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Applications of "[Embedded - Microcontrollers](#)"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	33
Program Memory Size	3.5KB (2K x 14)
Program Memory Type	FLASH
EEPROM Size	64 x 8
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf871-i-pt

PIC16F870/871

NOTES:

PIC16F870/871

3.5 Reading the FLASH Program Memory

Reading FLASH program memory is much like that of EEPROM data memory, only two NOP instructions must be inserted after the RD bit is set. These two instruction cycles that the NOP instructions execute, will be used by the microcontroller to read the data out of program memory and insert the value into the EEDATH:EEDATA registers. Data will be available following the second NOP instruction. EEDATH and EEDATA will hold their value until another read operation is initiated, or until they are written by firmware.

The steps to reading the FLASH program memory are:

1. Write the address to EEADRH:EEADR. Make sure that the address is not larger than the memory size of the PIC16F870/871 devices.
2. Set the EEPGD bit to point to FLASH program memory.
3. Set the RD bit to start the read operation.
4. Execute two NOP instructions to allow the microcontroller to read out of program memory.
5. Read the data from the EEDATH:EEDATA registers.

EXAMPLE 3-3: FLASH PROGRAM READ

```
BSF    STATUS, RP1    ;
BCF    STATUS, RP0    ;Bank 2
MOVF   ADDRHL, W      ;Write the
MOVWF  EEADR          ;address bytes
MOVF   ADDRHL, W      ;for the desired
MOVWF  EEADRH         ;address to read
BSF    STATUS, RP0    ;Bank 3
BSF    EECON1, EEPGD ;Point to Program memory
BSF    EECON1, RD     ;Start read operation
NOP    ;Required two NOPs
NOP    ;
BCF    STATUS, RP0    ;Bank 2
MOVF   EEDATA, W     ;DATAH = EEDATA
MOVWF  DATAH        ;
MOVF   EEDATH, W     ;DATAH = EEDATH
MOVWF  DATAH        ;
```

3.6 Writing to the FLASH Program Memory

Writing to FLASH program memory is unique, in that the microcontroller does not execute instructions while programming is taking place. The oscillator continues to run and all peripherals continue to operate and queue interrupts, if enabled. Once the write operation completes (specification D133), the processor begins executing code from where it left off. The other important difference when writing to FLASH program memory is that the WRT configuration bit, when clear, prevents any writes to program memory (see Table 3-1).

Just like EEPROM data memory, there are many steps in writing to the FLASH program memory. Both address and data values must be written to the SFRs. The EEPGD bit must be set, and the WREN bit must be set to enable writes. The WREN bit should be kept clear at all times, except when writing to the FLASH program memory. The WR bit can only be set if the WREN bit was set in a previous operation (i.e., they both cannot be set in the same operation). The WREN bit should then be cleared by firmware after the write. Clearing the WREN bit before the write actually completes will not terminate the write in progress.

Writes to program memory must also be prefaced with a special sequence of instructions that prevent inadvertent write operations. This is a sequence of five instructions that must be executed without interruption for each byte written. These instructions must then be followed by two NOP instructions to allow the microcontroller to setup for the write operation. Once the write is complete, the execution of instructions starts with the instruction after the second NOP.

The steps to write to program memory are:

1. Write the address to EEADRH:EEADR. Make sure that the address is not larger than the memory size of the PIC16F870/871 devices.
2. Write the 14-bit data value to be programmed in the EEDATH:EEDATA registers.
3. Set the EEPGD bit to point to FLASH program memory.
4. Set the WREN bit to enable program operations.
5. Disable interrupts (if enabled).
6. Execute the special five instruction sequence:
 - Write 55h to EECON2 in two steps (first to W, then to EECON2)
 - Write AAh to EECON2 in two steps (first to W, then to EECON2)
 - Set the WR bit
7. Execute two NOP instructions to allow the microcontroller to setup for write operation.
8. Enable interrupts (if using interrupts).
9. Clear the WREN bit to disable program operations.

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TABLE 4-3: PORTB FUNCTIONS

Name	Bit#	Buffer	Function
RB0/INT	bit0	TTL/ST ⁽¹⁾	Input/output pin or external interrupt input. Internal software programmable weak pull-up.
RB1	bit1	TTL	Input/output pin. Internal software programmable weak pull-up.
RB2	bit2	TTL	Input/output pin. Internal software programmable weak pull-up.
RB3/PGM	bit3	TTL/ST ⁽¹⁾	Input/output pin or programming pin in LVP mode. Internal software programmable weak pull-up.
RB4	bit4	TTL	Input/output pin (with interrupt-on-change). Internal software programmable weak pull-up.
RB5	bit5	TTL	Input/output pin (with interrupt-on-change). Internal software programmable weak pull-up.
RB6/PGC	bit6	TTL/ST ⁽²⁾	Input/output pin (with interrupt-on-change) or In-Circuit Debugger pin. Internal software programmable weak pull-up. Serial programming clock.
RB7/PGD	bit7	TTL/ST ⁽²⁾	Input/output pin (with interrupt-on-change) or In-Circuit Debugger pin. Internal software programmable weak pull-up. Serial programming data.

Legend: TTL = TTL input, ST = Schmitt Trigger input

Note 1: This buffer is a Schmitt Trigger input when configured as the external interrupt or LVP mode.

2: This buffer is a Schmitt Trigger input when used in Serial Programming mode.

TABLE 4-4: SUMMARY OF REGISTERS ASSOCIATED WITH PORTB

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
06h, 106h	PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	uuuu uuuu
86h, 186h	TRISB	PORTB Data Direction Register								1111 1111	1111 1111
81h, 181h	OPTION_REG	RBPUP	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged. Shaded cells are not used by PORTB.

6.4 Timer1 Operation in Asynchronous Counter Mode

If control bit $\overline{T1SYNC}$ (T1CON<2>) is set, the external clock input is not synchronized. The timer continues to increment asynchronous to the internal phase clocks. The timer will continue to run during SLEEP and can generate an interrupt-on-overflow, which will wake-up the processor. However, special precautions in software are needed to read/write the timer (Section 6.4.1).

In Asynchronous Counter mode, Timer1 cannot be used as a time base for capture or compare operations.

6.4.1 READING AND WRITING TIMER1 IN ASYNCHRONOUS COUNTER MODE

Reading TMR1H or TMR1L while the timer is running from an external asynchronous clock, will ensure a valid read (taken care of in hardware). However, the user should keep in mind that reading the 16-bit timer in two 8-bit values itself, poses certain problems, since the timer may overflow between the reads.

For writes, it is recommended that the user simply stop the timer and write the desired values. A write contention may occur by writing to the timer registers, while the register is incrementing. This may produce an unpredictable value in the timer register.

Reading the 16-bit value requires some care. Examples 12-2 and 12-3 in the PIC[®] Mid-Range MCU Family Reference Manual (DS33023) show how to read and write Timer1 when it is running in Asynchronous mode.

6.5 Timer1 Oscillator

A crystal oscillator circuit is built-in between pins T1OSI (input) and T1OSO (amplifier output). It is enabled by setting control bit, T1OSCEN (T1CON<3>). The oscillator is a low power oscillator, rated up to 200 kHz. It will continue to run during SLEEP. It is primarily intended for use with a 32 kHz crystal. Table 6-1 shows the capacitor selection for the Timer1 oscillator.

The Timer1 oscillator is identical to the LP oscillator. The user must provide a software time delay to ensure proper oscillator start-up.

