

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Details	
Product Status	Active
Core Processor	Z8
Core Size	8-Bit
Speed	16MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	24
Program Memory Size	2KB (2K x 8)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e3116seg

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Power connections follow conventional descriptions below:

Connection	Circuit	Device
Power	V _{CC}	V _{DD}
Ground	GND	V _{SS}

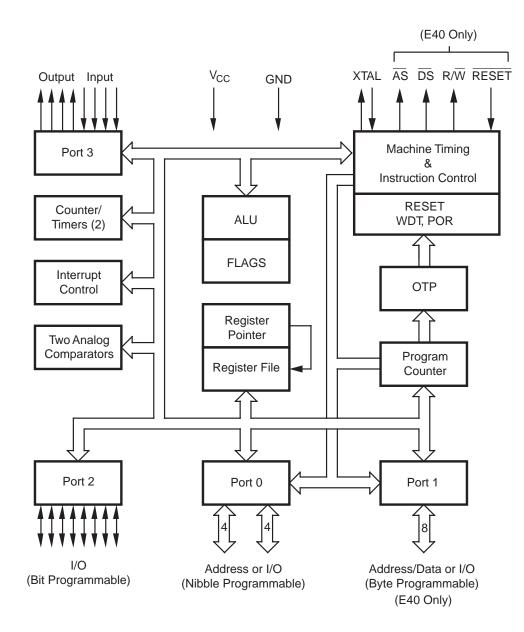


Figure 1. Z86E30/E31/E40 Functional Block Diagram

PIN IDENTIFICATION

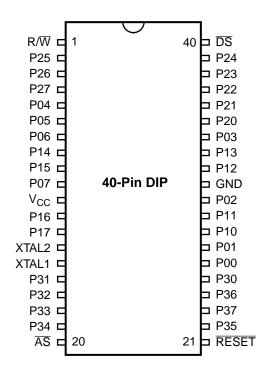


Figure 3. 40-Pin DIP Pin Configuration Standard Mode

Table 1. 40-Pin DIP Pin IdentificationStandard Mode

D: "	<u> </u>	– .:	D : /:
Pin #	Symbol	Function	Direction
1	R/W	Read/Write	Output
2–4	P25–P27	Port 2, Pins 5,6,7	In/Output
5–7	P04–P06	Port 0, Pins 4,5,6	In/Output
8–9	P14–P15	Port 1, Pins 4,5	In/Output
10	P07	Port 0, Pin 7	In/Output
11	V _{CC}	Power Supply	
12–13	P16–P17	Port 1, Pins 6,7	In/Output
14	XTAL2	Crystal Oscillator	Output
15	XTAL1	Crystal Oscillator	Input
16–18	P31–P33	Port 3, Pins 1,2,3	Input
19	P34	Port 3, Pin 4	Output
20	AS	Address Strobe	Output
21	RESET	Reset	Input
22	P35	Port 3, Pin 5	Output
23	P37	Port 3, Pin 7	Output
24	P36	Port 3, Pin 6	Output
25	P30	Port 3, Pin 0	Input
26–27	P00–P01	Port 0, Pins 0,1	In/Output
28–29	P10–P11	Port 1, Pins 0,1	In/Output
30	P02	Port 0, Pin 2	In/Output
31	GND	Ground	
32–33	P12–P13	Port 1, Pins 2,3	In/Output
34	P03	Port 0, Pin 3	In/Output
35–39	P20-P24	Port 2, Pins 0,1,2,3,4	In/Output
40	DS	Data Strobe	Output

