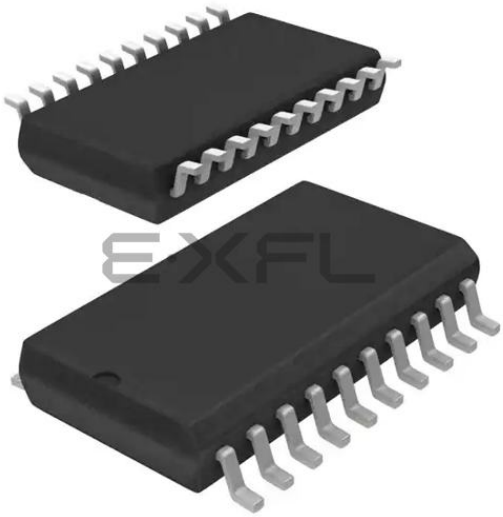

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	F²MC-8FX
Core Size	8-Bit
Speed	16MHz
Connectivity	LINbus, LPC, SIO, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	17
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	496 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.5V
Data Converters	A/D 6x8/10b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SOIC (0.295", 7.50mm Width)
Supplier Device Package	20-SOP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb95f203kpf-g-sne2

(Continued)

Part number / Parameter	MB95 F204H	MB95 F203H	MB95 F202H	MB95 F204K	MB95 F203K	MB95 F202K	MB95 F214H	MB95 F213H	MB95 F212H	MB95 F214K	MB95 F213K	MB95 F212K
Watch prescaler	Eight different time intervals can be selected.											
Flash memory	It supports automatic programming, Embedded Algorithm, write/erase/erase-suspend/erase-resume commands. It has a flag indicating the completion of the operation of Embedded Algorithm. Number of write/erase cycles: 100000 Data retention time: 20 years For write/erase, external Vpp(+10 V) input is required. Flash Security Feature for protecting the contents of the flash											
Standby mode	Sleep mode, stop mode, watch mode, timebase timer mode											
Package	SDIP-24 SOP-20						DIP-8 SOP-8					

2. Packages and Corresponding Products

Part number / Package	MB95 F204H	MB95 F203H	MB95 F202H	MB95 F204K	MB95 F203K	MB95 F202K	MB95 F214H	MB95 F213H	MB95 F212H	MB95 F214K	MB95 F213K	MB95 F212K
24-pin plastic SDIP	O	O	O	O	O	O	X	X	X	X	X	X
20-pin plastic SOP	O	O	O	O	O	O	X	X	X	X	X	X
8-pin plastic DIP	X	X	X	X	X	X	O	O	O	O	O	O
8-pin plastic SOP	X	X	X	X	X	X	O	O	O	O	O	O

O: Available

X: Unavailable

3. Differences Among Products And Notes On Product Selection

Current consumption

When using the on-chip debug function, take account of the current consumption of flash erase/program.

For details of current consumption, see “18.Electrical Characteristics”.

Package

For details of information on each package, see “2.Packages and Corresponding Products” and “22.Package Dimensions”.

Operating voltage

The operating voltage varies, depending on whether the on-chip debug function is used or not.

For details of the operating voltage, see “18.Electrical Characteristics”.

On-chip debug function

The on-chip debug function requires that V_{CC}, V_{SS} and 1 serial-wire be connected to an evaluation tool. In addition, if the flash memory data has to be updated, the RSTX/PF2 pin must also be connected to the same evaluation tool.

6. Pin Description (MB95200H Series 20 pins)

Pin no.	Pin name	I/O circuit type*	Function
1	PF0/X0	B	General-purpose I/O port This pin is also used as the main clock input oscillation pin.
2	PF1/X1	B	General-purpose I/O port This pin is also used as the main clock input/output oscillation pin.
3	V_{SS}	—	Power supply pin (GND)
4	PG2/X1A	C	General-purpose I/O port This pin is also used as the subclock input/output oscillation pin.
5	PG1/X0A	C	General-purpose I/O port This pin is also used as the subclock input oscillation pin.
6	V_{CC}	—	Power supply pin
7	C	—	Capacitor connection pin
8	PF2/RSTX	A	General-purpose I/O port This pin is also used as a reset pin. This pin is a dedicated reset pin in MB95F204H/F203H/F202H.
9	P62/TO10	D	General-purpose I/O port High-current port This pin is also used as the 8/16-bit composite timer ch. 1 output.
10	P63/TO11	D	General-purpose I/O port High-current port This pin is also used as the 8/16-bit composite timer ch. 1 output.
11	P64/EC1	D	General-purpose I/O port This pin is also used as the 8/16-bit composite timer ch. 1 clock input.
12	P00/AN00	E	General-purpose I/O port This pin is also used as the A/D converter analog input.
13	P01/AN01	E	General-purpose I/O port This pin is also used as the A/D converter analog input.
14	P02/INT02/AN02/SCK	E	General-purpose I/O port This pin is also used as the external interrupt input. This pin is also used as the A/D converter analog input. This pin is also used as the LIN-UART clock I/O.
15	P03/INT03/AN03/SOT	E	General-purpose I/O port This pin is also used as the external interrupt input. This pin is also used as the A/D converter analog input. This pin is also used as the LIN-UART data output.
16	P04/INT04/AN04/SIN /HCLK1/EC0	F	General-purpose I/O port This pin is also used as the external interrupt input. This pin is also used as the A/D converter analog input. This pin is also used as the LIN-UART data input. This pin is also used as the external clock input. This pin is also used as the 8/16-bit composite timer ch. 0 clock input.

(Continued)

