D): Under development

NOTE:

1. The user ROM is programmed before shipment.

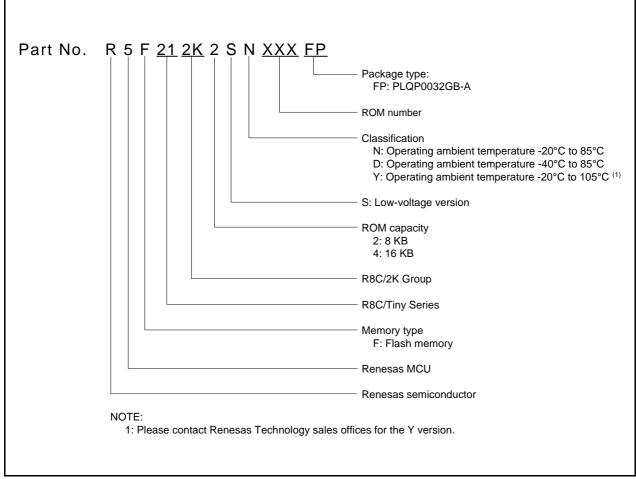


Figure 1.1 Part Number, Memory Size, and Package of R8C/2K Group

# 1.4 Pin Assignment

Figure 1.4 shows the Pin Assignment (Top View). Table 1.7 outlines the Pin Name Information by Pin Number.

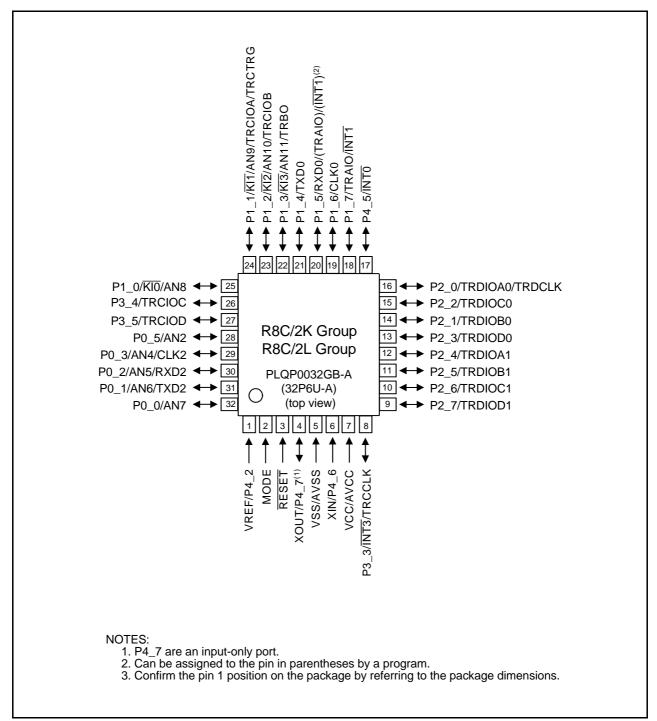


Figure 1.4 Pin Assignment (Top View)

Table 1.7 Pin Name Information by Pin Number

Pin	Control Pin	Port	I/O Pin Functions for of Peripheral Modules					
Number	Control Pin	Polt	Interrupt	Timer	Serial Interface	A/D Converter		
1	VREF	P4_2						
2	MODE							
3	RESET							
4	XOUT	P4_7						
5	VSS/AVSS							
6	XIN	P4_6						
7	VCC/AVCC							
8		P3_3	ĪNT3	TRCCLK				
9		P2_7		TRDIOD1				
10		P2_6		TRDIOC1				
11		P2_5		TRDIOB1				
12		P2_4		TRDIOA1				
13		P2_3		TRDIOD0				
14		P2_1		TRDIOB0				
15		P2_2		TRDIOC0				
16		P2_0		TRDIOA0/TRDCLK				
17		P4_5	ĪNT0					
18		P1_7	INT1	TRAIO				
19		P1_6			CLK0			
20		P1_5	( <del>INT1</del> ) <sup>(1)</sup>	(TRAIO) <sup>(1)</sup>	RXD0			
21		P1_4			TXD0			
22		P1_3	KI3	TRBO		AN11		
23		P1_2	KI2	TRCIOB		AN10		
24		P1_1	KI1	TRCIOA/TRCTRG		AN9		
25		P1_0	KI0			AN8		
26		P3_4		TRCIOC				
27		P3_5		TRCIOD				
28		P0_5				AN2		
29		P0_3			CLK2	AN4		
30		P0_2			RXD2	AN5		
31		P0_1			TXD2	AN6		
32		P0_0				AN7		

1. Can be assigned to the pin in parentheses by a program.

# 1.5 Pin Functions

Table 1.8 lists Pin Functions.

