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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	33
Program Memory Size	7KB (4K x 14)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	192 x 8
Voltage - Supply (Vcc/Vdd)	4V ~ 5.5V
Data Converters	A/D 8x8b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.59x16.59)
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Timer1 Module Data Sheet Errata

Clarifications/Corrections to the Data Sheet:

In the Device data sheets listed below, the following clarifications and corrections should be noted. Any silicon issues related to the Timer1 Module will be reported in a separate silicon errata. Please check the Microchip web site for any existing issues.

Device	Data Sheet	Device	Data Sheet	Device	Data Sheet	Device	Data Sheet
PIC12F609	DS41302	PIC16F716	DS41206	PIC18F2321	DC20000	PIC18F6585	DS30491
PIC12HV609		PIC16F737		PIC18F4321	DS39689	PIC18F6680	
PIC12F615		PIC16F747		PIC18F2331	DS39616	PIC18F8585	
PIC12HV615		PIC16F767	DS30498	PIC18F2431		PIC18F8680	
PIC12F617		FIC 10F707		FIC 10F2431		FIC 10F0000	
PIC12F629	DS41190	PIC16F777		PIC18F4331		PIC18F24J10	- DS39682
PIC12F675	D341190	PIC16F785	DS41249	PIC18F4431		PIC18F25J10	
PIC12F635		PIC16HV785	D341248	PIC18F2439	DS30485	PIC18F44J10	
PIC16F636	DS41232	PIC16F818	DS39598	PIC18F2539		PIC18F45J10	
PIC16F639		PIC16F819	D339396	PIC18F4439		PIC18F63J11	
PIC12F683	DS41211	PIC16F870 PIC18F4539	PIC18F4539	1	PIC18F64J11]	
PIC14000	DS40122	PIC16F871	DS30569	PIC18F2455		PIC18F65J11	D620774
PIC16C62A		PIC16F872	DS30221	PIC18F2550	DS39632	PIC18F83J11	DS39774
PIC16C63	DS30234	PIC16F873	- DS30292	PIC18F4455		PIC18F84J11	
PIC16C64A		PIC16F874		PIC18F4550		PIC18F85J11	
PIC16C65A		PIC16F876		PIC18F2480	DS39637	PIC18F63J90	DS39770
PIC16C66		PIC16F877		PIC18F4480		PIC18F64J90	
PIC16C67		PIC16F873A		PIC18F4580		PIC18F65J90	
PIC16C62B	DC25000	PIC16F874A	DS39582	PIC18F2510	DS39636	PIC18F83J90	
PIC16C72A	DS35008	PIC16F876A		PIC18F2610		PIC18F84J90	
PIC16C63A		PIC16F877A		PIC18F4510		PIC18F85J90	
PIC16C65B	DS30605	PIC16F882		PIC18F4610		PIC18F65J10	- DS39663
PIC16C73B	DS30605	PIC16F883	DS41291	PIC18F2520	DS39631	PIC18F65J15	
PIC16C74B		PIC16F884		PIC18F4520		PIC18F66J10	
PIC16C72		PIC16F886		PIC18F2585	DS39625 - DS39626	PIC18F66J15	
PIC16C73A		PIC16F887		PIC18F2680		PIC18F67J10	
PIC16C74A	DS30390	PIC16F913	DS41250	PIC18F4585		PIC18F85J10	
PIC16C76		PIC16F914		PIC18F4680		PIC18F85J15	
PIC16C77		PIC16F916		PIC18F2620		PIC18F86J10	
PIC16C745	DS41124	PIC16F917		PIC18F4620		PIC18F85J15	
PIC16C765		PIC16F946				PIC18F87J10	

Device	Data Sheet	Device	Data Sheet	Device	Data Sheet	Device	Data Sheet
PIC16C773	DS30275	PIC17C42A	DS30412	PIC18F4685	DS39761	PIC18F65J50	DS39775
PIC16C774		PIC17C43		PIC18F6390	DS39629	PIC18F66J50	
PIC16C923	DS30444	PIC17C44		PIC18F6490		PIC18F66J55	
PIC16C924		PIC17C752		PIC18F8390		PIC18F67J50	
PIC16C925	DS39544	PIC17C756A	DS30289	PIC18F8490		PIC18F85J50	
PIC16C926	D339344	PIC17C762	D330209	PIC18F6520		PIC18F85J55	
PIC16F72	DS39597	PIC17C766	,	PIC18F6620		PIC18F87J50	
PIC16F73		PIC18C242		PIC18F6720	DS39609	PIC18F66J11	- DS39778
PIC16F74	DS30325	PIC18C252	Desouse	PIC18F8520	DS39009	PIC18F66J16	
PIC16F76	DS30325	PIC18C442	DS39026	PIC18F8620	_	PIC18F67J11	
PIC16F77		PIC18C452	,	PIC18F8720		PIC18F86J11	
PIC16F87	DC20407	PIC18C601	DC20E44	PIC18F6525		PIC18F86J16	
PIC16F88	DS30487	PIC18C801	DS39541	PIC18F6621	D000040	PIC18F87J11	
PIC16F610		PIC18C658	DC2047E	PIC18F8525	DS39612	PIC18F66J60	DS39762
PIC16HV610	DC41200	PIC18C858	DS30475	PIC18F8621		PIC18F66J65	
PIC16F616	DS41288	PIC18F242		PIC18F6527	D020040	PIC18F67J60	
PIC16HV616		PIC18F252	DS39564	PIC18F6622		PIC18F86J60	
PIC16F627A		PIC18F442	D339304	PIC18F6627		PIC18F86J65	
PIC16F628A	DS40044	PIC18F452	,	PIC18F6722		PIC18F87J60	
PIC16F648A		PIC18F248		PIC18F8527	DS39646	PIC18F96J60	
PIC16F630	DC40020	PIC18F258	DS41159	PIC18F8622		PIC18F96J65	
PICF676	DS40039	PIC18F458		PIC18F8627		PIC18F97J60	
PIC16F631	DS41262 DS41202 DS41203	PIC18F1220	Desoene	PIC18F8722			
PIC16F677		PIC18F1320	DS39605				
PIC16F685		PIC18F1230	DS39758	1			
PIC16F687		PIC18F1330					
PIC16F689		PIC18F2220	- DS39599				
PIC16F690		PIC18F2330					
PIC16F684		PIC18F4220					
PIC16F688		PIC18F4320					

