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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	16MHz
Connectivity	UART/USART
Peripherals	-
Number of I/O	32
Program Memory Size	8KB (8K x 8)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	236 x 8
Voltage - Supply (Vcc/Vdd)	-
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e2116fsc00tr

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



# **Z86E21**

# CMOS Z8® OTP MICROCONTROLLER

#### GENERAL DESCRIPTION

The Z86E21 microcontroller (MCU) introduces the next level of sophistication to single-chip architecture. The Z86E21 is a member of the Z8 single-chip microcontroller family with 8 Kbytes of EPROM and 236 bytes of general purpose RAM.

The Z86E21 is a pin compatible, One-Time-Programmable (OTP) version of the Z86C21. The Z86E21 contains 8 Kbytes of EPROM memory in place of the 8 Kbyte of ROM on the Z86C21.

The MCU is housed in a 40-pin DIP, 44-pin Leaded Chip-Carrier, or a 44-pin Quad Flat Pack, and is manufactured in CMOS technology. The ROMless pin option is available on the 44-pin versions only. The MCU can address both external memory and preprogrammed ROM which enables this Z8 microcomputer to be used in high volume applications or where code flexibility is required.

Zilog's CMOS microcontroller offers fast execution, efficient use of memory, sophisticated interrupts, input/output bit manipulation capabilities, and easy hardware/software system expansion along with low cost and low power consumption.

The Z86E21 architecture is based on Zilog's 8-bit microcontroller core. The device offers a flexible I/O scheme, an efficient register and address space structure, multiplexed capabilities between address/data, I/O, and a number of ancillary features that are useful in many industrial and advanced scientific applications.

The device applications demand powerful I/O capabilities. The Z86E21 fulfills this with 32-pin dedicated to input and output. These lines are grouped into four ports. Each port consists of eight lines, and is configurable under software control to provide timing, status signals, serial or parallel I/O with or without handshake, and an address/data bus for interfacing external memory.

There are three basic address spaces available to support this wide range of configuration: Program Memory, Data Memory and 236 General-Purpose registers.

To unburden the program from coping with real-time problems such as counting/timing and serial data communication, the Z86E21 offers two on-chip counter/timers with a large number of user selectable modes, and an asynchronous receiver/transmitter (UART) (see Functional Block Description).

In ROM Protect Mode, the instructions LDC, LDCI, LDE and LDEI are disabled when reading address locations %0000 to %1FFF.

#### Notes:

All Signals with a preceding front slash, "/", are active Low, e.g.: B//W (WORD is active Low); /B/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

Connection	Circuit	Device
Power Ground	V <sub>cc</sub> GND	$egin{array}{c} egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}$

#### PRODUCT RECOMMENDATIONS

Zilog recommends the following programming equipment for use with this One-Time-Programmable product:

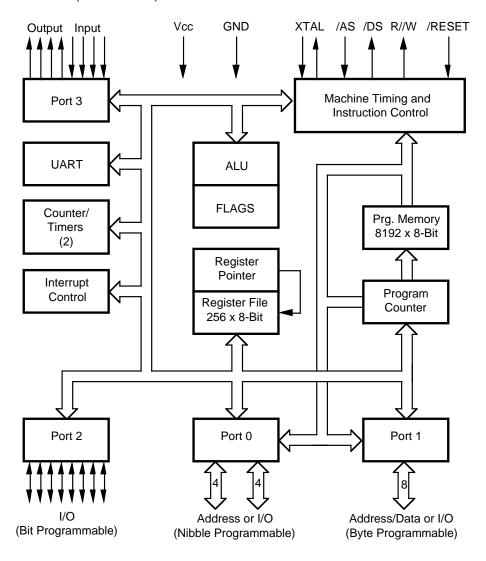
Device	Zilog Support Tool	Recommended Hardware	Revision Level Software
Z86E21	Z86C1200ZEM ICEBOX™ Emulator* (*Does not support 4K/8K option.)	В	1.5
Z86E21	Data I/O 3900 Programmer* (*Does not support option bits.)		1.1
Z86E21	Data I/O Unisite Programmer* (*Does not support option bits.)		3.7

Some non-Zilog programmers may have different programming waveforms, voltages and timings and not all programmers may meet the programming requirements of Zilog's One-Time-Programmable products.