TABLE 6-1: CAPACITOR SELECTION FOR THE TIMER1 OSCILLATOR

Osc Type	Freq.	C1	C2
LP	32 kHz	33 pF	33 pF
	100 kHz	15 pF	15 pF
	200 kHz	15 pF	15 pF
These values are for design guidance only.			
Crystals Tested:			
32.768 kHz	Epson C-001R32.768K-A	± 20 PPM	
100 kHz	Epson C-2 100.00 KC-P	± 20 PPM	
200 kHz	STD XTL 200.000 kHz	± 20 PPM	
Note 1: Higher capacitance increases the stability of oscillator, but also increases the start-up time. 2: Since each resonator/crystal has its own characteristics, the user should consult the resonator/crystal manufacturer for appropriate values of external components.			

6.6 Resetting Timer1 Using a CCP Trigger Output

If the CCP1 module is configured in Compare mode to generate a “special event trigger” (CCP1M3:CCP1M0 = 1011), this signal will reset Timer1.

Note: The special event triggers from the CCP1 module will not set interrupt flag bit TMR1IF (PIR1<0>).

Timer1 must be configured for either Timer or Synchronized Counter mode to take advantage of this feature. If Timer1 is running in Asynchronous Counter mode, this RESET operation may not work.

In the event that a write to Timer1 coincides with a special event trigger from CCP1, the write will take precedence.

In this mode of operation, the CCPRH:CCPRL register pair effectively becomes the period register for Timer1.

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7.1 Timer2 Prescaler and Postscaler

The prescaler and postscaler counters are cleared when any of the following occurs:

- a write to the TMR2 register
- a write to the T2CON register
- any device RESET (POR, MCLR Reset, WDT Reset, or BOR)

TMR2 is not cleared when T2CON is written.

7.2 Output of TMR2

The output of TMR2 (before the postscaler) is fed to the SSP module, which optionally uses it to generate shift clock.

TABLE 7-1: REGISTERS ASSOCIATED WITH TIMER2 AS A TIMER/COUNTER

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
0Bh,8Bh, 10Bh,18Bh	INTCON	GIE	PEIE	TOIE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000u
0Ch	PIR1	PSPIF ⁽¹⁾	ADIF	RCIF	TXIF	—	CCP1IF	TMR2IF	TMR1IF	0000 -000	0000 -000
8Ch	PIE1	PSPIE ⁽¹⁾	ADIE	RCIE	TXIE	—	CCP1IE	TMR2IE	TMR1IE	0000 -000	0000 -000
11h	TMR2	Timer2 Module's Register								0000 0000	0000 0000
12h	T2CON	—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	-000 0000
92h	PR2	Timer2 Period Register								1111 1111	1111 1111

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used by the Timer2 module.

Note 1: Bits PSPIE and PSPIF are reserved on the PIC16F870; always maintain these bits clear.

TABLE 9-4: BAUD RATES FOR ASYNCHRONOUS MODE (BRGH = 1)

BAUD RATE (K)	Fosc = 20 MHz			Fosc = 16 MHz			Fosc = 10 MHz		
	KBAUD	% ERROR	SPBRG value (decimal)	KBAUD	% ERROR	SPBRG value (decimal)	KBAUD	% ERROR	SPBRG value (decimal)
0.3	-	-	-	-	-	-	-	-	-
1.2	-	-	-	-	-	-	-	-	-
2.4	-	-	-	-	-	-	2.441	1.71	255
9.6	9.615	0.16	129	9.615	0.16	103	9.615	0.16	64
19.2	19.231	0.16	64	19.231	0.16	51	19.531	1.72	31
28.8	29.070	0.94	42	29.412	2.13	33	28.409	1.36	21
33.6	33.784	0.55	36	33.333	0.79	29	32.895	2.10	18
57.6	59.524	3.34	20	58.824	2.13	16	56.818	1.36	10
HIGH	4.883	-	255	3.906	-	255	2.441	-	255
LOW	1250.000	-	0	1000.000	-	0	625.000	-	0

BAUD RATE (K)	Fosc = 4 MHz			Fosc = 3.6864 MHz		
	KBAUD	% ERROR	SPBRG value (decimal)	KBAUD	% ERROR	SPBRG value (decimal)
0.3	-	-	-	-	-	-
1.2	1.202	0.17	207	1.2	0	191
2.4	2.404	0.17	103	2.4	0	95
9.6	9.615	0.16	25	9.6	0	23
19.2	19.231	0.16	12	19.2	0	11
28.8	27.798	3.55	8	28.8	0	7
33.6	35.714	6.29	6	32.9	2.04	6
57.6	62.500	8.51	3	57.6	0	3
HIGH	0.977	-	255	0.9	-	255
LOW	250.000	-	0	230.4	-	0