1. Asynchronous Counter

When Timer1 is started or updated, the timer needs to see a falling edge from the external clock source before a rising edge can increment the counter. If writes to TMR1H and TMR1L are not completed while the external clock pulse is still high, Timer1 will miss counting the first clock pulse after the update.

When using an external crystal, the pulse width from rising to falling edge is temperature dependent and may decrease with temperature. As a result, the timer may require an additional oscillation to overflow.

Code examples are given for the affected devices:

- PIC12/14/16/17 devices Example 1 and Example 2
- PIC18 devices Example 3

Both examples include code to wait for Timer1 to increment twice between the \mathtt{RTCisr} and \mathtt{Update} labels.

In PIC18 devices, it is not possible to reliably update Timer1 in a *low-priority* interrupt. A high-priority interrupt could occur at any time and unexpectedly delay the TMR1 update.

PIC18 devices also include Timer3 which is functionally identical to Timer1.

Work around

Switching Timer1 to the main system oscillator after reloading, the timer ensures the timer will see a falling edge before switching back to the external clock source.

Due to the time from Timer1 overflow to the reload being application specific, wait for the timer to increment before beginning the reload sequence. This ensures the timer does not miss a rising edge during reload. The timing of the clock source changing is critical and is detailed in Example 1 and Example 2.

EXAMPLE 1: PIC12/14/16/17 CODE EXAMPLE FOR 1 SECOND OVERFLOW PERIOD WITH 32.786 kHZ OSCILLATOR

```
BTFSC
            TMR1L,0
   GOTO
            $-1
   BTFSS
            TMR1L,0
   GOTO
            $-1
                            ;Timer has just incremented, 31 µs before next rising edge to
                            ; complete reload
Update:
            T1CON, TMR1CS ;Select system clock for Timer1
   BCF
            TMR1H,7 ;Timer1 high byte 0x80
   BSF
            T1CON, TMR1ON ; Timer1 off
   BCF
   BSF
            T1CON,TMR1C ;Select external crystal
   BSF
            T1CON, TMR1ON ; Timer1 on
Critical Timing of code sequence for instructions following last write to TMR1L or TMR1H.
```

EXAMPLE 2: PIC12/14/16/17 CODE EXAMPLE FOR OVERFLOW PERIODS OTHER THAN 1 SECOND OR USING AN OSCILLATOR OTHER THAN 32.768 kHZ

```
BTFSC
        TMR1L, 0
GOTO
        $-1
BTFSS TMR1L, 0
COTO
       S-1
                            ;Timer has just incremented, 31µs before next rising
                            edge to complete reload.
BCF
       T1CON, TMR1CS
                          ; Select system clock for Timer1.
MOVF
       TMR1, W
                           ; Sample low byte of Timer1 before increments.
ADDWF TMR1 Reload lo, F ; Add reload value for low byte
BTFSC STATUS, C
                           ; if this generates a carry then
       TMR1 Reload hi, F ; modify the reload value for the high byte.
INCF
MOVF
        TMR1 Reload hi, W ; Reload Timer1 high byte.
MOVWF
        TMR1H
        TMR1 Reload lo, W ; Reload Timer1 low byte.
MOVF
MOVW
        TMR1L
                          ;Timer1 off.
BCF
       T1CON, TMR1ON
       T1CON, TMR1CS
                           ; Select external crystal.
        T1CON, TMR1ON
BSF
                           ;Timer1 on.
-Critical Timing of code sequence for instructions.
```

EXAMPLE 3: PIC18 HIGH-PRIORITY INTERRUPT SERVICE ROUTINE

```
HIntVector code 0x0008 ; (3-4Tcy), fixed interrupt latency
   goto
          HighISR
                          ; (3Tcy) jump to high priority ISR code
                          ; unprotected code space
           code
HighISR:
   btfss PIR1, TMR1IF ; (1Tcy) TMR1 overflow?
   goto NextISR
                          ; (2Tcy) No, check another interrupt source
  Insert the next 4 lines of code when TMR1 can not
; be reliably updated before clock pulse goes low
RTCisr:
   \label{eq:btfsc} {\tt TMR1L,0} \qquad \qquad \hbox{;} \quad {\tt wait for TMR1L<0> to become clear}
                          ; may already be clear (loops for 0 to 30.5us); wait for TMR1L<0> to become set
   bra
           $-2
   btfss TMR1L,0
                          ; (loops for 30.5us)
; If TMR1 update can be completed before clock pulse
; goes low, start update here
Update:
           TMR1H,7 ; reload for next 1 second overflow PIR1,TMR1IF ; clear flag Seconds,F ; record second
          TMR1H,7
   bsf
   incf Seconds, F
   retfie FAST
NextISR:
                           ; Another interrupt source...
                           ; code for other interrupts, if needed
retfieFAST
```

REVISION HISTORY

Rev A Document (7/2007) Initial release of this errata.

Rev B Document (03/2010)

Added PIC12F617 device to the Clarifications/ Corrections to the Data Sheet section.

NOTES:

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