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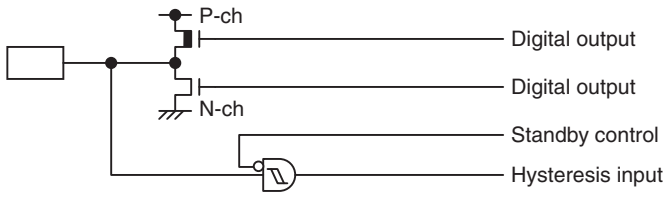
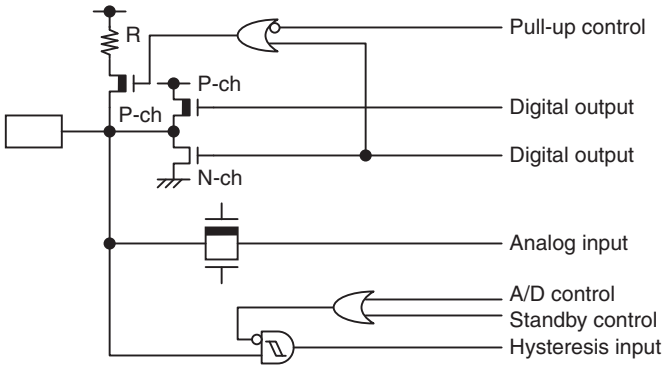
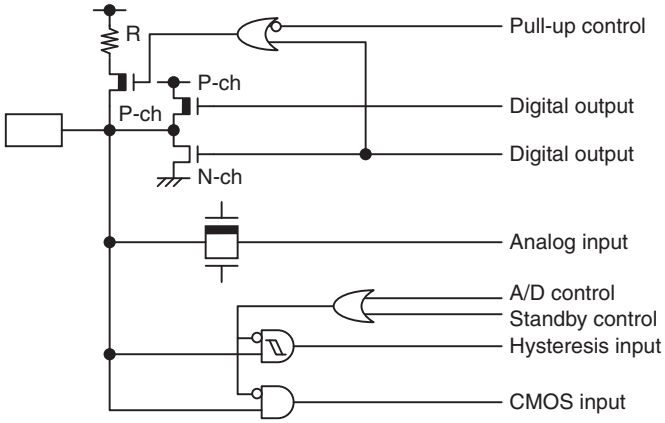
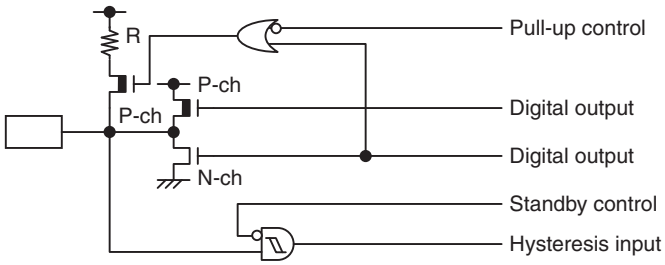
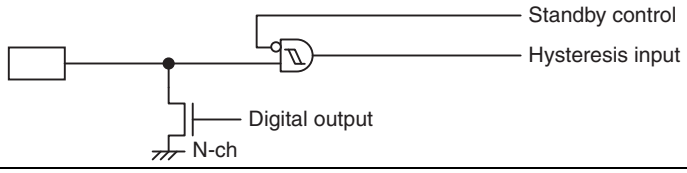
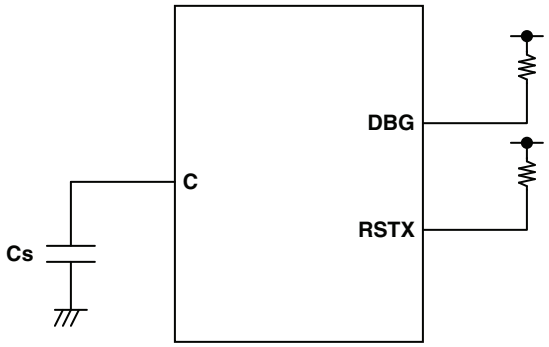
Type	Circuit	Remarks
D		• CMOS output • Hysteresis input
E		• CMOS output • Hysteresis input • Pull-up control available
F		• CMOS output • Hysteresis input • CMOS input • Pull-up control available
G		• Hysteresis input • CMOS output • Pull-up control available
H		• N-ch open drain output • Hysteresis input

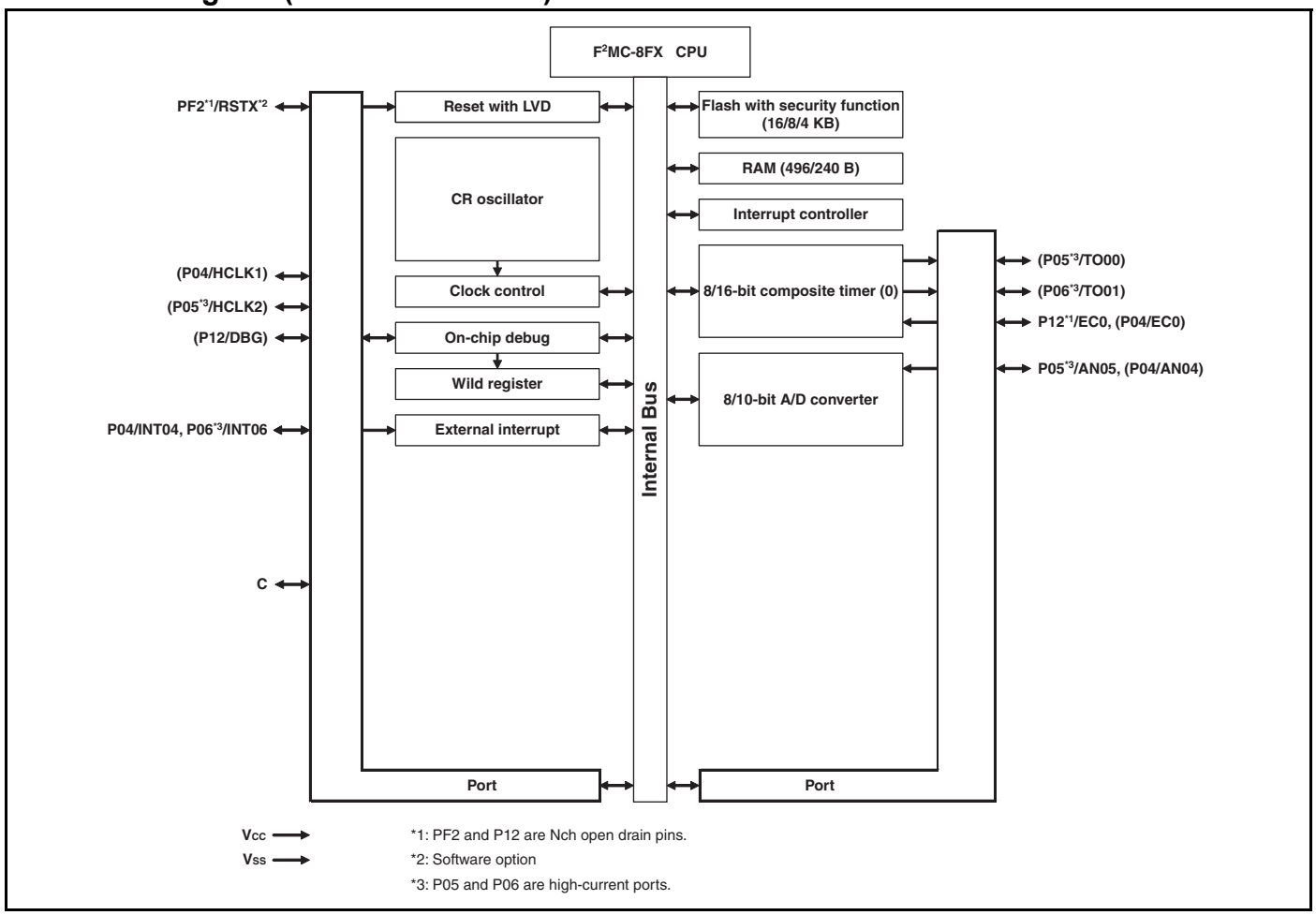
C pin

Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. The bypass capacitor for the V_{CC} pin must have a capacitance larger than C_S. For the connection to a smoothing capacitor C_S, see the diagram below. To prevent the device from unintentionally entering an unknown mode due to noise, minimize the distance between the C pin and C_S and the distance between C_S and the V_{SS} pin when designing the layout of a printed circuit board.