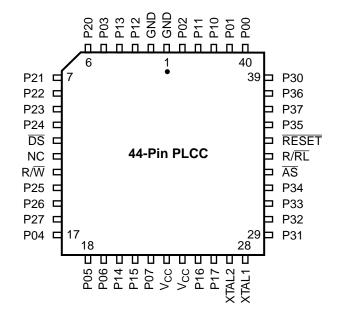


Figure 4. 44-Pin PLCC Pin Configuration Standard Mode

Table 2. 44-Pin PLCC Pin Identification

Pin #	Symbol	Function	Direction
1–2	GND	Ground	
3–4	P12–P13	Port 1, Pins 2,3	In/Output
5	P03	Port 0, Pin 3	In/Output
6–10	P20–P24	Port 2, Pins 0,1,2,3,4	In/Output
11	DS	Data Strobe	Output
12	NC	No Connection	
13	R/W	Read/Write	Output
14–16	P25–P27	Port 2, Pins 5,6,7	In/Output
17–19	P04–P06	Port 0, Pins 4,5,6	In/Output
20–21	P14–P15	Port 1, Pins 4,5	In/Output
22	P07	Port 0, Pin 7	In/Output
23–24	V _{CC}	Power Supply	
25–26	P16–P17	Port 1, Pins 6,7	In/Output
27	XTAL2	Crystal Oscillator	Output
28	XTAL1	Crystal Oscillator	Input
29–31	P31–P33	Port 3, Pins 1,2,3	Input
32	P34	Port 3, Pin 4	Output

Table 2. 44-Pin PLCC Pin Identification

Pin #	Symbol	Function	Direction
33	ĀS	Address Strobe	Output
34	R/RL	ROM/ROMless select	Input
35	RESET	Reset	Input
36	P35	Port 3, Pin 5	Output
37	P37	Port 3, Pin 7	Output
38	P36	Port 3, Pin 6	Output
39	P30	Port 3, Pin 0	Input
40–41	P00–P01	Port 0, Pins 0,1	In/Output
42–43	P10–P11	Port 1, Pins 0,1	In/Output
44	P02	Port 0, Pin 2	In/Output

PIN IDENTIFICATION (Continued)

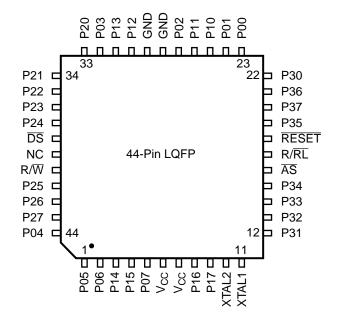


Figure 5. 44-Pin LQFP Pin Configuration Standard Mode

Table 3. 44-Pin LQFP Pin Identification

Pin #	Symbol	Function	Direction
1–2	P05-P06	Port 0, Pins 5,6	In/Output
3–4	P14–P15	Port 1, Pins 4,5	In/Output
5	P07	Port 0, Pin 7	In/Output
6–7	V _{CC}	Power Supply	
8–9	P16–P17	Port 1, Pins 6,7	In/Output
10	XTAL2	Crystal Oscillator	Output
11	XTAL1	Crystal Oscillator	Input
12–14	P31–P33	Port 3, Pins 1,2,3	Input
15	P34	Port 3, Pin 4	Output
16	ĀS	Address Strobe	Output
17	R/RL	ROM/ROMless select	Input
18	RESET	Reset	Input
19	P35	Port 3, Pin 5	Output
20	P37	Port 3, Pin 7	Output
21	P36	Port 3, Pin 6	Output
22	P30	Port 3, Pin 0	Input
23–24	P00-P01	Port 0, Pin 0,1	In/Output
25–26	P10–P11	Port 1, Pins 0,1	In/Output

Table 3. 44-Pin LQFP Pin Identification

Pin #	Symbol	Function	Direction
27	P02	Port 0, Pin 2	In/Output
28–29	GND	Ground	
30–31	P12–P13	Port 1, Pins 2,3	In/Output
32	P03	Port 0, Pin 3	In/Output
33–37	P20–4	Port 2, Pins 0,1,2,3,4	In/Output
38	DS	Data Strobe	Output
39	NC	No Connection	
40	R/W	Read/Write	Output
41–43	P25–P27	Port 2, Pins 5,6,7	In/Output
44	P04	Port 0, Pin 4	In/Output

DC ELECTRICAL CHARACTERISTICS (Continued)