Table 1.8 Pin Functions

Item	Pin Name	I/O Type	Description
Power supply input	VCC, VSS	_	Apply 2.2 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin.
Analog power supply input	AVCC, AVSS	-	Power supply for the A/D converter. Connect a capacitor between AVCC and AVSS.
Reset input	RESET	I	Input "L" on this pin resets the MCU.
MODE	MODE	I	Connect this pin to VCC via a resistor.
XIN clock input	XIN	I	These pins are provided for XIN clock generation circuit I/O.  Connect a ceramic resonator or a crystal oscillator between
XIN clock output	XOUT	0	the XIN and XOUT pins <sup>(1)</sup> . To use an external clock, input it to the XIN pin and leave the XOUT pin open.
INT interrupt input	ĪNTO, ĪNT1, ĪNT3	I	INT interrupt input pins. INT0 is timer RB, timer RC and timer RD input pins.
Key input interrupt	KI0 to KI3	I	Key input interrupt input pins
Timer RA	TRAIO	I/O	Timer RA I/O pin
Timer RB	TRBO	0	Timer RB output pin
Timer RC	TRCCLK	I	External clock input pin
	TRCTRG	I	External trigger input pin
	TRCIOA, TRCIOB, TRCIOC, TRCIOD	I/O	Timer RC I/O pins
Timer RD	TRDIOA0, TRDIOA1, TRDIOB0, TRDIOB1, TRDIOC0, TRDIOC1, TRDIOD0, TRDIOD1	I/O	Timer RD I/O pins
	TRDCLK	I	External clock input pin
Serial interface	CLK0, CLK2	I/O	Transfer clock I/O pins
	RXD0, RXD2	I	Serial data input pins
	TXD0, TXD2	0	Serial data output pins
Reference voltage input	VREF	I	Reference voltage input pin to A/D converter
A/D converter	AN2, AN4 to AN11	I	Analog input pins to A/D converter
I/O port	P0_0 to P0_3, P0_5, P1_0 to P1_7, P2_0 to P2_7, P3_3 to P3_5, P4_5,	I/O	CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually.  Any port set to input can be set to use a pull-up resistor or not by a program.  P2_0 to P2_7 also function as LED drive ports.
Input port	P4_2, P4_6, P4_7	I	Input-only ports

I: Input

O: Output

I/O: Input and output

NOTE:

1. Refer to the oscillator manufacturer for oscillation characteristics.

### 3. **Memory**

### 3.1 **R8C/2K Group**

Figure 3.1 is a Memory Map of R8C/2K Group. The R8C/2K Group has 1 Mbyte of address space from addresses

The internal ROM is allocated lower addresses, beginning with address 0FFFFh. For example, a 16-Kbyte internal ROM area is allocated addresses 0C000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. They store the starting address of each interrupt routine.

The internal RAM is allocated higher addresses beginning with address 00400h. For example, a 1.5-Kbyte internal RAM area is allocated addresses 00400h to 009FFh. The internal RAM is used not only for storing data but also for calling subroutines and as stacks when interrupt requests are acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh. The peripheral function control registers are allocated here. All addresses within the SFR, which have nothing allocated are reserved for future use and cannot be accessed by users.