- DBG/RSTX/C pin connection diagram



12. Block Diagram (MB95210H Series)



14. I/O Map (MB95200H Series)

Address	Register abbreviation	Register name	R/W	Initial value
0000_H	PDR0	Port 0 data register	R/W	00000000_B
0001_H	DDR0	Port 0 direction register	R/W	00000000_B
0002_H	PDR1	Port 1 data register	R/W	00000000_B
0003_H	DDR1	Port 1 direction register	R/W	00000000_B
0004_H	—	(Disabled)	—	—
0005_H	WATR	Oscillation stabilization wait time setting register	R/W	11111111_B
0006_H	—	(Disabled)	—	—
0007_H	SYCC	System clock control register	R/W	$XXXXXX11_B$
0008_H	STBC	Standby control register	R/W	$00000XXX_B$
0009_H	RSRR	Reset source register	R	$XXXXXXXX_B$
$000A_H$	TBTC	Timebase timer control register	R/W	00000000_B
$000B_H$	WPCR	Watch prescaler control register	R/W	00000000_B
$000C_H$	WDTC	Watchdog timer control register	R/W	00000000_B
$000D_H$	SYCC2	System clock control register 2	R/W	$XX100011_B$
$000E_H$ to 0015_H	—	(Disabled)	—	—
0016_H	PDR6	Port 6 data register	R/W	00000000_B
0017_H	DDR6	Port 6 direction register	R/W	00000000_B
0018_H to 0027_H	—	(Disabled)	—	—
0028_H	PDRF	Port F data register	R/W	00000000_B
0029_H	DDRF	Port F direction register	R/W	00000000_B
$002A_H$	PDRG	Port G data register	R/W	00000000_B
$002B_H$	DDRG	Port G direction register	R/W	00000000_B
$002C_H$	PUL0	Port 0 pull-up register	R/W	00000000_B
$002D_H$ to 0034_H	—	(Disabled)	—	—
0035_H	PULG	Port G pull-up register	R/W	00000000_B
0036_H	T01CR1	8/16-bit composite timer 01 status control register 1 ch. 0	R/W	00000000_B
0037_H	T00CR1	8/16-bit composite timer 00 status control register 1 ch. 0	R/W	00000000_B
0038_H	T11CR1	8/16-bit composite timer 11 status control register 1 ch. 1	R/W	00000000_B
0039_H	T10CR1	8/16-bit composite timer 10 status control register 1 ch. 1	R/W	00000000_B
$003A_H$ to 0048_H	—	(Disabled)	—	—
0049_H	EIC10	External interrupt circuit control register ch. 2/ch. 3	R/W	00000000_B

(Continued)

15. I/O Map (MB95210H Series)

Address	Register abbreviation	Register name	R/W	Initial value
0000_H	PDR0	Port 0 data register	R/W	00000000_B
0001_H	DDR0	Port 0 direction register	R/W	00000000_B
0002_H	PDR1	Port 1 data register	R/W	00000000_B
0003_H	DDR1	Port 1 direction register	R/W	00000000_B
0004_H	—	(Disabled)	—	—
0005_H	WATR	Oscillation stabilization wait time setting register	R/W	11111111_B
0006_H	—	(Disabled)	—	—
0007_H	SYCC	System clock control register	R/W	$XXXXXX11_B$
0008_H	STBC	Standby control register	R/W	$00000XXX_B$
0009_H	RSRR	Reset source register	R	$XXXXXXXX_B$
$000A_H$	TBTC	Timebase timer control register	R/W	00000000_B
$000B_H$	WPCR	Watch prescaler control register	R/W	00000000_B
$000C_H$	WDTC	Watchdog timer control register	R/W	00000000_B
$000D_H$	SYCC2	System clock control register 2	R/W	$XX100011_B$
$000E_H$ to 0015_H	—	(Disabled)	—	—
0016_H	—	(Disabled)	—	—
0017_H	—	(Disabled)	—	—
0018_H to 0027_H	—	(Disabled)	—	—
0028_H	PDRF	Port F data register	R/W	00000000_B
0029_H	DDRF	Port F direction register	R/W	00000000_B
$002A_H$	—	(Disabled)	—	—
$002B_H$	—	(Disabled)	—	—
$002C_H$	PUL0	Port 0 pull-up register	R/W	00000000_B
$002D_H$ to 0034_H	—	(Disabled)	—	—
0035_H	—	(Disabled)	—	—
0036_H	T01CR1	8/16-bit composite timer 01 status control register 1 ch. 0	R/W	00000000_B
0037_H	T00CR1	8/16-bit composite timer 00 status control register 1 ch. 0	R/W	00000000_B
0038_H	—	(Disabled)	—	—
0039_H	—	(Disabled)	—	—
$003A_H$ to 0048_H	—	(Disabled)	—	—
0049_H	—	(Disabled)	—	—

(Continued)