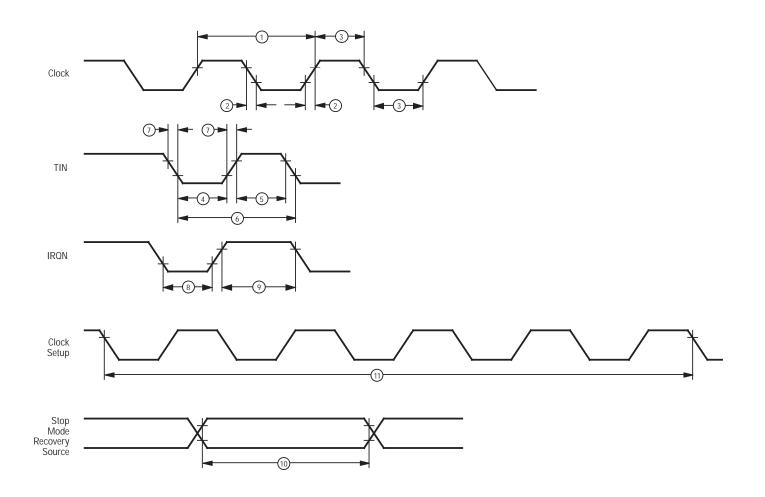
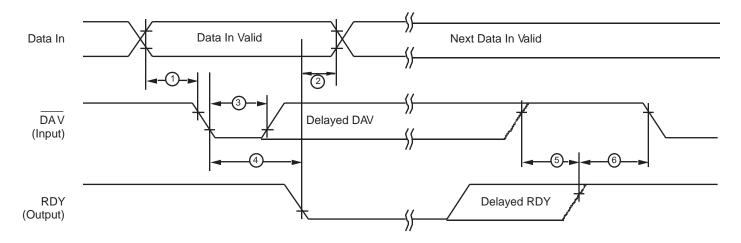


Figure 15. Additional Timing Diagram

Handshake Timing Diagrams





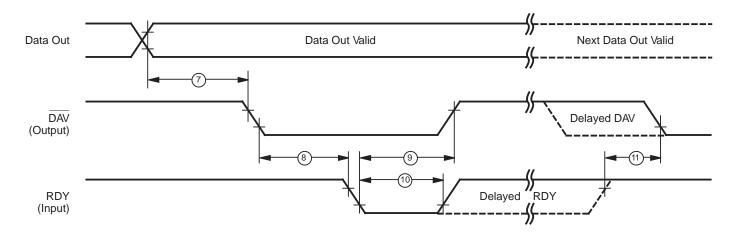


Figure 17. Output Handshake Timing

FUNCTIONAL DESCRIPTION

The MCU incorporates the following special functions to enhance the standard Z8 architecture to provide the user with increased design flexibility.

RESET. The device is reset in one of three ways:

- 1. Power-On Reset
- 2. Watch-Dog Timer
- 3. STOP-Mode Recovery Source

Note: Having the Auto Power-On Reset circuitry built-in, the MCU does not need to be connected to an external power-on reset circuit. The reset time is 5 ms (typical). The MCU does not reinitialize WDTMR, SMR, P2M, and P3M registers to their reset values on a STOP-Mode Recovery operation.

Note: The device V_{CC} must rise up to the operating V_{CC} specification before the TPOR expires.

Program Memory. The MCU can address up to 4 KB of Internal Program Memory (Figure 22). The first 12 bytes of program memory are reserved for the interrupt vectors. These locations contain six 16-bit vectors that correspond to the six available interrupts. For EPROM mode, byte 12 (000CH) to address 4095 (0FFFH) consists of programmable EPROM. After reset, the program counter points at the address 000CH, which is the starting address of the user program.

In ROMless mode, the Z86E40 can address up to 64 KB of External Program Memory. The ROM/ROMless option is only available on the 44-pin devices.

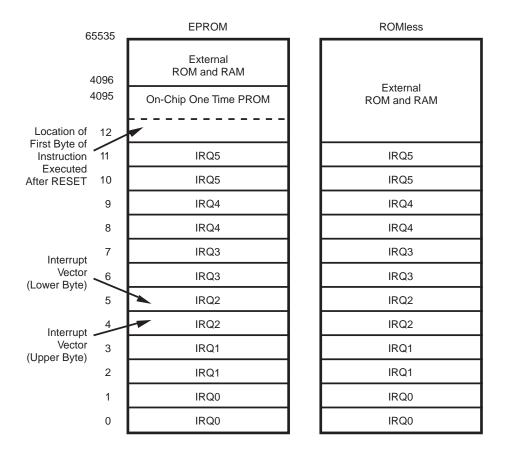


Figure 22. Program Memory Map (ROMIess Z86E40 Only)

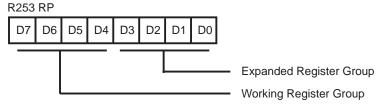
EPROM Protect. When in ROM Protect Mode, and executing out of External Program Memory, instructions LDC, LDCI, LDE, and LDEI cannot read Internal Program Memory.