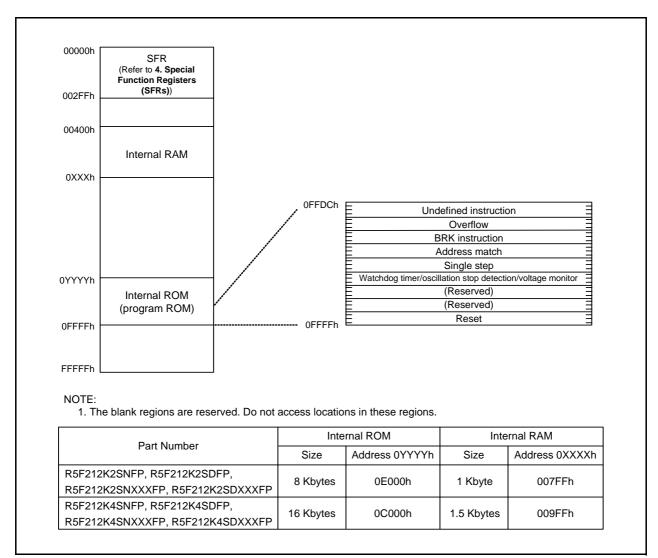


Figure 3.1 Memory Map of R8C/2K Group

SFR Information (5)<sup>(1)</sup> Table 4.5

Address	Register	Symbol	After reset
0100h	Timer RA Control Register	TRACR	00h
0100h	Timer RA I/O Control Register	TRAIOC	00h
010111 0102h	Timer RA Mode Register	TRAMR	00h
0103h	Timer RA Prescaler Register	TRAPRE	FFh
0104h	Timer RA Register	TRA	FFh
0105h	LIN Control Register 2	LINCR2	00h
0106h	LIN Control Register	LINCR	00h
0107h	LIN Status Register	LINST	00h
0108h	Timer RB Control Register	TRBCR	00h
0109h	Timer RB One-Shot Control Register	TRBOCR	00h
010Ah	Timer RB I/O Control Register	TRBIOC	00h
010Bh	Timer RB Mode Register	TRBMR	00h
010Ch	Timer RB Prescaler Register	TRBPRE	FFh
010Dh	Timer RB Secondary Register	TRBSC	FFh
010Eh	Timer RB Primary Register	TRBPR	FFh
	Timer RB Primary Register	IRBPR	FFN
010Fh			
0110h			
0111h			
0112h			
0113h			
0114h			
0115h			
0116h			
0117h		+	
0118h		+	
0119h			
011Ah			
011Bh			
-			
011Ch			
011Dh			
011Eh			
011Fh			
0120h	Timer RC Mode Register	TRCMR	01001000b
0121h	Timer RC Control Register 1	TRCCR1	00h
0122h	Timer RC Interrupt Enable Register	TRCIER	01110000b
0123h	Timer RC Status Register	TRCSR	01110000b
0124h	Timer RC I/O Control Register 0	TRCIOR0	10001000b
0125h	Timer RC I/O Control Register 1	TRCIOR1	10001000b
0126h	Timer RC Counter	TRC	00h
0120H	Time No Counter	TINO	00h
0127H	Timer RC General Register A	TRCGRA	FFh
0128h	Tilliel RC Gellelal Registel A	IRCGRA	
		TDOODD	FFh
012Ah	Timer RC General Register B	TRCGRB	FFh
012Bh			FFh
012Ch	Timer RC General Register C	TRCGRC	FFh
012Dh		<u> </u>	FFh
012Eh	Timer RC General Register D	TRCGRD	FFh
012Fh			FFh
0130h	Timer RC Control Register 2	TRCCR2	00011111b
0131h	Timer RC Digital Filter Function Select Register	TRCDF	00h
0132h	Timer RC Output Master Enable Register	TRCOER	01111111b
0133h	. 1	1	-
	1	+	
0134h			
0134h 0135h			
0135h			
0135h 0136h	Timor PD Start Pagistar	TENSTE	11111100b
0135h 0136h 0137h	Timer RD Start Register	TRDSTR	11111100b
0135h 0136h 0137h 0138h	Timer RD Mode Register	TRDMR	00001110b
0135h 0136h 0137h 0138h 0139h	Timer RD Mode Register Timer RD PWM Mode Register	TRDMR TRDPMR	00001110b 10001000b
0135h 0136h 0137h 0138h 0139h 013Ah	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register	TRDMR TRDPMR TRDFCR	00001110b 10001000b 10000000b
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1	TRDMR TRDPMR TRDFCR TRDOER1	00001110b 10001000b 10000000b FFh
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2	TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2	00001110b 10001000b 10000000b FFh 01111111b
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2 Timer RD Output Control Register	TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2 TRDOCR	00001110b 10001000b 10000000b FFh
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2	TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2	00001110b 10001000b 10000000b FFh 01111111b
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch 013Dh	Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2 Timer RD Output Control Register	TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2 TRDOCR	00001110b 10001000b 10000000b FFh 01111111b