17. Interrupt Source Table (MB95210H Series)

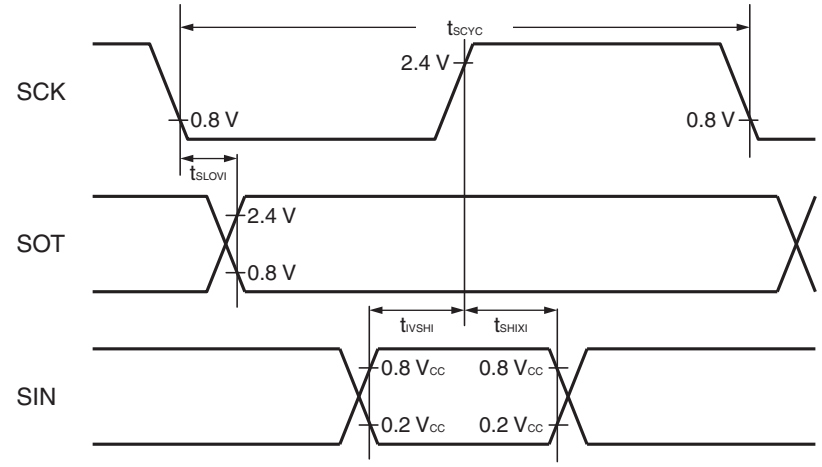
Interrupt source	Interrupt request number	Vector table address		Bit name of interrupt level setting register	Priority order of interrupt sources of the same level (occurring simultaneously)
		Upper	Lower		
External interrupt ch. 4	IRQ0	$FFFA_H$	$FFFB_H$	L00 [1:0]	High
—	IRQ1	$FFF8_H$	$FFF9_H$	L01 [1:0]	
—	IRQ2	$FFF6_H$	$FFF7_H$	L02 [1:0]	
External interrupt ch. 6					
—	IRQ3	$FFF4_H$	$FFF5_H$	L03 [1:0]	
—					
—	IRQ4	$FFF2_H$	$FFF3_H$	L04 [1:0]	
8/16-bit composite timer ch. 0 (Lower)	IRQ5	$FFF0_H$	$FFF1_H$	L05 [1:0]	
8/16-bit composite timer ch. 0 (Upper)	IRQ6	$FFEE_H$	$FFEF_H$	L06 [1:0]	
—	IRQ7	$FFEC_H$	$FFED_H$	L07 [1:0]	
—	IRQ8	$FFEA_H$	$FFEB_H$	L08 [1:0]	
—	IRQ9	$FFE8_H$	$FFE9_H$	L09 [1:0]	
—	IRQ10	$FFE6_H$	$FFE7_H$	L10 [1:0]	
—	IRQ11	$FFE4_H$	$FFE5_H$	L11 [1:0]	
—	IRQ12	$FFE2_H$	$FFE3_H$	L12 [1:0]	
—	IRQ13	$FFE0_H$	$FFE1_H$	L13 [1:0]	
—	IRQ14	$FFDE_H$	$FFDF_H$	L14 [1:0]	
—	IRQ15	$FFDC_H$	$FFDD_H$	L15 [1:0]	
—	IRQ16	$FFDA_H$	$FFDB_H$	L16 [1:0]	
—	IRQ17	$FFD8_H$	$FFD9_H$	L17 [1:0]	
8/10-bit A/D converter	IRQ18	$FFD6_H$	$FFD7_H$	L18 [1:0]	
Timebase timer	IRQ19	$FFD4_H$	$FFD5_H$	L19 [1:0]	
Watch prescaler	IRQ20	$FFD2_H$	$FFD3_H$	L20 [1:0]	
—	IRQ21	$FFD0_H$	$FFD1_H$	L21 [1:0]	
—	IRQ22	$FFCE_H$	$FFCF_H$	L22 [1:0]	
Flash memory	IRQ23	$FFCC_H$	$FFCD_H$	L23 [1:0]	Low

(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

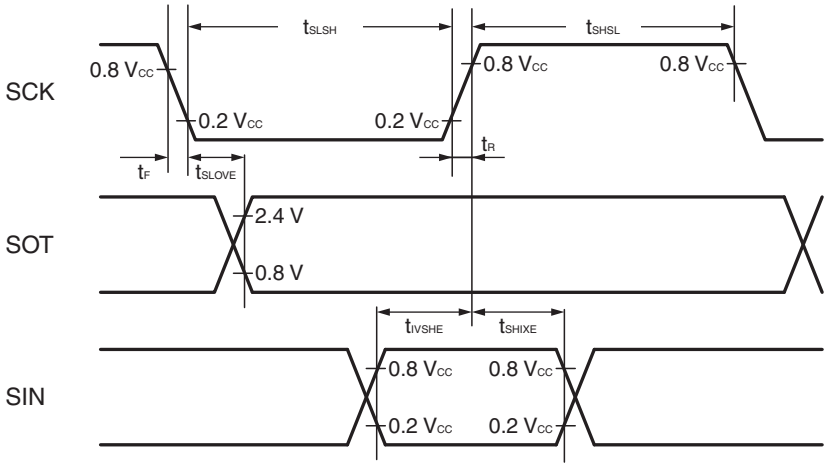
Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input capacitance	C_{IN}	Other than V_{CC} and V_{SS}	f = 1 MHz	—	5	15	pF	
Power supply current*4	I_{CC}	V_{CC} (External clock operation)	V_{CC} = 5.5 V F_{CH} = 32 MHz F_{MP} = 16 MHz Main clock mode (divided by 2)	—	13	17	mA	Flash memory product (except writing and erasing)
				—	33.5	39.5	mA	Flash memory product (at writing and erasing)
				—	15	21	mA	At A/D conversion
	I_{CCS}		V_{CC} = 5.5 V F_{CH} = 32 MHz F_{MP} = 16 MHz Main sleep mode (divided by 2)	—	5.5	9	mA	
	I_{CCL}		V_{CC} = 5.5 V F_{CL} = 32 kHz F_{MPL} = 16 kHz Subclock mode (divided by 2) T_A = +25 °C	—	65	153	µA	
	I_{CCLS}		V_{CC} = 5.5 V F_{CL} = 32 kHz F_{MPL} = 16 kHz Subsleep mode (divided by 2) T_A = +25 °C	—	10	84	µA	
	I_{CCT}		V_{CC} = 5.5 V F_{CL} = 32 kHz Watch mode Main stop mode T_A = +25°C	—	5	30	µA	

(Continued)

- Internal shift clock mode



- External shift clock mode



*Sampling is executed at the rising edge of the sampling clock*1, and serial clock delay is enabled*2.(ESCR register : SCES bit = 0, ECCR register : SCDE bit = 1)*

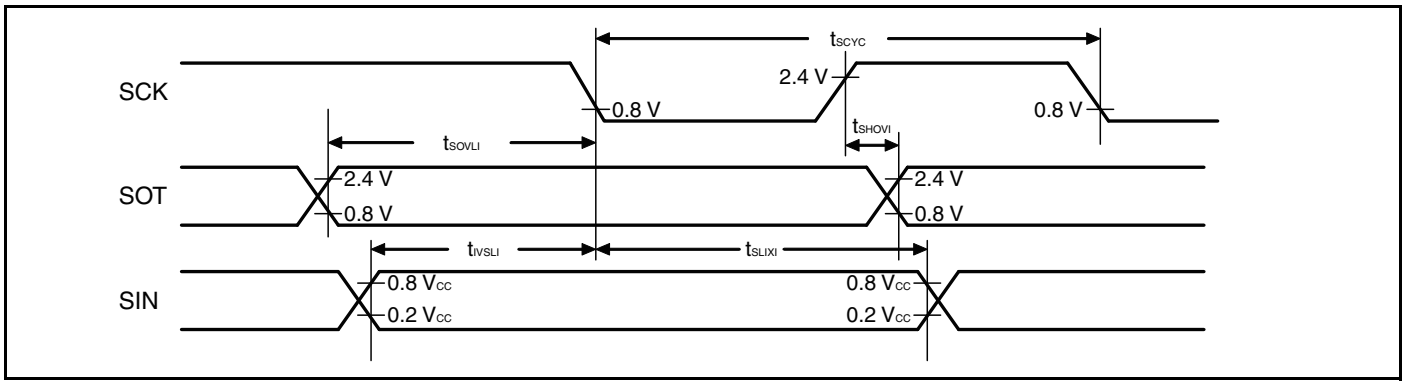
(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK ↑→ SOT delay time	t_{SHOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK ↓	t_{IVSLI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↓→ valid SIN hold time	t_{SLIXI}	SCK, SIN		0	—	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCK, SOT		—	4 t_{MCLK}*3	ns