When in ROM Protect Mode and executing out of Internal Program Memory, instructions LDC, LDCI, LDE, and LDEI can read Internal Program Memory.

Register File. The register file consists of three I/O port registers, 236/125 general-purpose registers, 15 control and status registers, and three system configuration registers in the expanded register group. The instructions can access registers directly or indirectly through an 8-bit address field. This allows a short 4-bit register address using the Register Pointer (Figure 24). In the 4-bit mode, the register file is divided into 16 working register groups, each

occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working-register group.

Note: Register Bank E0–EF can only be accessed through working register and indirect addressing modes. (This bank is available in Z86E30/E40 only.)



Default setting after RESET = 00000000

Figure 24. Register Pointer Register

Expanded Register File (ERF). The register file has been expanded to allow for additional system control registers, mapping of additional peripheral devices and input/output ports into the register address area. The Z8 register address space R0 through R15 is implemented as 16 groups of 16 registers per group (Figure 26). These register groups are known as the Expanded Register File (ERF).

The low nibble (D3–D0) of the Register Pointer (RP) select the active ERF group, and the high nibble (D7–D4) of register RP select the working register group. Three system configuration registers reside in the Expanded Register File at bank FH: PCON, SMR, and WDTMR. The rest of the Expanded Register is not physically implemented and is reserved for future expansion. **Interrupts.** The MCU has six different interrupts from six different sources. The interrupts are maskable and prioritized (Figure 28). The six sources are divided as follows: four sources are claimed by Port 3 lines P33–P30) and two

in counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests (Table 10).

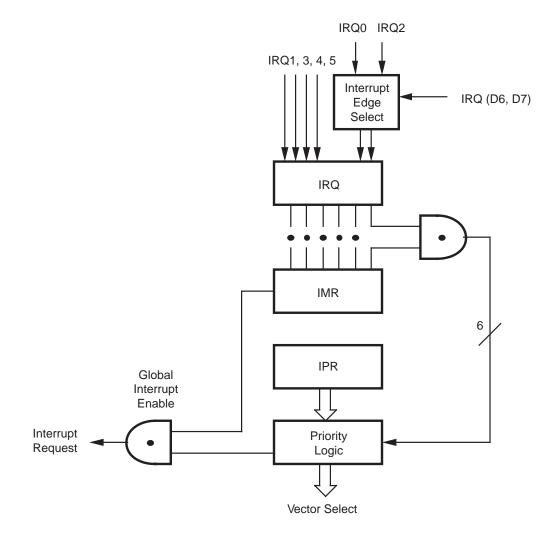




Table 10.	Interrupt Types,	Sources,	and Vectors
-----------	------------------	----------	-------------

Name	Source	Vector Location	Comments
IRQ0	DAV0, IRQ0	0, 1	External (P32), Rising/Falling Edge Triggered
IRQ1	IRQ1	2, 3	External (P33), Falling Edge Triggered
IRQ2	DAV2, IRQ2, T _{IN}	4, 5	External (P31), Rising/Falling Edge Triggered
IRQ3	IRQ3	6, 7	External (P30), Falling Edge Triggered
IRQ4	Т0	8, 9	Internal
IRQ5	TI	10, 11	Internal

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority Register (IPR). An interrupt machine cycle is activated when an interrupt request is granted. Thus, disabling all subsequent interrupts, saves the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt. All interrupts are vectored through locations in the program memory. This memory location and the next byte contain the 16-bit starting address of the interrupt service routine for that particular interrupt request.

To accommodate polled interrupt systems, interrupt inputs are masked and the interrupt request register is polled to determine which of the interrupt requests need service.

An interrupt resulting from AN1 is mapped into IRQ2, and an interrupt from AN2 is mapped into IRQ0. Interrupts IRQ2 and IRQ0 may be rising, falling or both edge triggered, and are programmable by the user. The software may poll to identify the state of the pin.