FIGURE 9-7: ASYNCHRONOUS RECEPTION WITH ADDRESS DETECT

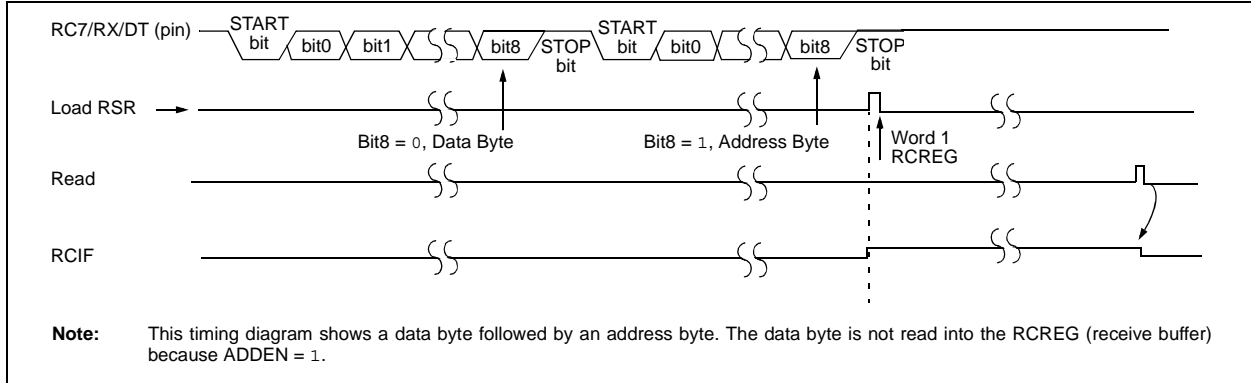


FIGURE 9-8: ASYNCHRONOUS RECEPTION WITH ADDRESS BYTE FIRST

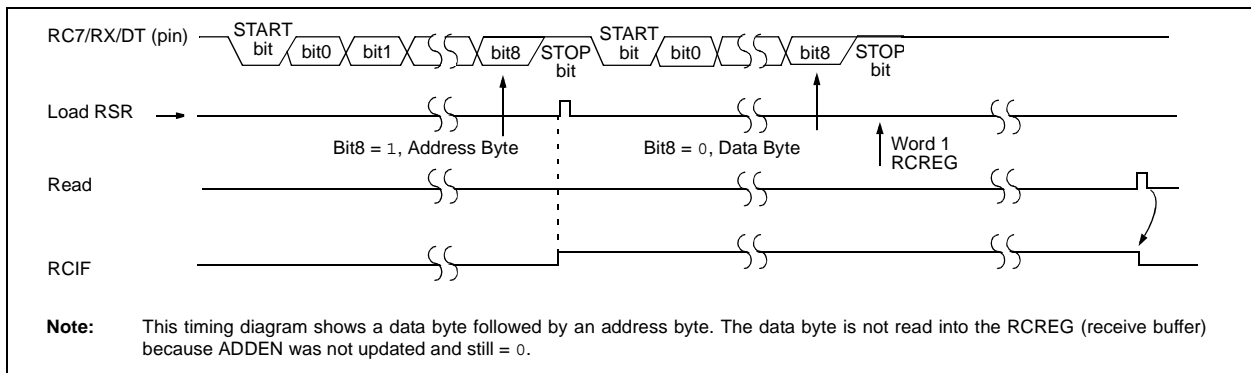


TABLE 9-7: REGISTERS ASSOCIATED WITH ASYNCHRONOUS RECEPTION

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
0Bh, 8Bh, 10Bh, 18Bh	INTCON	GIE	PEIE	TOIE	INTE	RBIE	TOIF	INTF	R0IF	0000 000x	0000 000u
0Ch	PIR1	PSPIF ⁽¹⁾	ADIF	RCIF	TXIF	—	CCP1IF	TMR2IF	TMR1IF	0000 -000	0000 -000
18h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
1Ah	RCREG	USART Receive Register								0000 0000	0000 0000
8Ch	PIE1	PSPIE ⁽¹⁾	ADIE	RCIE	TXIE	—	CCP1IE	TMR2IE	TMR1IE	0000 -000	0000 -000
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
99h	SPBRG	Baud Rate Generator Register								0000 0000	0000 0000

Legend: x = unknown, - = unimplemented locations read as '0'. Shaded cells are not used for asynchronous reception.

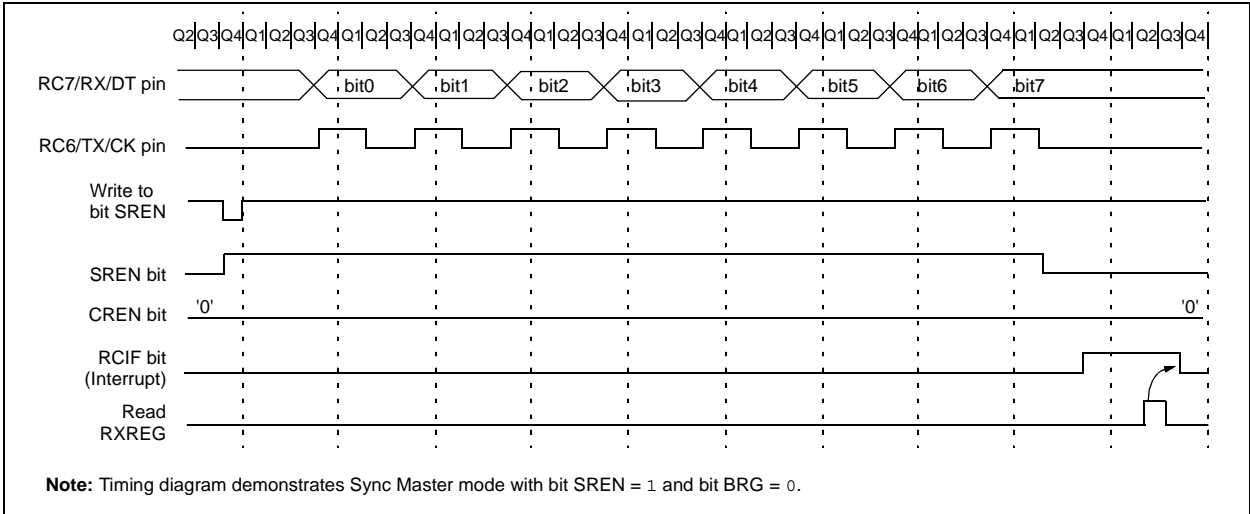
Note 1: Bits PSPIE and PSPIF are reserved on the PIC16F870; always maintain these bits clear.

TABLE 9-9: REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
0Bh, 8Bh, 10Bh, 18Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	R0IF	0000 000x	0000 000u
0Ch	PIR1	PSPIF ⁽¹⁾	ADIF	RCIF	TXIF	—	CCP1IF	TMR2IF	TMR1IF	0000 -000	0000 -000
18h	RCSTA	SPEN	RX9	SREN	CREN	—	FERR	OERR	RX9D	0000 -00x	0000 -00x
1Ah	RCREG	USART Receive Register								0000 0000	0000 0000
8Ch	PIE1	PSPIE ⁽¹⁾	ADIE	RCIE	TXIE	—	CCP1IE	TMR2IE	TMR1IE	0000 -000	0000 -000
98h	TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
99h	SPBRG	Baud Rate Generator Register								0000 0000	0000 0000

Legend: x = unknown, - = unimplemented, read as '0'. Shaded cells are not used for synchronous master reception.
Note 1: Bits PSPIE and PSPIF are reserved on the PIC16F870; always maintain these bits clear.

FIGURE 9-11: SYNCHRONOUS RECEPTION (MASTER MODE, SREN)



11.0 SPECIAL FEATURES OF THE CPU

The PIC16F870/871 devices have a host of features intended to maximize system reliability, minimize cost through elimination of external components, provide Power Saving Operating modes and offer code protection. These are:

- Oscillator Selection
- RESET
 - Power-on Reset (POR)
 - Power-up Timer (PWRT)
 - Oscillator Start-up Timer (OST)
 - Brown-out Reset (BOR)
- Interrupts
- Watchdog Timer (WDT)
- SLEEP
- Code Protection
- ID Locations
- In-Circuit Serial Programming
- Low Voltage In-Circuit Serial Programming
- In-Circuit Debugger

PIC16F870/871 devices have a Watchdog Timer, which can be shut-off only through configuration bits. It runs off its own RC oscillator for added reliability.

There are two timers that offer necessary delays on power-up. One is the Oscillator Start-up Timer (OST), intended to keep the chip in RESET until the crystal oscillator is stable. The other is the Power-up Timer (PWRT), which provides a fixed delay of 72 ms (nominal) on power-up only. It is designed to keep the part in RESET while the power supply stabilizes. With these two timers on-chip, most applications need no external RESET circuitry.

SLEEP mode is designed to offer a very low current Power-down mode. The user can wake-up from SLEEP through external RESET, Watchdog Timer Wake-up, or through an interrupt.

Several oscillator options are also made available to allow the part to fit the application. The RC oscillator option saves system cost while the LP crystal option saves power. A set of configuration bits is used to select various options.

Additional information on special features is available in the PIC[®] Mid-Range MCU Family Reference Manual (DS33023).

11.1 Configuration Bits

The configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1'), to select various device configurations. The erased, or unprogrammed value of the configuration word is 3FFFh. These bits are mapped in program memory location 2007h.

It is important to note that address 2007h is beyond the user program memory space, which can be accessed only during programming.