If difficulty is encountered in programming a Zilog OTP product, please contact your local Zilog sales office.

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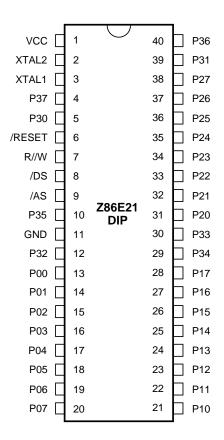
# **GENERAL DESCRIPTION** (Continued)



**Functional Block Diagram** 

### **PIN DESCRIPTION**

Standard Mode



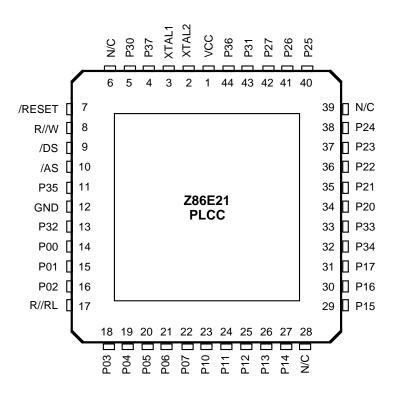
#### **40-Lead DIP Pin Assignments**

#### 40-Lead DIP Pin Identification

Pin #	Symbol	Function	Direction
1 2 3 4 5	V <sub>cc</sub> XTAL2 XTAL1 P37 P30	Power Supply Crystal, Oscillator Clock Crystal, Oscillator Clock Port 3 pin 7 Port 3 pin 0	Input Output Input Output Input
6 7 8 9 10	/RESET R//W /DS /AS P35	Reset Read/Write Data Strobe Address Strobe Port 3 pin 5	Input Output Output Output Output

Pin #	Symbol	Function	Direction
11	GND	Ground, GND	Input
12	P32	Port 3 pin 2	Input
13-20	P00-P07	Port 0 pin 0,1,2,3,4,5,6,7	In/Output
21-28	P10-P17	Port 1 pin 0,1,2,3,4,5,6,7	In/Output
29	P34	Port 3 pin 4	Output
30	P33	Port 3 pin 3	Input
31-38	P20-P27	Port 2 pin 0,1,2,3,4,5,6,7	In/Output
39	P31	Port 3 pin 1	Input
40	P36	Port 3 pin 6	Output

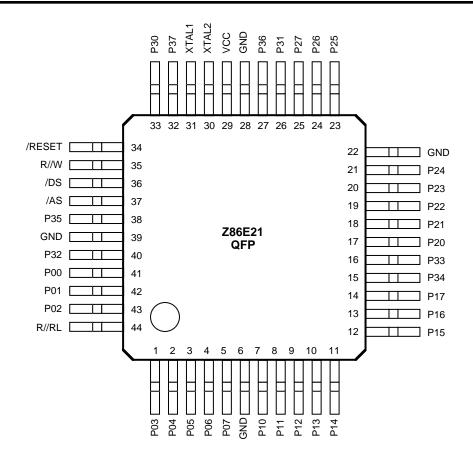
# **PIN DESCRIPTION** (Continued) Standard Mode