*1: There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

*2: The serial clock delay function is a function that delays the output signal of the serial clock for half clock.

*3: See “18.4.2. Source Clock/Machine Clock” for t_{MCLK}.



*Sampling is executed at the falling edge of the sampling clock*1, and serial clock delay is enabled*2.*
(ESCR register : SCES bit = 1, ECCR register : SCDE bit = 1)

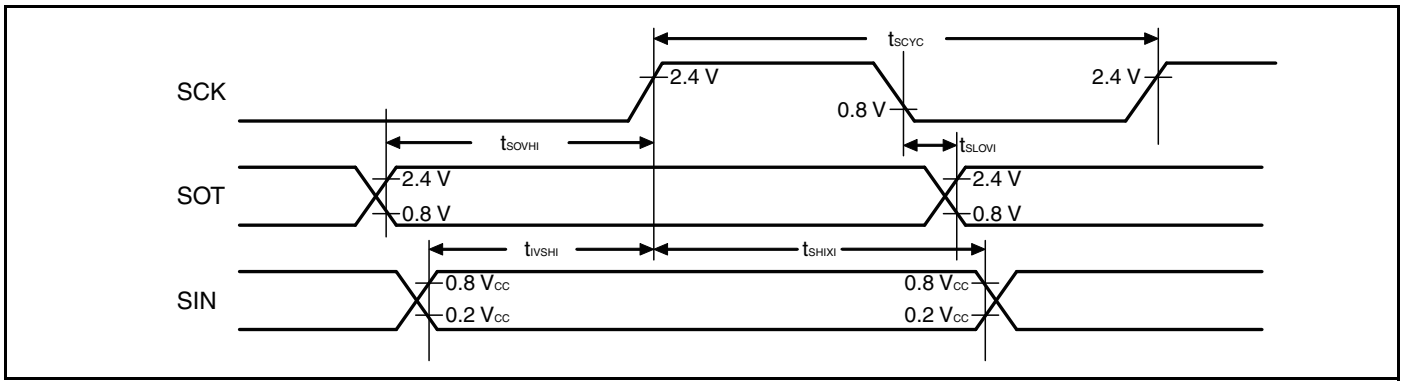
(V_{CC} = 5.0 V±10%, V_{SS} = 0.0 V, T_A = -40°C to +85°C)

Parameter	Symbol	Pin name	Condition	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCK	Internal clock operation output pin: C_L = 80 pF+1 TTL	5 t_{MCLK}*3	—	ns
SCK ↓→ SOT delay time	t_{SLOVI}	SCK, SOT		-95	+95	ns
Valid SIN → SCK ↑	t_{IVSHI}	SCK, SIN		t_{MCLK}*3+190	—	ns
SCK ↑→ valid SIN hold time	t_{SHIXI}	SCK, SIN		0	—	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCK, SOT		—	4 t_{MCLK}*3	ns

*1: There is a function used to choose whether the sampling of reception data is performed at a rising edge or a falling edge of the serial clock.

*2: The serial clock delay function is a function that delays the output signal of the serial clock for half clock.

*3: See “18.4.2.Source Clock/Machine Clock” for t_{MCLK}.



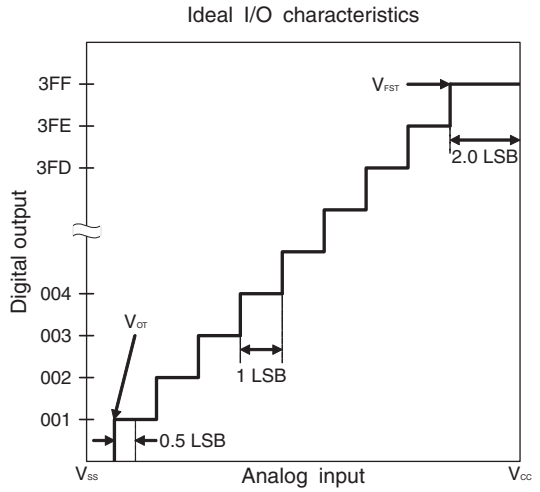
18.4.7 Low-voltage Detection

(V_{SS} = 0.0 V, T_A = -40°C to +85°C)

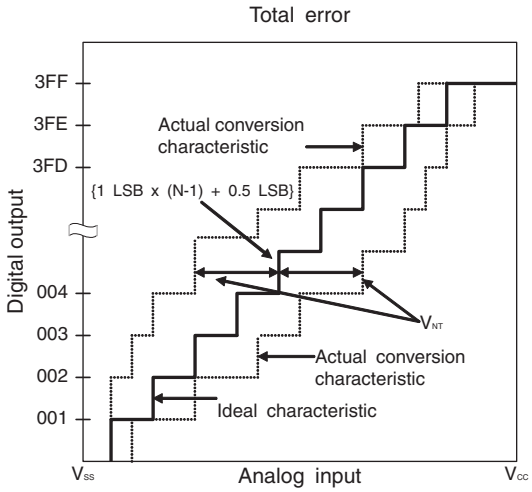
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Release voltage	V_{DL+}	2.52	2.7	2.88	V	At power supply rise
Detection voltage	V_{DL-}	2.42	2.6	2.78	V	At power supply fall
Hysteresis width	V_{HYS}	70	100	—	mV	
Power supply start voltage	V_{off}	—	—	2.3	V	
Power supply end voltage	V_{on}	4.9	—	—	V	
Power supply voltage change time (at power supply rise)	t_r	1	—	—	µs	Slope of power supply that the reset release signal generates
		—	3000	—	µs	Slope of power supply that the reset release signal generates within the rating (V_{DL+})
Power supply voltage change time (at power supply fall)	t_f	300	—	—	µs	Slope of power supply that the reset detection signal generates
		—	300	—	µs	Slope of power supply that the reset detection signal generates within the rating (V_{DL-})
Reset release delay time	t_{d1}	—	—	300	µs	
Reset detection delay time	t_{d2}	—	—	20	µs	