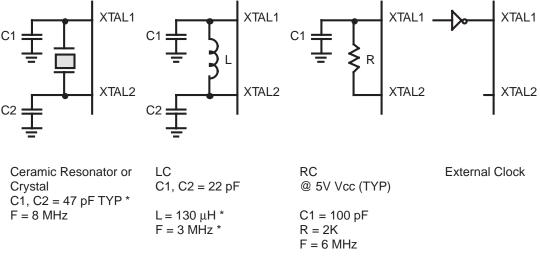
Programming bits for the Interrupt Edge Select are located in bits D7 and D6 of the IRQ Register (R250). The configuration is shown in Table 11. Table 11. IRQ Register Configuration

D7 D6	P31	P32
0		1 52
0 0	F	F
0 1	F	R
1 0	R	F
1 1	R/F	R/F

R = Rising Edge

Clock. The on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, RC, ceramic resonator, or any suitable external clock source (XTAL1 = Input, XTAL2 = Output). The crystal should be AT cut, 10 KHz to 16 MHz max, with a series resistance (RS) less than or equal to 100 Ohms.

The crystal should be connected across XTAL1 and XTAL2 using the vendor's recommended capacitor values from each pin directly to device pin Ground. The RC oscillator option can be selected in the programming mode. The RC oscillator configuration must be an external resistor connected from XTAL1 to XTAL2, with a frequency-setting capacitor from XTAL1 to Ground (Figure 29).



* Typical value including pin parasitics

Figure 29. Oscillator Configuration

FUNCTIONAL DESCRIPTION (Continued)

Power-On Reset (POR). A timer circuit clocked by a dedicated on-board RC oscillator is used for the Power-On Reset (POR) timer function. The POR timer allows V_{CC} and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- 1. Power fail to Power OK status
- 2. Stop-Mode Recovery (if D5 of SMR=0)
- 3. WDT time-out

The POR time is a nominal 5 ms. Bit 5 of the STOP mode Register (SMR) determines whether the POR timer is bypassed after STOP-Mode Recovery (typical for an external clock and RC/LC oscillators with fast start up times).

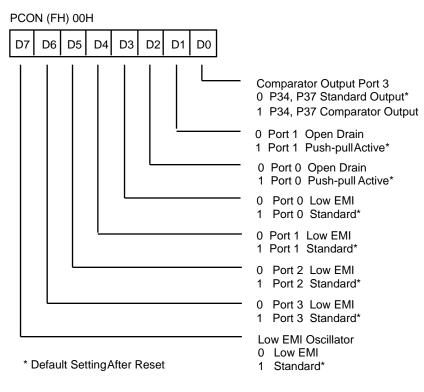
HALT. Turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupt IRQ0, IRQ1, and IRQ2 remain active. The device is recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT.

In order to enter STOP or HALT Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user must execute a NOP (Opcode=FFH) immediately before the appropriate sleep instruction, that is:

FF	NOP	; clear the pipeline
6F	STOP	; enter STOP Mode
	or	
FF	NOP	; clear the pipeline
7F	HALT	; enter HALT Mode

STOP. This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10 microamperes or less. STOP Mode is terminated by one of the following resets: either by WDT time-out, POR, a Stop-Mode Recovery Source, which is defined by the SMR register or external reset. This causes the processor to restart the application program at address 000CH.

Port Configuration Register (PCON). The PCON register configures the ports individually; comparator output on Port 3, open-drain on Port 0 and Port 1, low EMI on Ports 0, 1, 2 and 3, and low EMI oscillator. The PCON register is located in the expanded register file at Bank F, location 00 (Figure 30).





FUNCTIONAL DESCRIPTION (Continued)

EPROM MODE

Table 14 shows the programming voltages of each programming mode. Table 15, and figures that follow show the programming timing of each programming mode. Figure 38 shows the circuit diagram of a Z86E40 programming adapter, which adapts from 2764A to Z86E40 and Figure 39 shows the Z86E30/E31 Programming Adapter Circuitry. Figure 40 shows the flowchart of an Intelligent Programming Algorithm, which is compatible with 2764A EPROM (Z86E40 is 4K EPROM, 2764A is 8K EPROM). Since the EPROM size of Z86E30/E31/E40 differs from 2764A, the programming address range has to be set from 0000H to 0FFFH for the Z86E30/E40 and 0000H to 07FFH for Z86E31. Otherwise, the upper portion of EPROM data will overwrite the lower portion of EPROM data. Figure 39 shows the adaptation from the 2764A to Z86E30/E31.