TABLE 11-4: STATUS BITS AND THEIR SIGNIFICANCE

POR	BOR	TO	PD	
0	x	1	1	Power-on Reset
0	x	0	x	Illegal, \overline{TO} is set on \overline{POR}
0	x	x	0	Illegal, \overline{PD} is set on \overline{POR}
1	0	1	1	Brown-out Reset
1	1	0	1	WDT Reset
1	1	0	0	WDT Wake-up
1	1	u	u	\overline{MCLR} Reset during normal operation
1	1	1	0	\overline{MCLR} Reset during SLEEP or interrupt wake-up from SLEEP

Legend: x = don't care, u = unchanged

TABLE 11-5: RESET CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	STATUS Register	PCON Register
Power-on Reset	000h	0001 1xxx	---- --0x
\overline{MCLR} Reset during normal operation	000h	000u uuuu	---- --uu
\overline{MCLR} Reset during SLEEP	000h	0001 0uuu	---- --uu
WDT Reset	000h	0000 1uuu	---- --uu
WDT Wake-up	PC + 1	uuu0 0uuu	---- --uu
Brown-out Reset	000h	0001 1uuu	---- --u0
Interrupt wake-up from SLEEP	PC + 1 ⁽¹⁾	uuu1 0uuu	---- --uu

Legend: u = unchanged, x = unknown, - = unimplemented bit, read as '0'

Note 1: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

TABLE 11-6: INITIALIZATION CONDITIONS FOR ALL REGISTERS

Register	Devices		Power-on Reset, Brown-out Reset	\overline{MCLR} Resets WDT Reset	Wake-up via WDT or Interrupt
W	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
INDF	PIC16F870	PIC16F871	N/A	N/A	N/A
TMR0	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
PCL	PIC16F870	PIC16F871	0000h	0000h	PC + 1 ⁽²⁾
STATUS	PIC16F870	PIC16F871	0001 1xxx	000q quuu ⁽³⁾	uuuq quuu ⁽³⁾
FSR	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTA	PIC16F870	PIC16F871	--0x 0000	--0u 0000	--uu uuuu
PORTB	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTC	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTD	PIC16F870	PIC16F871	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTE	PIC16F870	PIC16F871	---- -xxx	---- -uuu	---- -uuu
PCLATH	PIC16F870	PIC16F871	---0 0000	---0 0000	---u uuuu
INTCON	PIC16F870	PIC16F871	0000 000x	0000 000u	uuuu uuuu ⁽¹⁾

Legend: u = unchanged, x = unknown, - = unimplemented bit, read as '0', q = value depends on condition, r = reserved, maintain clear

Note 1: One or more bits in INTCON, PIR1 and/or PIR2 will be affected (to cause wake-up).

2: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

3: See Table 11-5 for RESET value for specific condition.

12.0 INSTRUCTION SET SUMMARY

Each PIC16F870/871 instruction is a 14-bit word, divided into an OPCODE, which specifies the instruction type, and one or more operands, which further specify the operation of the instruction. The PIC16F870/871 instruction set summary in Table 12-2 lists **byte-oriented**, **bit-oriented**, and **literal and control** operations. Table 12-1 shows the opcode field descriptions.

For **byte-oriented** instructions, 'f' represents a file register designator and 'd' represents a destination designator. The file register designator specifies which file register is to be used by the instruction.

The destination designator specifies where the result of the operation is to be placed. If 'd' is zero, the result is placed in the W register. If 'd' is one, the result is placed in the file register specified in the instruction.

For **bit-oriented** instructions, 'b' represents a bit field designator which selects the number of the bit affected by the operation, while 'f' represents the address of the file in which the bit is located.

For **literal and control** operations, 'k' represents an eight or eleven bit constant or literal value.

TABLE 12-1: OPCODE FIELD DESCRIPTIONS

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f. Default is d = 1.
PC	Program Counter
TO	Time-out bit
PD	Power-down bit

The instruction set is highly orthogonal and is grouped into three basic categories:

- **Byte-oriented** operations
- **Bit-oriented** operations
- **Literal and control** operations

All instructions are executed within one single instruction cycle, unless a conditional test is true, or the program counter is changed as a result of an instruction. In this case, the execution takes two instruction cycles, with the second cycle executed as a NOP. One instruction cycle consists of four oscillator periods. Thus, for an oscillator frequency of 4 MHz, the normal instruction execution time is 1 μ s. If a conditional test is true, or the program counter is changed as a result of an instruction, the instruction execution time is 2 μ s.

Table 12-2 lists the instructions recognized by the MPASM™ assembler.

Figure 12-1 shows the general formats that the instructions can have.

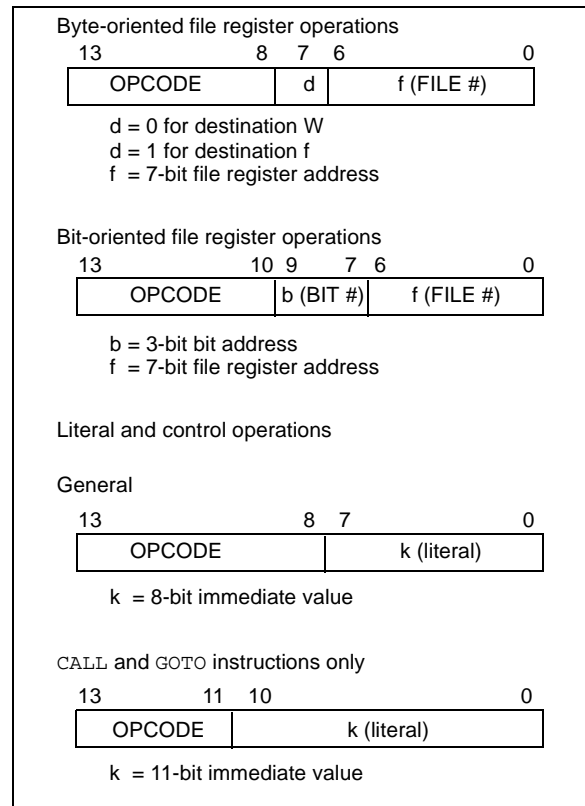
Note: To maintain upward compatibility with future PIC16F870/871 products, do not use the OPTION and TRIS instructions.

All examples use the following format to represent a hexadecimal number:

0xhh

where h signifies a hexadecimal digit.

FIGURE 12-1: GENERAL FORMAT FOR INSTRUCTIONS



A description of each instruction is available in the PIC® Mid-Range MCU Family Reference Manual (DS33023).

13.9 MPLAB ICE 2000 High Performance Universal In-Circuit Emulator

The MPLAB ICE 2000 universal in-circuit emulator is intended to provide the product development engineer with a complete microcontroller design tool set for PIC microcontrollers. Software control of the MPLAB ICE 2000 in-circuit emulator is advanced by the MPLAB Integrated Development Environment, which allows editing, building, downloading and source debugging from a single environment.

The MPLAB ICE 2000 is a full-featured emulator system with enhanced trace, trigger and data monitoring features. Interchangeable processor modules allow the system to be easily reconfigured for emulation of different processors. The universal architecture of the MPLAB ICE in-circuit emulator allows expansion to support new PIC microcontrollers.

The MPLAB ICE 2000 in-circuit emulator system has been designed as a real-time emulation system with advanced features that are typically found on more expensive development tools. The PC platform and Microsoft® Windows 32-bit operating system were chosen to best make these features available in a simple, unified application.

13.10 MPLAB ICE 4000 High Performance Universal In-Circuit Emulator

The MPLAB ICE 4000 universal in-circuit emulator is intended to provide the product development engineer with a complete microcontroller design tool set for high-end PIC microcontrollers. Software control of the MPLAB ICE in-circuit emulator is provided by the MPLAB Integrated Development Environment, which allows editing, building, downloading and source debugging from a single environment.

The MPLAB ICE 4000 is a premium emulator system, providing the features of MPLAB ICE 2000, but with increased emulation memory and high speed performance for dsPIC30F and PIC18XXX devices. Its advanced emulator features include complex triggering and timing, up to 2 Mb of emulation memory, and the ability to view variables in real-time.

The MPLAB ICE 4000 in-circuit emulator system has been designed as a real-time emulation system with advanced features that are typically found on more expensive development tools. The PC platform and Microsoft Windows 32-bit operating system were chosen to best make these features available in a simple, unified application.