18.5.3 Definitions of A/D Converter Terms

- Resolution
  It indicates the level of analog variation that can be distinguished by the A/D converter.
  When the number of bits is 10, analog voltage can be divided into 2^{10} = 1024.
- Linearity error (unit: LSB)
  It indicates how much an actual conversion value deviates from the straight line connecting the zero transition point ("00 0000 0000" ← → "00 0000 0001") of a device to the full-scale transition point ("11 1111 1111" ← → "11 1111 1110") of the same device.
- Differential linear error (unit: LSB)
  It indicates how much the input voltage required to change the output code by 1 LSB deviates from an ideal value.
- Total error (unit: LSB)
  It indicates the difference between an actual value and a theoretical value. The error can be caused by a zero transition error, a full-scale transition errors, a linearity error, a quantum error, or noise.



$$1\ LSB = \frac{V_{CC} - V_{SS}}{1024}\ (V)$$



$$\text{Total error of digital output N} = \frac{V_{NT} - \{1\ LSB \times (N - 1) + 0.5\ LSB\}}{1\ LSB}\ [LSB]$$

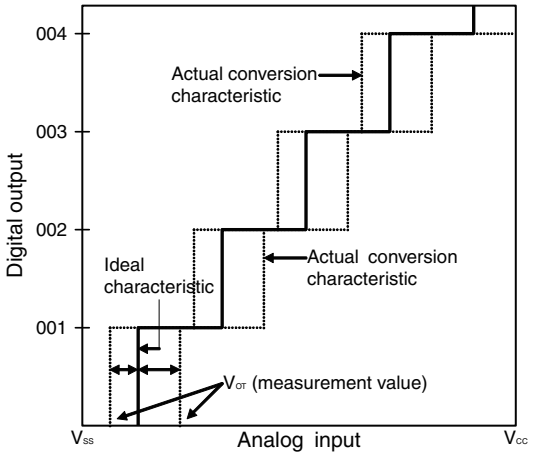
N : A/D converter digital output value

V_{NT}: Voltage at which the digital output transits from (N - 1) to N

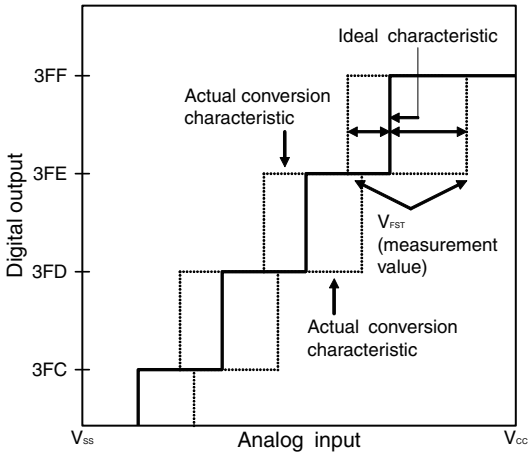
(Continued)

(Continued)

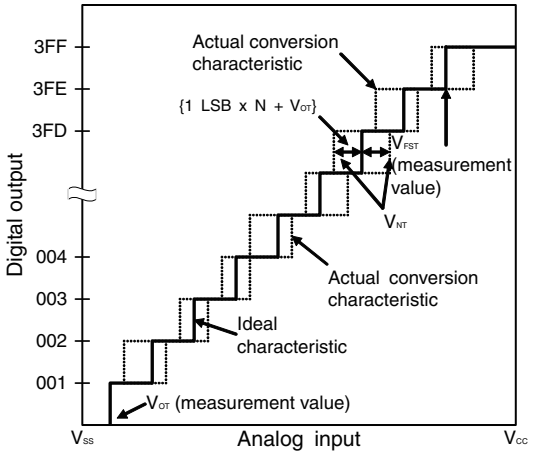
Zero transition error



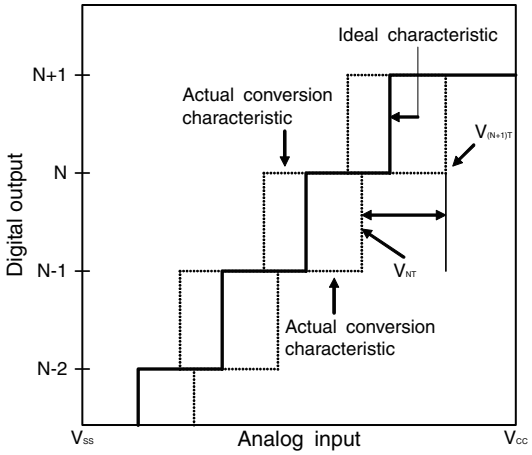
Full-scale transition error



Linearity error



Differential linearity error



$$\text{Linearity error of digital output N} = \frac{V_{NT} - \{1\ \text{LSB} \times N + V_{OT}\}}{1\ \text{LSB}}$$

$$\text{Differential linear error of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1\ \text{LSB}} - 1$$

N : A/D converter digital output value

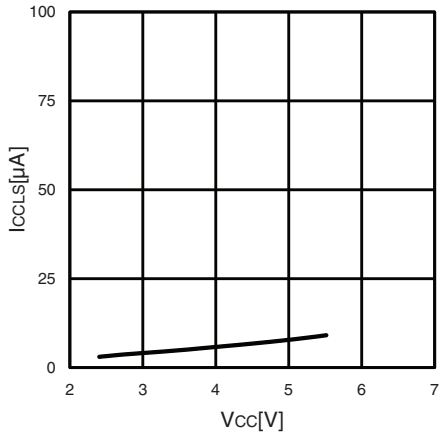
V_{NT}: Voltage at which the digital output transits from (N - 1) to N

V_{OT} (ideal value) = V_{SS} + 0.5 LSB [V]

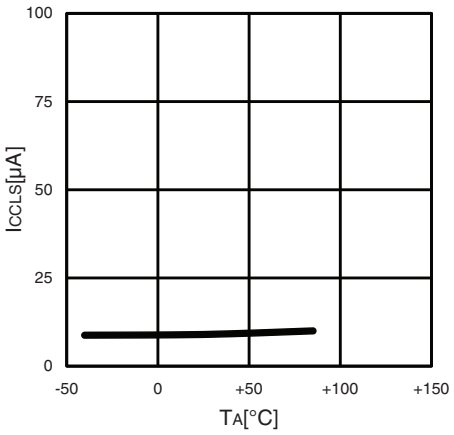
V_{FST} (ideal value) = V_{CC} - 2.0 LSB [V]