44-Lead PLCC Pin Assignments

#### **44-Lead PLCC Pin Identification**

Pin #	Symbol	Function	Direction	Pin #	Symbol	Function
1	V <sub>CC</sub>	Power Supply	Input	14-16	P00-P02	Port 0 pin
2	XTAL2	Crystal, Oscillator Clock	Output	17	R//RL	ROM/ROM
3	XTAL1	Crystal, Oscillator Clock	Input	18-22	P03-P07	Port 0 pin 3
4	P37	Port 3 pin 7	Output	23-27	P10-P14	Port 1 pin 0
5	P30	Port 3 pin 0	Input	28	N/C	Not Conne
6	N/C	Not Connected	Input	29-31	P15-P17	Port 1 pin
7	/RESET	Reset	Input	32	P34	Port 3 pin
8	R//W	Read/Write	Output	33	P33	Port 3 pin 3
9	/DS	Data Strobe	Output	34-38	P20-P24	Port 2 pin 0
10	/AS	Address Strobe	Output	39	N/C	Not Connec
11	P35	Port 3 pin 5	Output	40-42	P25-P27	Port 2 pin 5,
12	GND	Ground, GND	Input	43	P31	Port 3 pin 1
13	P32	Port 3 pin 2	Input	44	P36	Port 3 pin 6



44-Lead QFP Pin Assignments

#### 44-Lead QFP Pin Identification

Pin #	Symbol	Function	Direction
1-5	P03-P07	Port 0 pin 3,4,5,6,7	In/Output
6	GND	Ground, GND	Input
7-14	P10-P17	Port 1 pin 0,1,2,3,4,5,6,7	In/Output
15	P34	Port 3 pin 4	Output
16	P33	Port 3 pin 3	Input
17-21	P20-P24	Port 2 pin 0,1,2,3,4	In/Output
22	GND	Ground, GND	Input
23-25	P25-P27	Port 2 pin 5,6,7	In/Output
26	P31	Port 3 pin 1 Port 3 pin 6 Ground, GND Power Supply Crystal, Oscillator Clock	Input
27	P36		Output
28	GND		Input
29	V <sub>CC</sub>		Input
30	XTAL2		Output

Pin#	Symbol	Function	Direction
31	XTAL1	Crystal, Oscillator Clock	Input
32	P37	Port 3 pin 7	Output
33	P30	Port 3 pin 0	Input
34	/RESET	Reset	Input
35	R//W	Read/Write	Output
36	/DS	Data Strobe	Output
37	/AS	Address Strobe	Output
38	P35	Port 3 pin 5	Output
39	GND	Ground, GND Port 3 pin 2 Port 0 pin 0,1,2 ROM/ROMless control	Input
40	P32		Input
41-43	P00-P02		In/Output
44	R//RL		Input

### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Description	Min	Max	Units
V <sub>CC</sub> T <sub>STG</sub>	Supply Voltage* Storage Temp Oper Ambient Temp	-0.3 -65	+7.0 +150 +	V C C

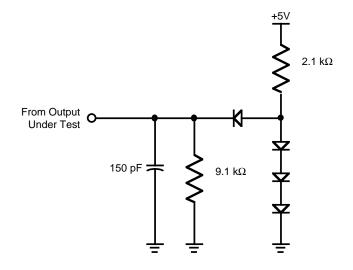
#### Notes:

- Voltages on all pins with respect to GND.
   13.0 V Maximum on P30-P33.
- † See Ordering Information

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability.

#### STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (Test Load Diagram).



**Test Load Diagram** 

# **DC CHARACTERISTICS**

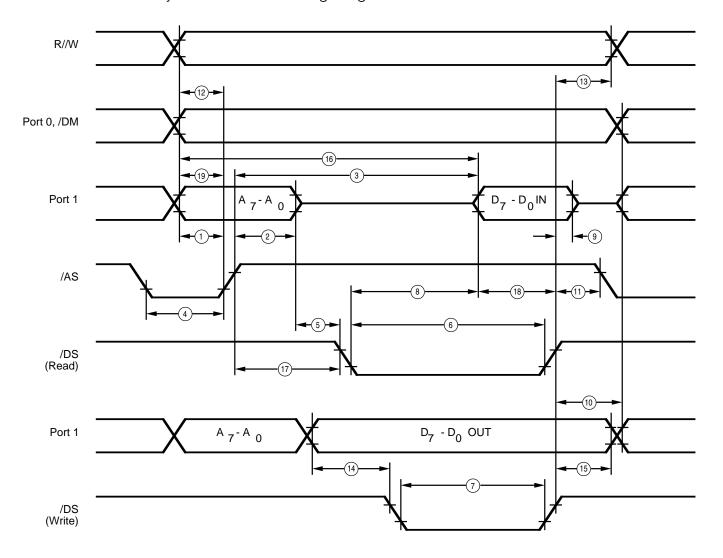
			: 0°C 70°C	T <sub>A</sub> = 1	-40°C 05°C	Typical		
Sym	. Parameter	Min	Max	Min	Max	@ <sup>°</sup> 25°C	Units	Conditions
	Max Input Voltage		7		7		V	I <sub>IN</sub> 250 μA
	Max Input Voltage		13		13		V	P30-P33 Only
$V_{CH}$	Clock Input High Voltage	3.8	$V_{cc}$	3.8	$V_{CC}$		V	Driven by External Clock Generator
V <sub>CL</sub>	Clock Input Low Voltage	-0.03	0.8	-0.03	0.8		V	Driven by External Clock Generator
V <sub>IH</sub>	Input High Voltage	2.0	V <sub>CC</sub> 0.8	2.0	V <sub>CC</sub> 0.8		V	
V".	Input Low Voltage	-0.3	8.0	-0.3	8.0		V	
V <sub>IL</sub> V <sub>OH</sub>	Output High Voltage	2.4		2.4			V	$I_{OH} = -2.0 \text{ mA}$
$V_{OL}^{OI}$	Output Low Voltage		0.4		0.4		V	$I_{OH} = -2.0 \text{ mA}$ $I_{OL} = +2.0 \text{ mA}$
V <sub>RH</sub>	Reset Input High Voltage	3.8	V <sub>CC</sub>	3.8	V <sub>cc</sub>		V	
$V_{RI}$	Reset Input Low Voltage	-0.03	8.0	-0.03	0.8		V	
I <sub>IL</sub> "	Input Leakage	-10	10	-10	10		μΑ	0V V <sub>IN</sub> +5.25V
I <sub>OL</sub>	Output Leakage	-10	10	-10	10		μA	0V V <sub>IN</sub> +5.25V
I <sub>IR</sub>	Reset Input Current		-50		-50		μA	$V_{CC} = +5.25V, V_{RI} = 0V$
l <sub>cc</sub>	Supply Current		50		50	25	mΑ	@ 12 MHz
00			60		60	35	mA	@ 16 MHz
I <sub>CC1</sub>	Standby Current		15		15	5	mA	HALT Mode V <sub>IN</sub> = OV, V <sub>CC</sub> @ 12 MHz
			20		20	10	mΑ	HALT Mode $V_{IN} = OV$ , $V_{CC} @ 16$ MHz
$I_{CC2}$	Standby Current		20		20	5	μA	STOP Mode $V_{IN}^{IN} = OV$ , $V_{CC}^{OO}$ 12 MHz
002			20		20	5	μA	STOP Mode V <sub>IN</sub> = OV, V <sub>CC</sub> @ 16 MHz

#### Notes:

I core requires loading TMR (%F1H) with any value prior to STOP execution. Use this sequence:

LD TMR,#00 NOP

**AC CHARACTERISTICS**External I/O or Memory Read or Write Timing Diagram



**External I/O or Memory Read/Write Timing** 

**AC CHARACTERISTICS**External I/O or Memory Read and Write Timing Table

					to 70				C to 1			
No	Symbol	Parameter	Max	MHz Min	16 M Max		12 N Max		16 M Max		Units	Notes
1	TdA(AS)	Address Valid to /AS Rise Delay	35		20		35		25		ns	[2,3]
2	TdAS(A)	/AS Rise to Address Float Delay	45		30		45		35		ns	[2,3]
3	TdAS(DR)	/AS Rise to Read Data Reg'd Valid		220		180		250		180	ns	[1,2,3]
4	TwAS	/AS Low Width	55		35		55		40		ns	[2,3]
5	TdAZ(DS)	Address Float to /DS Fall	0		0		0		0		ns	
6	TwDSR	/DS (Read) Low Width	185		135		185		135		ns	[1,2,3]
7	TwDSW	/DS (Write) Low Width	110		80		110		80		ns	[1,2,3]
8	TdDSR(DR)	/DS Fall to Read Data Req'd Valid		130		75		130		75	ns	[1,2,3]
9	ThDR(DS)	Read Data to /DS Rise Hold Time	0		0		0		0		ns	[2,3]
10	TdDS(A)	/DS Rise to Address Active Delay	45		35		65		50		ns	[2,3]
11	TdDS(AS)	/DS Rise to /AS Fall Delay	55		30		45		35		ns	[2,3]
12	TdR/W(AS)	R//W Valid to /AS Rise Delay	30		20		33		25		ns	[2,3]
13	TdDS(R/W)	/DS Rise to R//W Not Valid	35		30		50		35		ns	[2,3]
14	TdDW(DSW)	Write Data Valid to /DS Fall (Write) Delay	35		25		35		25		ns	[2,3]
15	TdDS(DW)	/DS Rise to Write Data Not Valid Delay	35		30		55		35		ns	[2,3]
16	TdA(DR)	Address Valid to Read Data Req'd Valid		255		200		310		230	ns	[1,2,3]
17	TdAS(DS)	/AS Rise to /DS Fall Delay	55		40		65		45		ns	[2,3]
18	TdDI(DS)	Data Input Setup to /DS Rise	75		60		75		60		ns	[1,2,3]
19	TdDM(AS)	/DM Valid to /AS Fall Delay	50		30		50		30		ns	[2,3]

#### Notes:

- [1] When using extended memory timing add 2 TpC.
- [2] Timing numbers given are for minimum TpC.
- [3] See clock cycle dependent characteristics table.

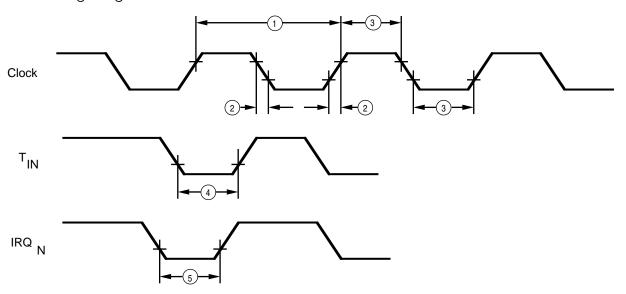
### Standard Test Load

All timing references use 2.0V for a logic 1 and 0.8V for a logic 0.

### **Clock Dependent Formulas**

Number	Symbol	Equation
1	TdA(AS)	0.40TpC + 0.32
2	TdAS(A)	0.59TpC - 3.25
3	TdAS(DR)	2.38TpC + 6.14
4	TwAS	0.66TpC - 1.65
6	TwDSR	2.33TpC - 10.56
7	TwDSW	1.27TpC + 1.67
8	TdDSR(DR)	1.97TpC - 42.5
10	TdDS(A)	0.8TpC
11	TdDS(AS)	0.59TpC - 3.14
12	TdR/W(AS)	0.4TpC
13	TdDS(R/W)	0.8TpC - 15
14	TdDW(DSW)	0.4TpC
15 16 17 18 19	TdDS(DW) TdA(DR) TdAS(DS) TsDI(DS) TdDM(AS)	0.88TpC - 19 4TpC - 20 0.91TpC - 10.7 0.8TpC - 10 0.9TpC - 26.3