13.11 MPLAB ICD 2 In-Circuit Debugger

Microchip's In-Circuit Debugger, MPLAB ICD 2, is a powerful, low cost, run-time development tool, connecting to the host PC via an RS-232 or high speed USB interface. This tool is based on the FLASH PIC MCUs and can be used to develop for these and other PIC microcontrollers. The MPLAB ICD 2 utilizes the in-circuit debugging capability built into the FLASH devices. This feature, along with Microchip's In-Circuit Serial Programming™ (ICSP™) protocol, offers cost effective in-circuit FLASH debugging from the graphical user interface of the MPLAB Integrated Development Environment. This enables a designer to develop and debug source code by setting breakpoints, single-stepping and watching variables, CPU status and peripheral registers. Running at full speed enables testing hardware and applications in real-time. MPLAB ICD 2 also serves as a development programmer for selected PIC devices.

13.12 PRO MATE II Universal Device Programmer

The PRO MATE II is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features an LCD display for instructions and error messages and a modular detachable socket assembly to support various package types. In Stand-Alone mode, the PRO MATE II device programmer can read, verify, and program PIC devices without a PC connection. It can also set code protection in this mode.

13.13 PICSTART Plus Development Programmer

The PICSTART Plus development programmer is an easy-to-use, low cost, prototype programmer. It connects to the PC via a COM (RS-232) port. MPLAB Integrated Development Environment software makes using the programmer simple and efficient. The PICSTART Plus development programmer supports most PIC devices up to 40 pins. Larger pin count devices, such as the PIC16C92X and PIC17C76X, may be supported with an adapter socket. The PICSTART Plus development programmer is CE compliant.

14.1 DC Characteristics: PIC16F870/871 (Industrial, Extended) PIC16LF870/871 (Commercial, Industrial)

PIC16LF870/871 (Commercial, Industrial)		Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ for Commercial					
PIC16F870/871 (Industrial, Extended)		Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
D001	VDD	Supply Voltage					
		PIC16LF870/871	2.0	—	5.5	V	All configurations. See Figure 14-2 for details.
D001 D001A		PIC16F870/871	4.0	—	5.5	V	All configurations. BOR enabled, $F_{\text{MAX}} = 14 \text{ MHz}$ (Note 7), -40°C to $+85^{\circ}\text{C}$
			V _{BOR} *	—	5.5	V	
D002*	VDR	RAM Data Retention Voltage⁽¹⁾	—	1.5	—	V	
D003	VPOR	VDD Start Voltage to ensure internal Power-on Reset signal	—	V _{SS}	—	V	See section on Power-on Reset for details
D004*	SVDD	VDD Rise Rate to ensure internal Power-on Reset signal	0.05	—	—	V/ms	See section on Power-on Reset for details
D005	V _{BOR}	Brown-out Reset Voltage	3.7	4.0	4.35	V	BOREN bit in configuration word enabled

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: This is the limit to which VDD can be lowered without losing RAM data.

2: The supply current is mainly a function of the operating voltage and frequency. Other factors such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature also have an impact on the current consumption.

The test conditions for all I_{DD} measurements in active Operation mode are:

$\text{OSC1} = \text{external square wave, from rail to rail; all I/O pins tri-stated, pulled to VDD}$

$\text{MCLR} = \text{VDD; WDT enabled/disabled as specified.}$

3: The power-down current in SLEEP mode does not depend on the oscillator type. Power-down current is measured with the part in SLEEP mode, with all I/O pins in hi-impedance state and tied to VDD and VSS.

4: For RC osc configuration, current through R_{EXT} is not included. The current through the resistor can be estimated by the formula $I_r = V_{\text{DD}}/2R_{\text{EXT}}$ (mA) with R_{EXT} in kΩ.

5: Timer1 oscillator (when enabled) adds approximately 20 μA to the specification. This value is from characterization and is for design guidance only. This is not tested.

6: The Δ current is the additional current consumed when this peripheral is enabled. This current should be added to the base I_{DD} or I_{PD} measurement.

7: When BOR is enabled, the device will operate correctly until the V_{BOR} voltage trip point is reached.

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14.2 DC Characteristics: PIC16F870/871 (Industrial) (Continued)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial Operating voltage V_{DD} range as described in DC spec Section 14.1 and Section 14.2.				
Param No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
D080	VOL	Output Low Voltage I/O ports	—	—	0.6	V	$I_{OL} = 8.5 \text{ mA}$, $V_{DD} = 4.5\text{V}$, -40°C to $+85^{\circ}\text{C}$
D083		OSC2/CLKO (RC osc config)	—	—	0.6	V	$I_{OL} = 1.6 \text{ mA}$, $V_{DD} = 4.5\text{V}$, -40°C to $+85^{\circ}\text{C}$
D090	VOH	Output High Voltage I/O ports (Note 3)	$V_{DD} - 0.7$	—	—	V	$I_{OH} = -3.0 \text{ mA}$, $V_{DD} = 4.5\text{V}$, -40°C to $+85^{\circ}\text{C}$
D092		OSC2/CLKO (RC osc config)	$V_{DD} - 0.7$	—	—	V	$I_{OH} = -1.3 \text{ mA}$, $V_{DD} = 4.5\text{V}$, -40°C to $+85^{\circ}\text{C}$
D150*	VOD	Open Drain High Voltage	—	—	8.5	V	RA4 pin
Capacitive Loading Specs on Output Pins							
D100	Cosc2	OSC2 pin	—	—	15	pF	In XT, HS and LP modes when external clock is used to drive OSC1.
D101	Cio	All I/O pins and OSC2 (in RC mode)	—	—	50	pF	
D102	CB	SCL, SDA in I ² C mode	—	—	400	pF	
Data EEPROM Memory							
D120	ED	Endurance	100K	—	—	E/W	25°C at 5V
D121	VDRW	VDD for read/write	VMIN	—	5.5	V	Using EECON to read/write VMIN = min operating voltage
D122	TDEW	Erase/write cycle time	—	4	8	ms	
Program FLASH Memory							
D130	EP	Endurance	1000	—	—	E/W	25°C at 5V
D131	VPR	VDD for read	VMIN	—	5.5	V	VMIN = min operating voltage
D132a		VDD for erase/write	VMIN	—	5.5	V	Using EECON to read/write, VMIN = min operating voltage
D133	TPEW	Erase/Write cycle time	—	4	8	ms	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: In RC oscillator configuration, the OSC1/CLKI pin is a Schmitt Trigger input. It is not recommended that the PIC16F870/871 be driven with external clock in RC mode.

2: The leakage current on the $\overline{\text{MCLR}}$ pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

3: Negative current is defined as current sourced by the pin.