(Continued)

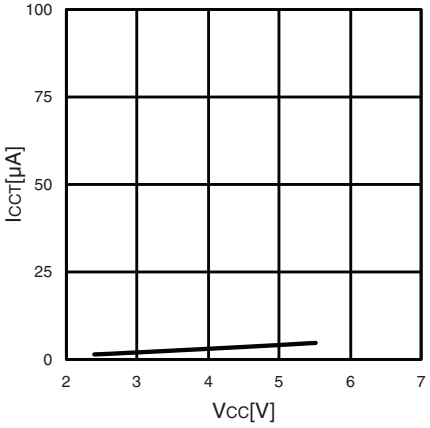
ICCLS - VCC
TA=+25°C, FMPL=16 kHz (divided by 2)
Subsleep mode with the external clock operating



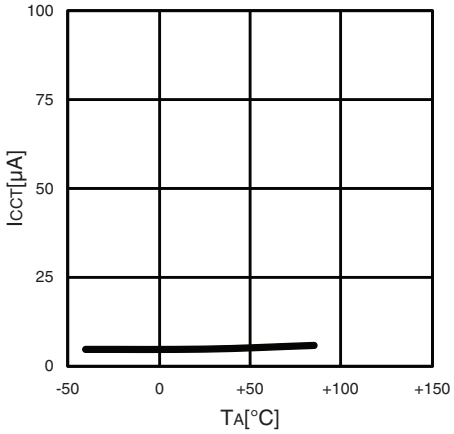
ICCLS - TA
VCC=5.5 V, FMPL=16 kHz (divided by 2)
Subsleep mode with the external clock operating



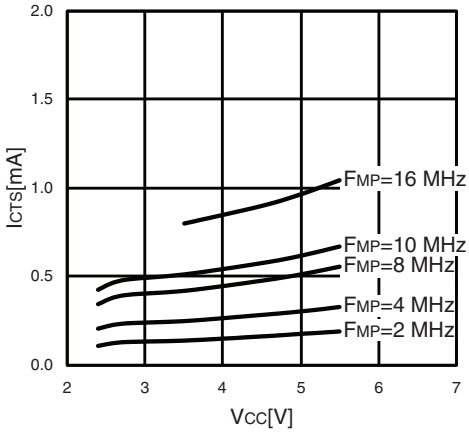
ICCT - VCC
TA=+25°C, FMPL=16 kHz (divided by 2)
Clock mode with the external clock operating



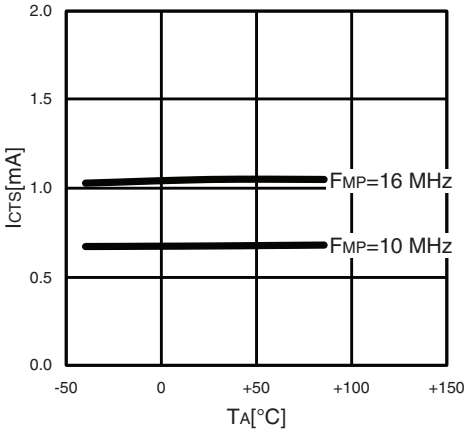
ICCT - TA
V=5.5 V, FMPL=16 kHz (divided by 2)
Clock mode with the external clock operating



ICTS - VCC
TA=+25°C, FMP=2, 4, 8, 10, 16 MHz (divided by 2)
Timebase timer mode with the external clock operating



ICTS - TA
V=5.5 V, FMP=10, 16 MHz (divided by 2)
Timebase timer mode with the external clock operating



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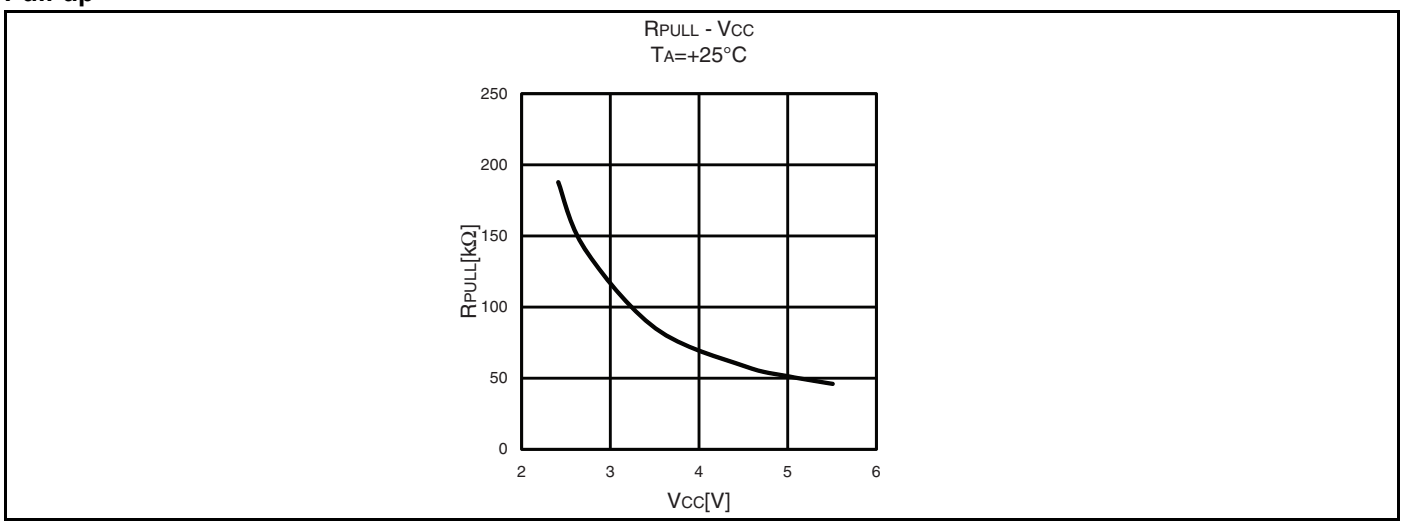
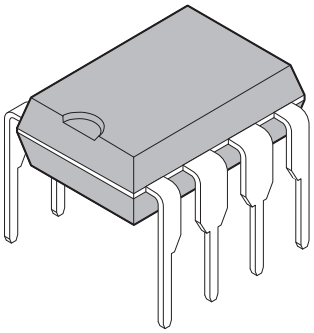
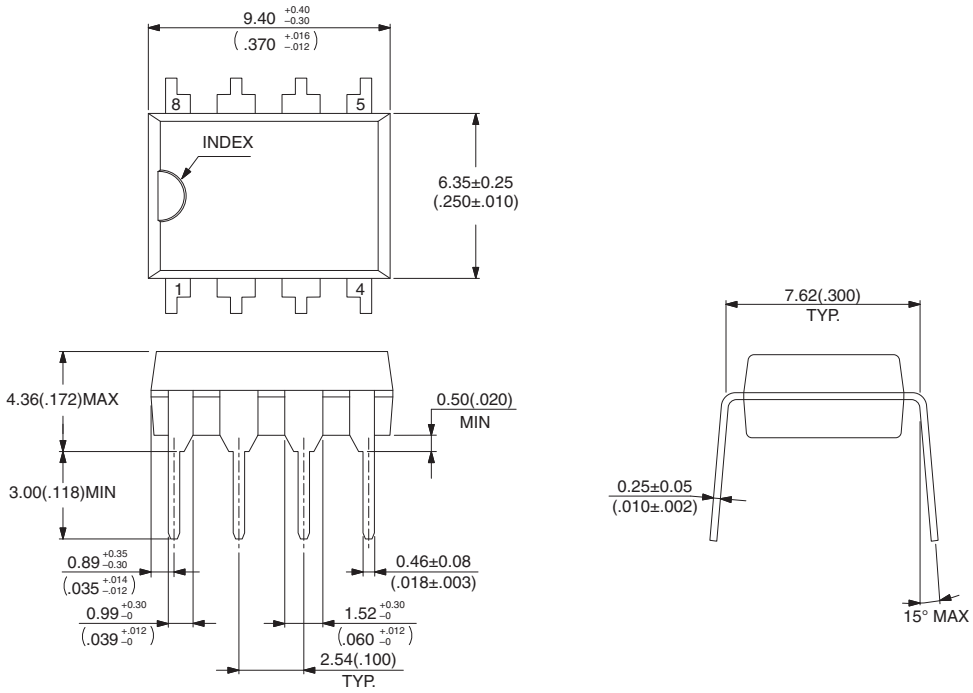
Pull-up