Note: EPROM Protect feature allows the LDC, LDCI, LDE, and LDEI instructions from internal program memory. A ROM lookup table can be used with this feature.

During programming, the V_{PP} input pin supplies the programming voltage and current to the EPROM. This pin is also used to latch which EPROM mode is to be used (R/W EPROM or R/W Option bits). The mode is set by placing the correct mode number on the least significant bits of the address and raising the EPM pin above V. After a setup time, the V_{PP} pin can then be raised or lowered. The latched EPROM mode will remain until the EPM pin is reduced below V_H.

Mode Name	Mode #	LSB Addr
EPROM R/W	0	0000
Option Bit R/W	3	0011

EPROM R/W mode allows the programming of the user mode program ROM.

Option Bit R/W allows the programming of the Z8 option bits. When the device is latched into Option Bit R/W mode, the address must then be changed to 63 decimals (000000111111 Binary). The Options are mapped into this address as follows:

Bit	Option	
7	Unused	
6	Unused	
5	32 KHz XTAL Option	
4	Permanent WDT	
3	Auto Latch Disable	
2	RC Oscillator Option	
1	RAM Protect	
0	ROM Protect	
-		

Table 14 gives the proper conditions for EPROM R/W operations, once the mode is latched.

FUNCTIONAL DESCRIPTION (Continued)