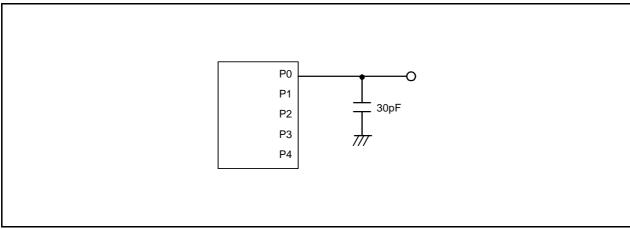
NOTE:

1. The blank regions are reserved. Do not access locations in these regions

verter Characteristics
١

Symbol	Parameter	Conditions	Standard			Unit	
Symbol	Farameter		Conditions	Min.	Тур.	Max.	Offic
=	Resolution		Vref = AVCC	-	-	10	Bits
=	Absolute	10-bit mode	φAD = 10 MHz, Vref = AVCC = 5.0 V	=	-	±3	LSB
	accuracy	8-bit mode	φAD = 10 MHz, Vref = AVCC = 5.0 V	_	_	±2	LSB
		10-bit mode	φAD = 10 MHz, Vref = AVCC = 3.3 V	_	_	±5	LSB
		8-bit mode	φAD = 10 MHz, Vref = AVCC = 3.3 V	_	_	±2	LSB
Rladder	Resistor ladder		Vref = AVCC	10	_	40	kΩ
tconv	Conversion time	10-bit mode	φAD = 10 MHz, Vref = AVCC = 5.0 V	3.3	_	_	μS
		8-bit mode	φAD = 10 MHz, Vref = AVCC = 5.0 V	2.8	_	_	μS
Vref	Reference voltag	e		2.2	_	AVcc	V
VIA	Analog input voltage <sup>(2)</sup>			0	-	AVcc	V
_	A/D operating	Without sample and hold	Vref = AVCC = 2.7 to 5.5 V	0.25	_	10	MHz
	clock frequency	With sample and hold	Vref = AVCC = 2.7 to 5.5 V	1	-	10	MHz

- AVcc = 2.7 to 5.5 V at T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
   When the analog input voltage is over the reference voltage, the A/D conversion result will be 3FFh in 10-bit mode and FFh in 8-bit mode.



Ports P0 to P4 Timing Measurement Circuit Figure 5.1

Table 5.4 Flash Memory (Program ROM) Electrical Characteristics

Cymbal	Doromotor	Conditions		Unit			
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Offic	
_	Program/erase endurance <sup>(2)</sup>	R8C/2K Group	100 <sup>(3)</sup>	=	=	times	
		R8C/2L Group	1,000(3)	-	-	times	
=	Byte program time		=	50	400	μS	
_	Block erase time		=	0.4	9	S	
td(SR-SUS)	Time delay from suspend request until suspend		-	-	97+CPU clock × 6 cycles	μS	
_	Interval from erase start/restart until following suspend request		650	-	-	μS	
_	Interval from program start/restart until following suspend request		0	-	-	ns	
=	Time from suspend until program/erase restart		=	-	3+CPU clock × 4 cycles	μS	
_	Program, erase voltage		2.7	_	5.5	V	
-	Read voltage		2.2	-	5.5	V	
-	Program, erase temperature		0	-	60	°C	
=	Data hold time <sup>(7)</sup>	Ambient temperature = 55°C	20	=	-	year	

- NOTES:

  1. Vcc = 2.7 to 5.5 V at Topr = 0 to 60°C, unless otherwise specified.
  - 2. Definition of programming/erasure endurance

The programming and erasure endurance is defined on a per-block basis.

If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.

However, the same address must not be programmed more than once per erase operation (overwriting prohibited).

- 3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
- 4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.
- 5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
- 6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- 7. The data hold time includes time that the power supply is off or the clock is not supplied.