8-pin plastic DIP	Lead pitch	2.54 mm
	Sealing method	Plastic mold
(DIP-8P-M03)		

8-pin plastic DIP
(DIP-8P-M03)



Dimensions in mm (inches).
Note: The values in parentheses are reference values

(Continued)

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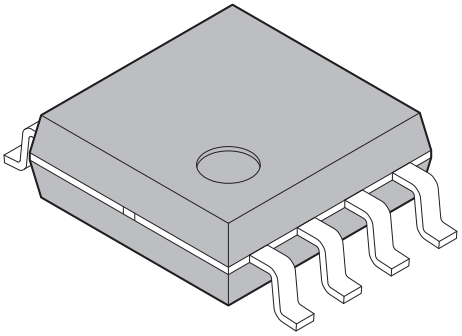
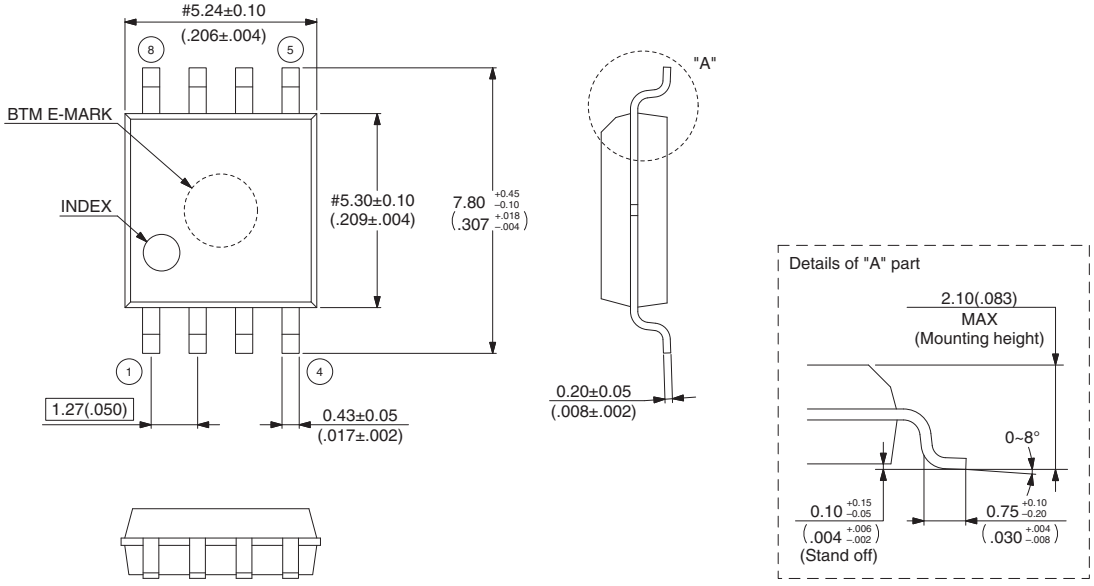
8-pin plastic SOP		
	Lead pitch	1.27 mm
	Package width × package length	5.30 mm × 5.24 mm
	Lead shape	Gullwing
	Lead bend direction	Normal bend
	Sealing method	Plastic mold
	Mounting height	2.10 mm Max
(FPT-8P-M08)		

8-pin plastic SOP
(FPT-8P-M08)

Note 1) Pins width and pins thickness include plating thickness.
Note 2) Pins width do not include tie bar cutting remainder.
Note 3) # : These dimensions do not include resin protrusion.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.

23. Major Changes

Spansion Publication Number: DS07-12623-5E

Page	Section	Change results
30	Electrical Characteristics 1. Absolute Maximum Ratings	Changed the characteristics of Input voltage.
33	3. DC Characteristics	Corrected the maximum value of “H” level input voltage for PF2 pin. $V_{CC} + 0.3 \rightarrow 10.5$
		Corrected the maximum value of Open-drain output application voltage. 0.2Vcc → Vss + 5.5
36		Added the footnote *5.
39	4. AC Characteristics (1) Clock Timing	Added a figure of HCLK1/HCLK2.
42	(2) Source Clock/Machine Clock	Corrected the graph of Operating voltage - Operating frequency (with the on-chip debug function). (Corrected the pitch)
43	(3) External Reset	Added “and power on” to the remarks column.
58	6. Flash Memory Program/Erase Characteristics	Added the row of “Current drawn on PF2”.
		Corrected the minimum value of Power supply voltage at erase/program. 4.5 → 3.0

Note: Please see “Document History” about later revised information.

Document History

Document Title: MB95200H/210H Series F^{2}MC-8FX 8-bit Microcontroller **Document Number: 002-07463**				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	–	AKIH	07/16/2010	Migrated to Cypress and assigned document number 002-07463. No change to document contents or format.
*A	5177811	AKIH	03/18/2016	Updated to Cypress format.