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NOTES:

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FIGURE 15-15: AVERAGE WDT PERIOD vs. VDD OVER TEMPERATURE (-40°C TO 125°C)

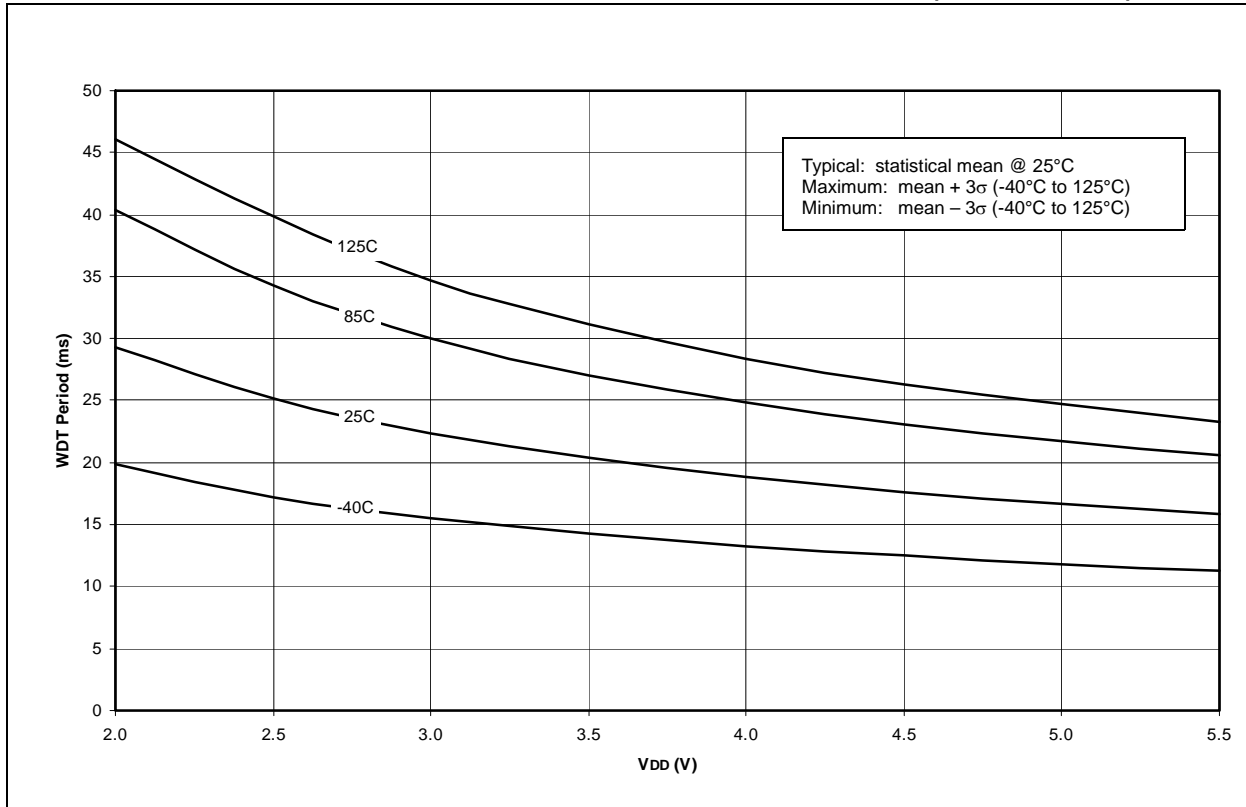


FIGURE 15-16: TYPICAL, MINIMUM AND MAXIMUM VOH vs. IOH (VDD = 5V, -40°C TO 125°C)

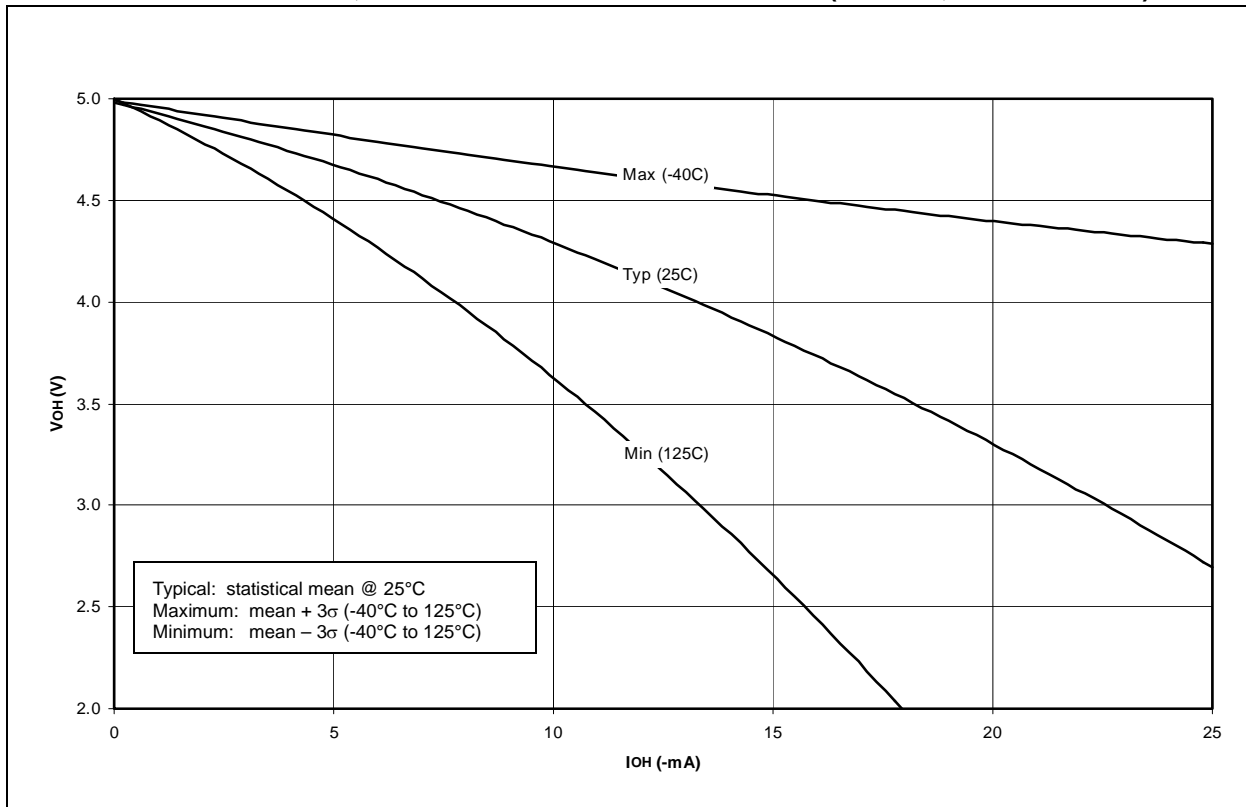


FIGURE 15-17: TYPICAL, MINIMUM AND MAXIMUM V_{OH} vs. I_{OH} ($V_{DD} = 3V$, $-40^{\circ}C$ TO $125^{\circ}C$)