Table 5.5 Flash Memory (Data flash Block A, Block B) Electrical Characteristics(4)

Symbol	Parameter	Conditions		Unit		
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
_	Program/erase endurance <sup>(2)</sup>		10,000(3)	-	-	times
_	Byte program time (program/erase endurance ≤ 1,000 times)		_	50	400	μS
_	Byte program time (program/erase endurance > 1,000 times)		_	65	_	μS
_	Block erase time (program/erase endurance ≤ 1,000 times)		_	0.2	9	S
_	Block erase time (program/erase endurance > 1,000 times)		_	0.3	-	S
td(SR-SUS)	Time delay from suspend request until suspend		=	-	97+CPU clock × 6 cycles	μS
_	Interval from erase start/restart until following suspend request		650	-	_	μS
_	Interval from program start/restart until following suspend request		0	-	-	ns
_	Time from suspend until program/erase restart		_	-	3+CPU clock × 4 cycles	μS
-	Program, erase voltage		2.7	_	5.5	V
_	Read voltage		2.2	_	5.5	V
=	Program, erase temperature		-20 <sup>(8)</sup>	-	85	°C
_	Data hold time <sup>(9)</sup>	Ambient temperature = 55 °C	20	_	-	year

- 1. Vcc = 2.7 to 5.5 V at Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
- 2. Definition of programming/erasure endurance

The programming and erasure endurance is defined on a per-block basis.

If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance

However, the same address must not be programmed more than once per erase operation (overwriting prohibited).

- Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
- Standard of block A and block B when program and erase endurance exceeds 1,000 times. Byte program time to 1,000 times is the same as that in program ROM.
- 5. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.
- 6. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
- 7. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- 8. -40°C for D version.
- 9. The data hold time includes time that the power supply is off or the clock is not supplied.

**Table 5.10 High-speed On-Chip Oscillator Circuit Electrical Characteristics** 

Cumbal	Doromotor	Condition	Standard			Unit
Symbol	Parameter	Condition	Min.	Тур.	Max.	Offic
fOCO40M	High-speed on-chip oscillator frequency temperature • supply voltage dependence	Vcc = 2.7  V to  5.5  V -20°C \le Topr \le 85°C <sup>(2)</sup>	39.2	40	40.8	MHz
		Vcc = 2.7 V to 5.5 V $-40^{\circ}$ C $\leq$ Topr $\leq$ 85 $^{\circ}$ C <sup>(2)</sup>	39.0	40	41.0	MHz
		Vcc = 2.2 V to 5.5 V $-20^{\circ}$ C $\leq$ Topr $\leq$ 85 $^{\circ}$ C <sup>(3)</sup>	35.2	40	44.8	MHz
		Vcc = 2.2 V to 5.5 V $-40^{\circ}$ C $\leq$ Topr $\leq$ 85 $^{\circ}$ C <sup>(3)</sup>	34.0	40	46.0	MHz
	High-speed on-chip oscillator frequency when correction value in FRA7 register is written to FRA1 register <sup>(4)</sup>	Vcc = 5.0 V, Topr = 25°C	_	36.864	_	MHz
		Vcc = 2.7 V to 5.5 V -20°C ≤ Topr ≤ 85°C	-3%	=	3%	%
_	Value in FRA1 register after reset		08h	_	F7h	-
_	Oscillation frequency adjustment unit of high- speed on-chip oscillator	Adjust FRA1 register (value after reset) to -1	-	+0.3	-	MHz
_	Oscillation stability time	Vcc = 5.0 V, Topr = 25°C	_	10	100	μS
=	Self power consumption at oscillation	Vcc = 5.0 V, Topr = 25°C	_	550	_	μΑ

- Vcc = 2.2 to 5.5 V, T<sub>opr</sub> = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.
   These standard values show when the FRA1 register value after reset is assumed.
- 3. These standard values show when the corrected value of the FRA6 register is written to the FRA1 register.
- 4. This enables the setting errors of bit rates such as 9600 bps and 38400 bps to be 0% when the serial interface is used in UART mode.