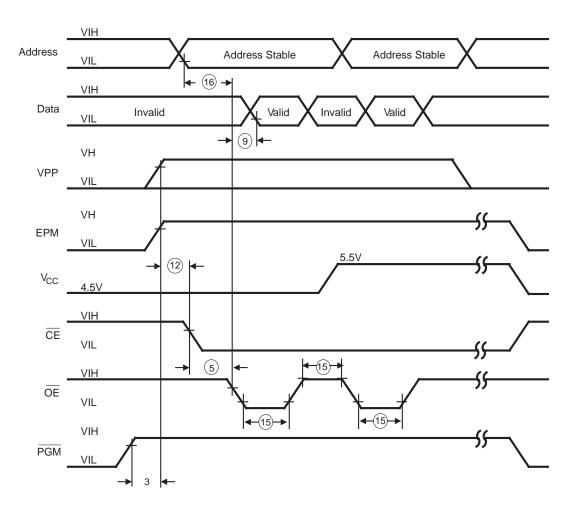


Figure 36. EPROM Read Mode Timing Diagram

Z86E40 TIMING DIAGRAMS

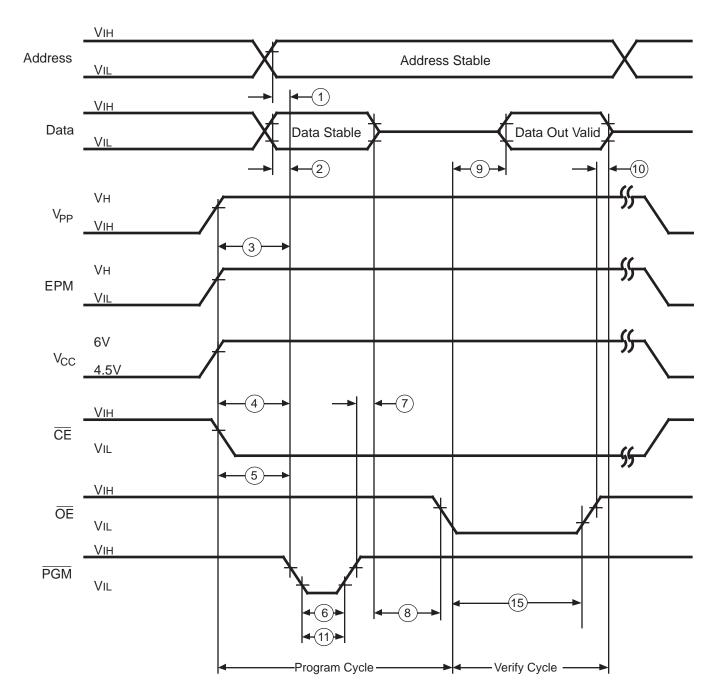
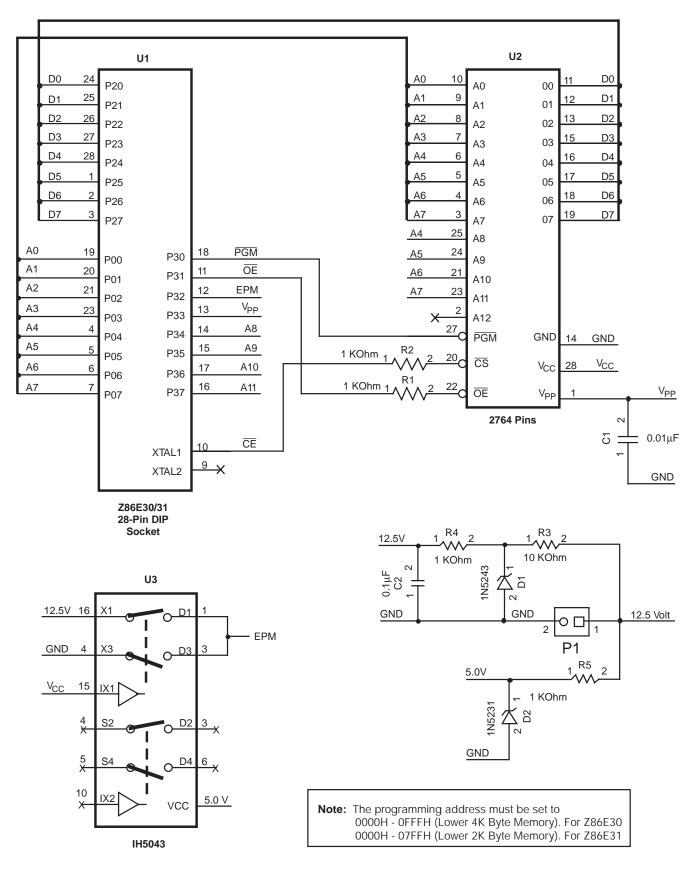


Figure 37. Timing Diagram of EPROM Program and Verify Modes





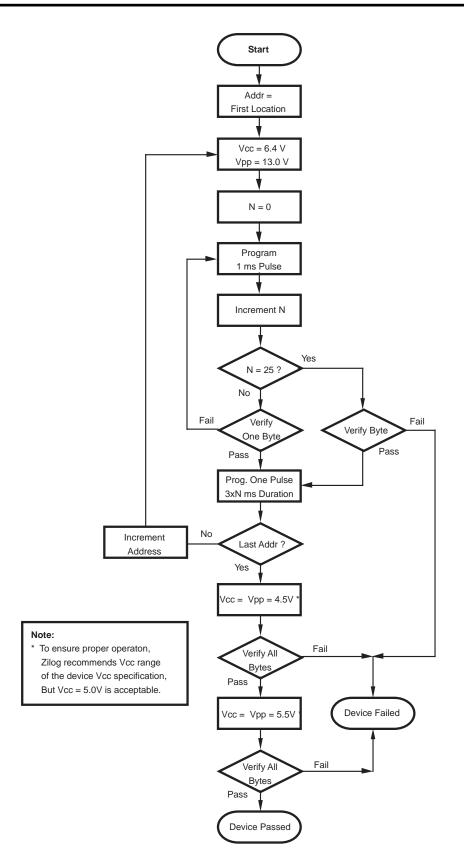
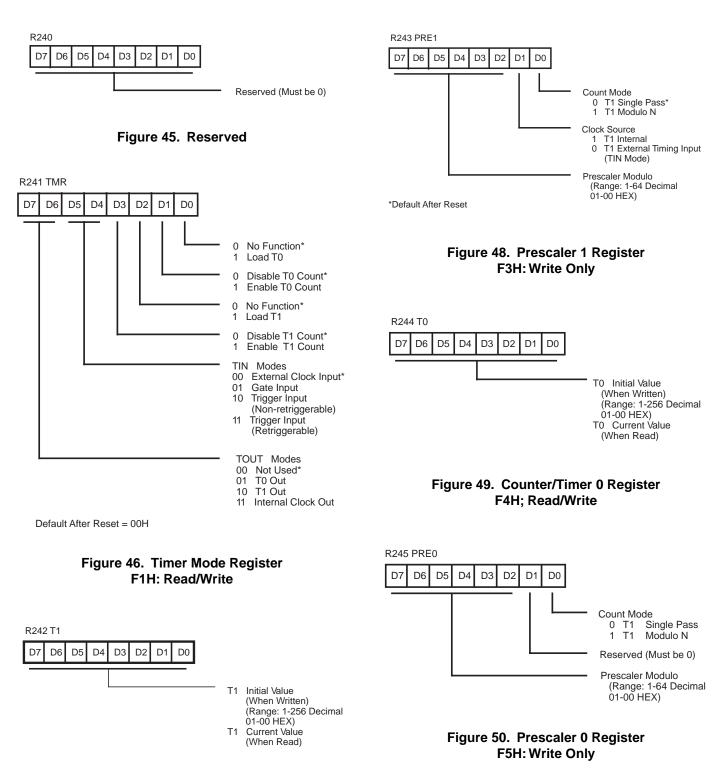
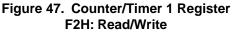