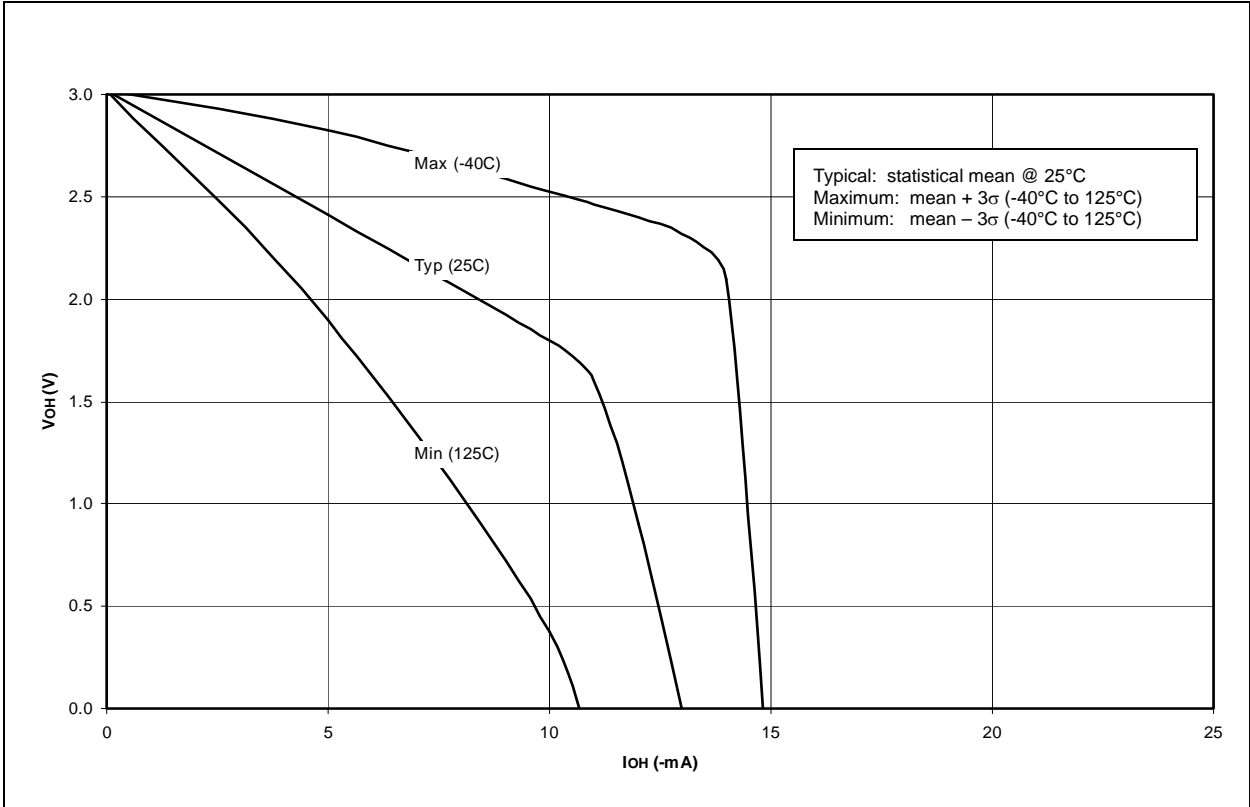
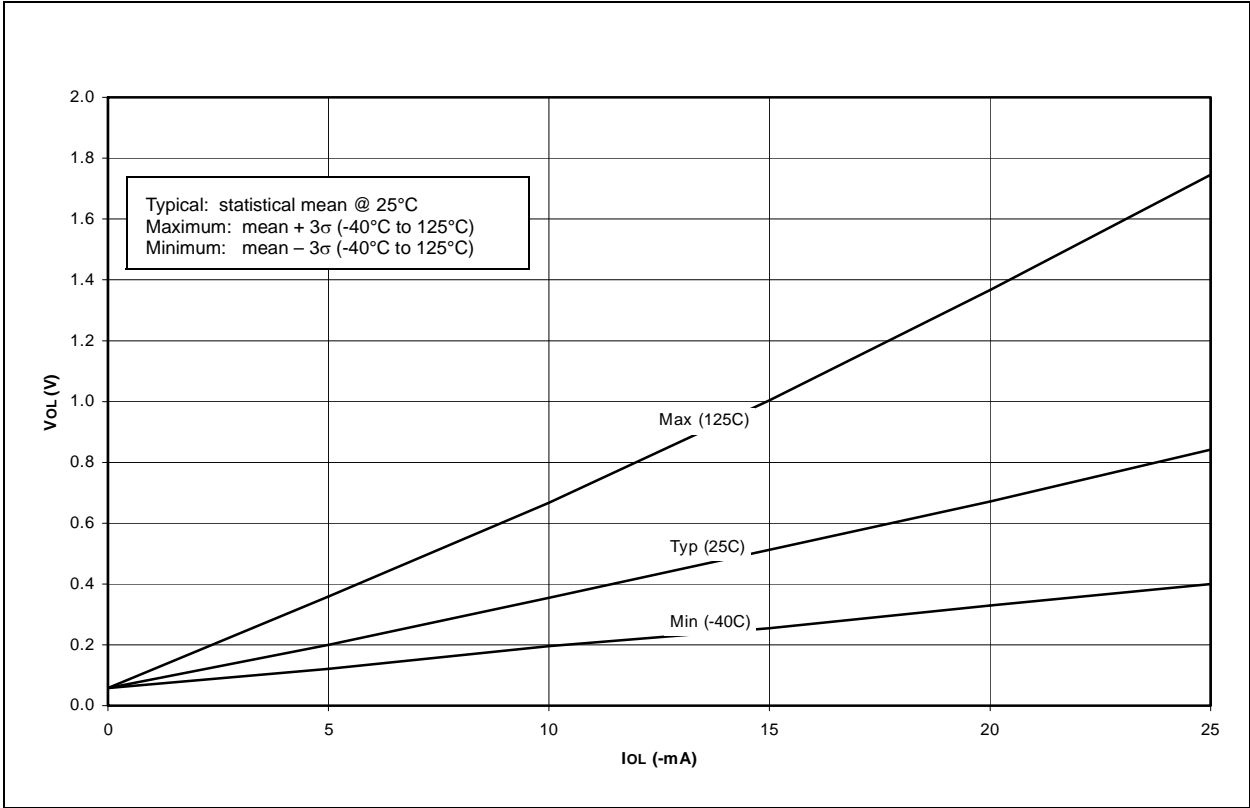


FIGURE 15-18: TYPICAL, MINIMUM AND MAXIMUM V_{OL} vs. I_{OL} ($V_{DD} = 5V$, $-40^{\circ}C$ TO $125^{\circ}C$)



PIC16F870/871

FIGURE 15-19: TYPICAL, MINIMUM AND MAXIMUM V_{OL} vs. I_{OL} ($V_{DD} = 3V$, $-40^{\circ}C$ TO $125^{\circ}C$)