**AC CHARACTERISTICS**Additional Timing Diagram



**Additional Timing** 

# **AC CHARACTERISTICS**

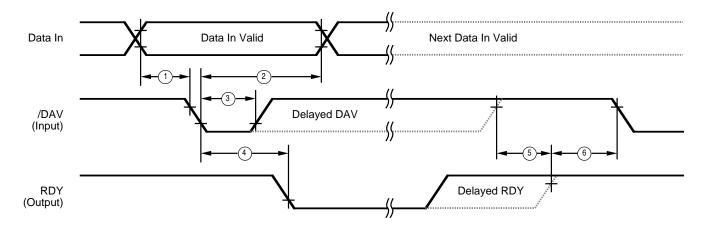
Additional Timing Table

N.a.	Comple of	Davamatar		T <sub>A</sub> = 0°C to 70°C 12 MHz 16 MHz			IHz 12	T <sub>A</sub> = -40°C to 105°C 12 MHz 16 MHz			l laita	Natas
<u>No</u>	Symbol	Parameter		Max	Min	Max	Min Ma	x Min	Max	Min	Units	Notes
1	TpC	Input Clock Period	83	1000	62.5	100	0 83	1000	62.5	1000	ns	[1]
2	TrC,TfC	Clock Input Rise & Fall Times		15		10		15		10	ns	[1]
3	TwC	Input Clock Width	37		21		37		21		ns	[1]
4	TwTinL	Timer Input Low Width	75		50		75		50		ns	[2]
5	TwTinH	Timer Input High Width	3TpC		3TpC	;	3TpC		3TpC			[2]
6	TpTin	Timer Input Period	8TpC		8TpC	,	8TpC		8TpC			[2]
7	TrTin,TfTin	Timer Input Rise & Fall Times	100		100		100		100		ns	[2]
8A	TwlL	Interrupt Request Input Low Times	70		50		70		50		ns	[2,4]
8B	TwlL	Interrupt Request Input Low Times	3TpC		3TpC	,	3TpC		3TpC			[2,5]
9	TwlH	Interrupt Request Input High Times	3TpC		3TpC	;	3TpC		3TpC			[2,3]

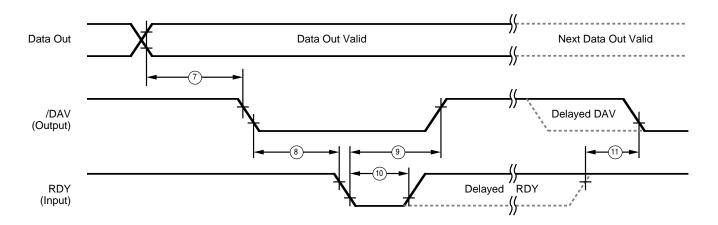
#### Notes:

- [1] Clock timing references use 3.8V for a logic 1 and 0.8V for a logic 0.
- [2] Timing references use 2.0V for a logic 1 and 0.8V for a logic 0.
- [3] Interrupt references request via Port 3.
- [4] Interrupt request via Port 3 (P31-P33).
- [5] Interrupt request via Port 30.

**AC CHARACTERISTICS** Handshake Timing Diagrams



**Input Handshake Timing** 



**Output Handshake Timing** 

#### **AC CHARACTERISTICS**

Handshake Timing Table

			$T_A = 0^{\circ}C \text{ to } 70^{\circ}C$ 12 MHz 16 MHz			$T_A = -40^{\circ}C \text{ to } 105^{\circ}C$ 12 MHz 16 MHz				Data	
No	Symbol	Parameter	Max	Min	Max	Min	Max	Min	Max	Min	Direction
1	TsDI(DAV)	Data In Setup Time	0		0		0		0		IN
2	ThDI(DAV)	Data In Hold Time	145		145		145		145		IN
3	TwDAV	Data Available Width	110		110		110		110		IN
4	TdDAVI(RDY)	DAV Fall to RDY Fall Delay		115		115		115		115	IN
5	TdDAVId(RDY)	DAV Rise to RDY Rise Delay		115		115		115		115	IN
6	TdDO(DAV)	RDY Rise to DAV Fall Delay	0		0		0		0		IN
7	TcLDAV0(RDY)	Data Out to DAV Fall Delay		TpC		TpC		TpC		TpC	OUT
8	TcLDAV0(RDY)	DAV Fall to RDY Fall Delay	0		0		0		0		OUT
9	TdRDY0(DAV)	RDY Fall to DAV Rise Delay		115		115		115		115	OUT
10	TwRDY	RDY Width	110		110		110		110		OUT
11	TdRDY0d(DAV)	RDY Rise to DAV Fall Delay		115		115		115		115	OUT

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