**Table 5.11 Low-speed On-Chip Oscillator Circuit Electrical Characteristics** 

Symbol	Parameter	Condition		Unit		
Symbol		Condition	Min.	Тур.	Max.	Offic
fOCO-S	Low-speed on-chip oscillator frequency		30	125	250	kHz
_	Oscillation stability time		-	10	100	μS
=	Self power consumption at oscillation	Vcc = 5.0 V, Topr = 25°C	-	15	-	μΑ

# NOTE:

1. Vcc = 2.2 to 5.5 V,  $T_{opr} = -20$  to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.

**Table 5.12 Power Supply Circuit Timing Characteristics** 

Symbol	Parameter	Condition	,	Unit		
Symbol	r alametei	Condition		Тур.	Max.	Offic
td(P-R)	Time for internal power supply stabilization during power-on <sup>(2)</sup>		1	=	2000	μS
td(R-S)	STOP exit time <sup>(3)</sup>		-	-	150	μS

- 1. The measurement condition is Vcc = 2.2 to 5.5 V and Topr = 25°C.
- Waiting time until the internal power supply generation circuit stabilizes during power-on.
- 3. Time until system clock supply starts after the interrupt is acknowledged to exit stop mode.

Table 5.18 Serial Into
------------------------

Symbol	Parameter		Standard		
Symbol			Max.	Unit	
tc(CK)	CLKi input cycle time	200	-	ns	
tW(CKH)	CLKi input "H" width	100	-	ns	
tW(CKL)	CLKi input "L" width	100	-	ns	
td(C-Q)	TXDi output delay time	-	50	ns	
th(C-Q)	TXDi hold time	0	-	ns	
tsu(D-C)	RXDi input setup time	50	=	ns	
th(C-D)	RXDi input hold time	90	-	ns	

i = 0, 2

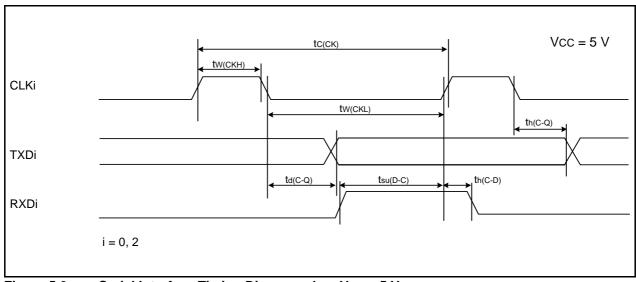


Figure 5.6 Serial Interface Timing Diagram when Vcc = 5 V

Table 5.19 External Interrupt INTi (i = 0, 1, 3) Input

Cymbol	Parameter	Stan	dard	Unit
Symbol	Falanetei		Max.	Offic
tW(INH)	ĪNTi input "H" width	250 <sup>(1)</sup>	-	ns
tW(INL)	INTi input "L" width	250 <sup>(2)</sup>	-	ns

- 1. When selecting the digital filter by the INTi input filter select bit, use an INTi input HIGH width of either (1/digital filter clock frequency x 3) or the minimum value of standard, whichever is greater.
- 2. When selecting the digital filter by the INTi input filter select bit, use an INTi input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

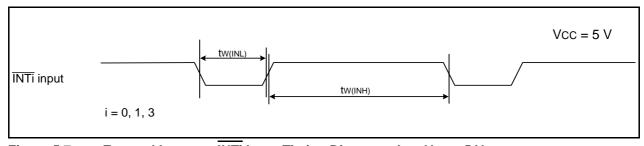


Figure 5.7 External Interrupt INTi Input Timing Diagram when Vcc = 5 V

Table 5.21 Electrical Characteristics (2) [Vcc = 3 V] (Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition		Standard			Unit
Symbol	Parameter		Condition	Min.	Тур.	Max.	Unit
Icc	Power supply current (Vcc = 2.7 to 3.3 V) Single-chip mode, output pins are open,	High-speed clock mode	XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	6	-	mA
	other pins are Vss		XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8		2	_	mA
		High-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator on fOCO = 10 MHz Low-speed on-chip oscillator on = 125 kHz No division	=	5	9	mA
		mode	XIN clock off High-speed on-chip oscillator on fOCO = 10 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	=	2	-	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR47 = 1	-	130	300	μА
	Wait mode  XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	25	70	μА		
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	=	23	55	μА
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	0.7	3.0	μΑ
			XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	1.1	-	μА

Table 5.26 Electrical Characteristics (1) [Vcc = 2.2 V]