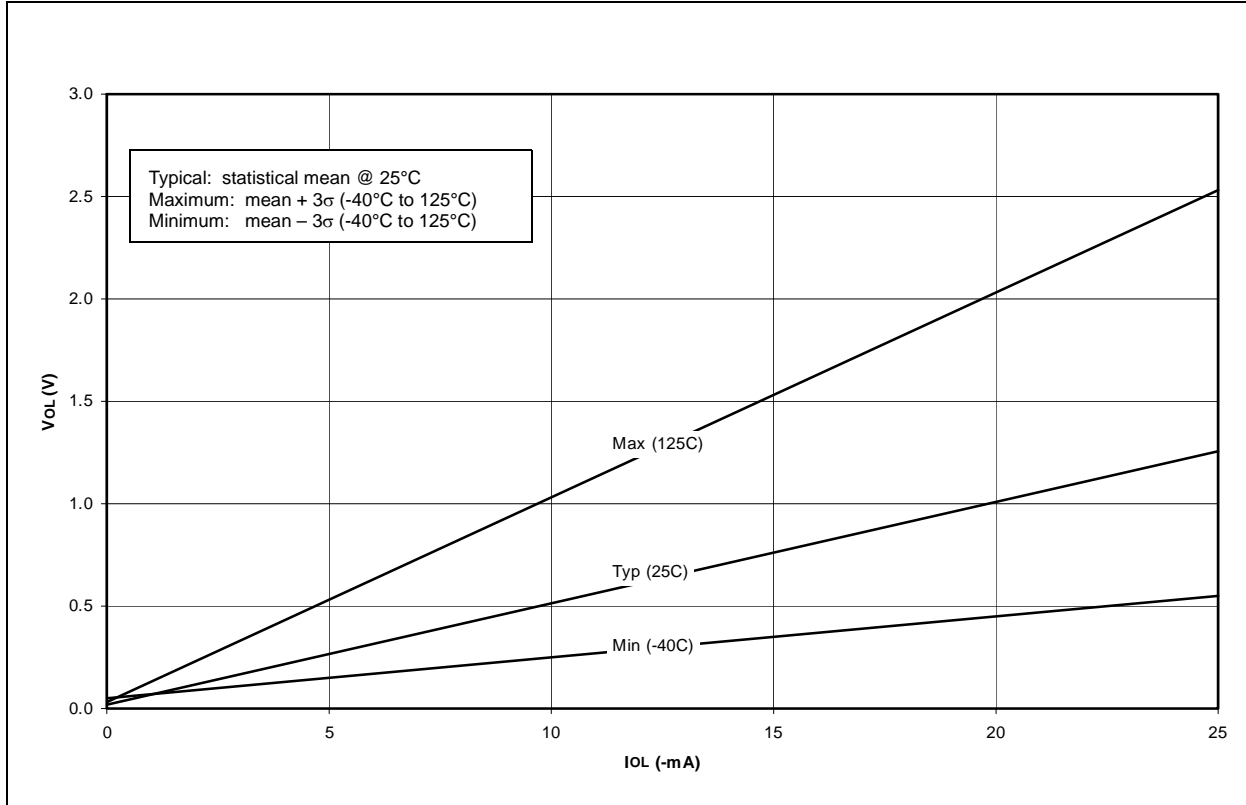
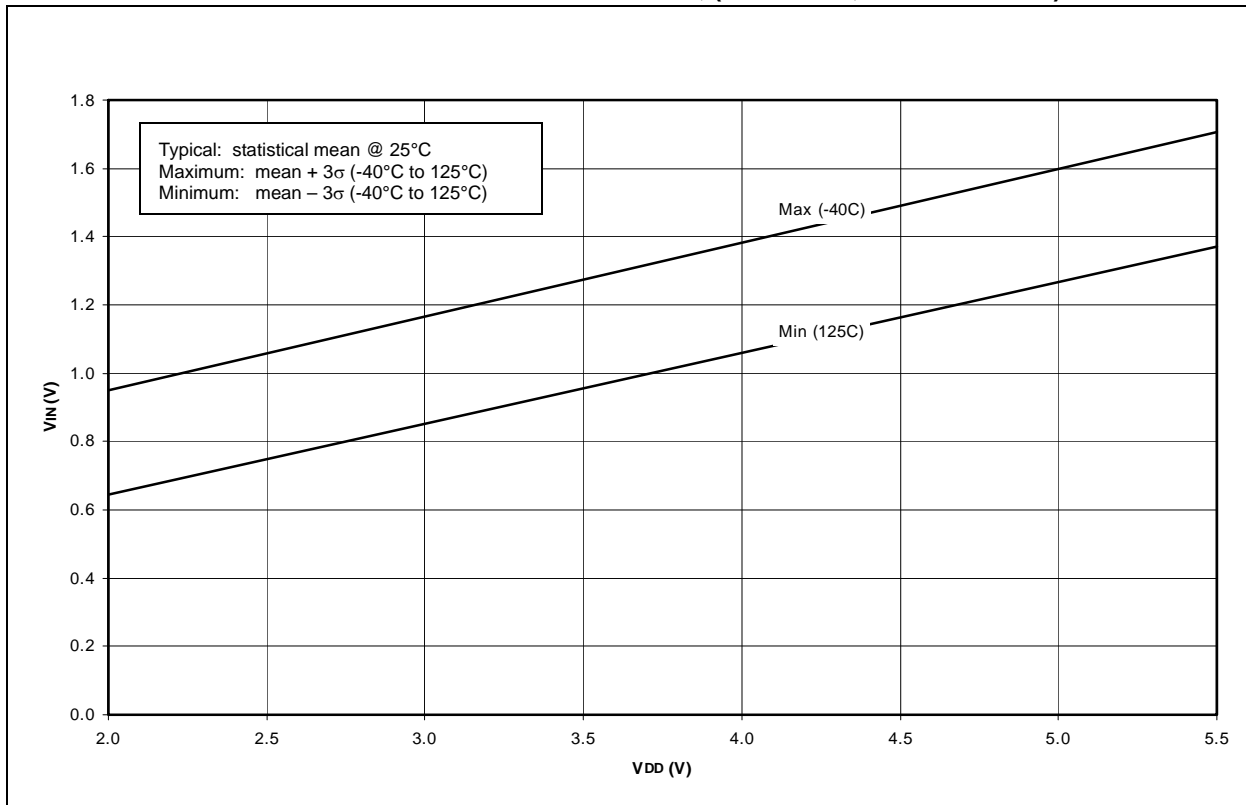


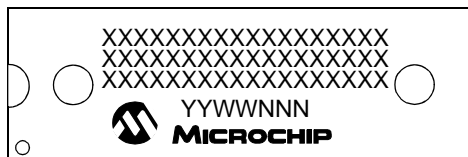
FIGURE 15-20: MINIMUM AND MAXIMUM V_{IN} vs. V_{DD} , (TTL INPUT, $-40^{\circ}C$ TO $125^{\circ}C$)



PIC16F870/871

Package Marking Information (Cont'd)

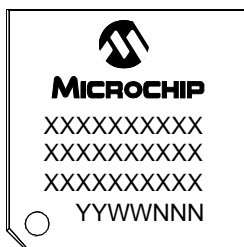
40-Lead PDIP



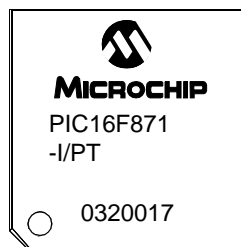
Example



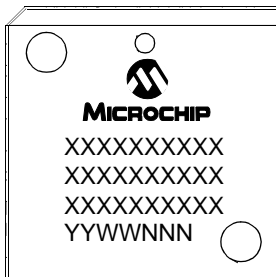
44-Lead TQFP



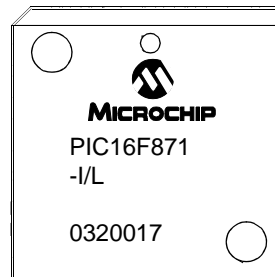
Example



44-Lead PLCC



Example



PIC16F870/871

PORTC.....	7, 8	Pulse Width Modulation.	
Associated Registers	37	See Capture/Compare/PWM, PWM Mode.	
PORTC Register	37	PUSH.....	24
RC0/T1OSO/T1CKI Pin	7, 8	R	
RC1/T1OSI Pin	7, 8	RAM. See Data Memory.	
RC2/CCP1 Pin	7, 8	RCREG Register	13
RC3 Pin.....	7, 8	RCSTA Register	13
RC4 Pin.....	7, 8	ADDEN Bit	62
RC5 Pin.....	7, 8	CREN Bit	62
RC6/TX/CK Pin	7, 8, 62	FERR Bit.....	62
RC7/RX/DT Pin.....	7, 8, 62, 63	OERR Bit	62
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PORTC Register	13	RX9D Bit.....	62
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RD7/PSP7 Pin	9	PCON (Power Control)	23
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PORTD Register	13	PIE2 (Peripheral Interrupt Enable 2).....	21
PORTE.....	9	PIR1 (Peripheral Interrupt Request Flag 1)	20
Analog Port Pins	41, 42	PIR2 (Peripheral Interrupt Request Flag 2)	22
Associated Registers	41	RCSTA (Receive Status and Control)	62
Input Buffer Full Status (IBF Bit)	40	STATUS	16
Input Buffer Overflow (IBOV Bit)	40	T1CON (Timer1 Control)	49
Output Buffer Full Status (OBF Bit).....	40	T2CON (Timer 2 Control)	53
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