Figure 40. Z86E40 Programming Algorithm

Z8 CONTROL REGISTER DIAGRAMS





PACKAGE INFORMATION

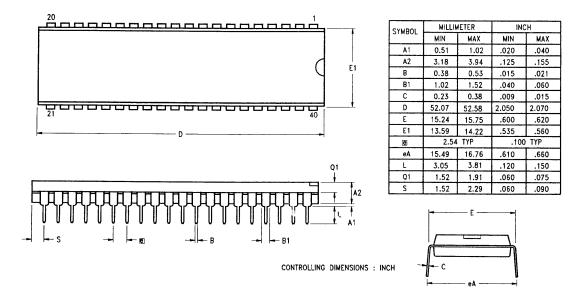


Figure 61. 40-Pin DIP Package Diagram

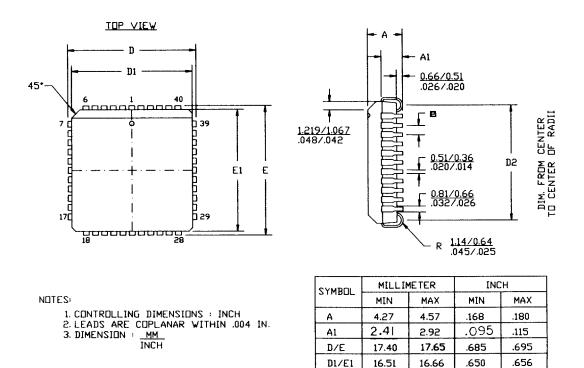


Figure 62. 44-Pin PLCC Package Diagram

D2

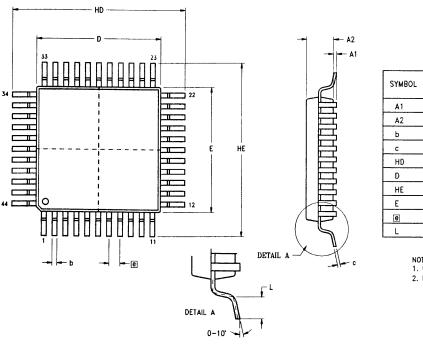
e

15.24

1.27 TYP

16.00

.600



SYMBOL	MILLIMETER		INCH	
	MIN	МАХ	MIN	MAX
A1	0.05	0.25	.002	.010
A2	2.00	2.25	.078	.089
b	0.25	0.45	.010	.018
с	0.13	0.20	.005	.008
HD	13.70	14.15	.539	.557
D	9.90	10.10	.390	.398
HE	13.70	14.15	.539	.557
E	9.90	10.10	.390	.398
θ	0.80 TYP		.0315 TYP	
L	0.60	1.20	.024	.047

.630

.050 TYP

Figure 63. 44-Pin LQFP Package Diagram

NOTES: 1. CONTROLLING DIMENSIONS : MILLIMETER 2. LEAD COPLANARITY : MAX .10 .004"

Customer Support

For answers to technical questions about the product, documentation, or any other issues with Zilog's offerings, please visit Zilog's Knowledge Base at <u>http://www.zilog.com/kb</u>.

For any comments, detail technical questions, or reporting problems, please visit Zilog's Technical Support at <u>http://support.zilog.com</u>.