Symbol	Parameter		Condition		Standard			Unit
Symbol	Fair	ametei	Cond	altion	Min.	Тур.	Max.	Offic
Vон	Output "H" voltage	Except P2_0 to P2_7, XOUT	lон = −1 mA		Vcc - 0.5	_	Vcc	V
		P2_0 to P2_7	Drive capacity HIGH	Iон = −2 mA	Vcc - 0.5	=	Vcc	V
			Drive capacity LOW	Iон = −1 mA	Vcc - 0.5	=	Vcc	V
		XOUT	Drive capacity HIGH	Iон = -0.1 mA	Vcc - 0.5	1	Vcc	V
			Drive capacity LOW	IOH = -50 μA	Vcc - 0.5	1	Vcc	V
Vol	Output "L" voltage	Except P2_0 to P2_7, XOUT	IoL = 1 mA		-	=	0.5	V
		P2_0 to P2_7	Drive capacity HIGH	IOL = 2 mA	-	-	0.5	V
			Drive capacity LOW	IOL = 1 mA	=	=	0.5	V
		XOUT	Drive capacity HIGH	IOL = 0.1 mA	=	=	0.5	V
			Drive capacity LOW	IOL = 50 μA	=	-	0.5	V
VT+-VT-	Hysteresis	INT0, INT1, INT3, KI0, KI1, KI2, KI3, TRAIO, RXD0, RXD2, CLK0, CLK2		•	0.05	0.3	-	V
		RESET			0.05	0.15	-	V
lін	Input "H" current		VI = 2.2 V		-	-	4.0	μА
lıL	Input "L" current		VI = 0 V		=	-	-4.0	μΑ
RPULLUP	Pull-up resistance		VI = 0 V		100	200	600	kΩ
RfXIN	Feedback resistance	XIN			-	5	-	MΩ
VRAM	RAM hold voltage		During stop mod	e	1.8	I	-	V

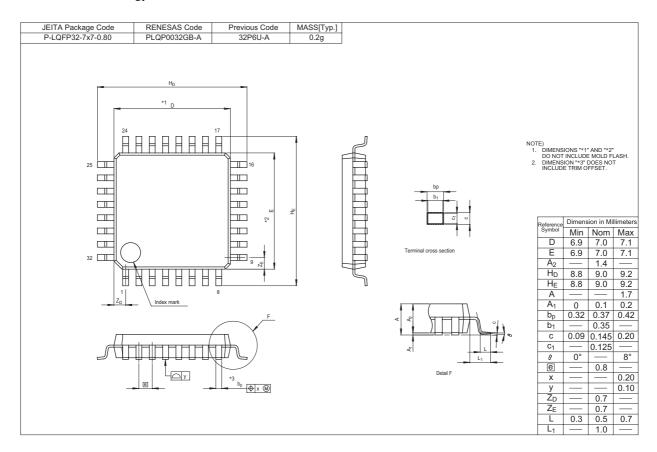
<sup>1.</sup> Vcc = 2.2 V at Topr = -20 to  $85^{\circ}C$  (N version) / -40 to  $85^{\circ}C$  (D version), f(XIN) = 5 MHz, unless otherwise specified.

Table 5.27 Electrical Characteristics (2) [Vcc = 2.2 V]  $(Topr = -20 \text{ to } 85^{\circ}\text{C (N version)} / -40 \text{ to } 85^{\circ}\text{C (D version)}, \text{ unless otherwise specified.})$ 

Symbol	Parameter		Condition		Standar	d	Unit
Symbol	Farameter		Condition	Min.	Тур.	Max.	Offic
Icc	Power supply current (Vcc = 2.2 to 2.7 V) Single-chip mode, output pins are open.	High-speed clock mode	XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	3.5	_	mA
	other pins are Vss		XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	1.5	_	mA
		High-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator on fOCO = 5 MHz Low-speed on-chip oscillator on = 125 kHz No division	_	3.5	_	mA
		mode	XIN clock off High-speed on-chip oscillator on fOCO = 5 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	1.5	_	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR47 = 1	_	100	230	μА
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	22	60	μА
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	20	55	μА
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	0.7	3.0	μΑ
			XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	1.1	-	μА

# **Package Dimensions**

Diagrams showing the latest package dimensions and mounting information are available in the "Packages" section of the Renesas Technology website.



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