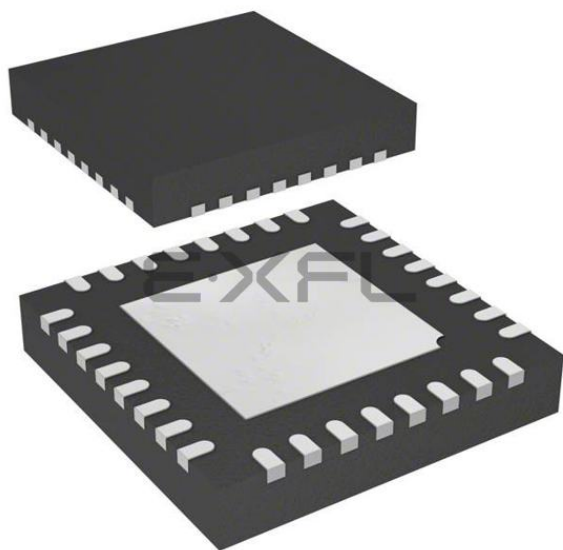




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Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, I ² S, POR, PWM, WDT
Number of I/O	24
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 11x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	32-UFQFPN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f301k8u7tr

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Figure 1. STM32F301x6/8 block diagram

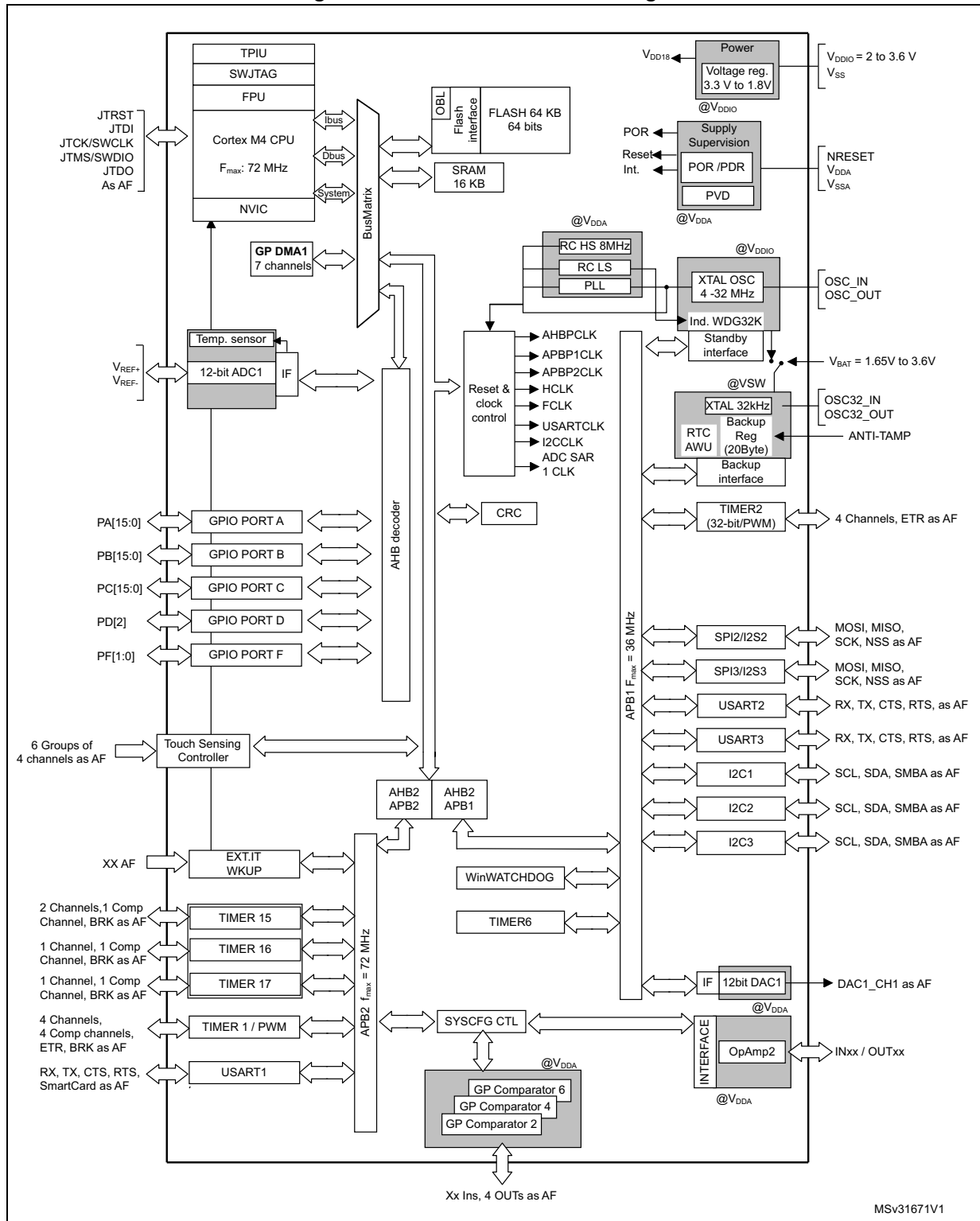




Table 13. STM32F301x6/8 pin definitions (continued)

Pin Number				Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
UQFN32	WLCSP49	LQFP48	LQFP64						
-	-	-	24	PC4	I/O	TT	-	EVENTOUT, TIM1_ETR, USART1_TX	
-	-	-	25	PC5	I/O	TTa	-	EVENTOUT, TIM15_BKIN, TSC_G3_IO1, USART1_RX	OPAMP2_VINM
15	G5	18	26	PB0	I/O	TTa	-	TSC_G3_IO2, TIM1_CH2N, EVENTOUT	ADC1_IN11, COMP4_INP, OPAMP2_VINP
-	G4	19	27	PB1	I/O	TTa	-	TSC_G3_IO3, TIM1_CH3N, COMP4_OUT, EVENTOUT	ADC1_IN12
-	G3	20	28	PB2	I/O	TTa	-	TSC_G3_IO4, EVENTOUT	COMP4_INM
-	E3	21	29	PB10	I/O	TT	-	TIM2_CH3, TSC_SYNC, USART3_TX, EVENTOUT	
-	G2	22	30	PB11	I/O	TTa	-	TIM2_CH4, TSC_G6_IO1, USART3_RX, EVENTOUT	ADC1_IN14, COMP6_INP
16	D3	23	31	VSS_2	S	-	-	Digital ground	
17	B2	24	32	VDD_2	S	-	-	Digital power supply	
-	E2	25	33	PB12	I/O	TT	-	TSC_G6_IO2, I2C2_SMBAL, SPI2_NSS/I2S2_WS, TIM1_BKIN, USART3_CK, EVENTOUT	
-	G1	26	34	PB13	I/O	TTa	-	TSC_G6_IO3, SPI2_SCK/I2S2_CK, TIM1_CH1N, USART3_CTS, EVENTOUT	ADC1_IN13

Table 14. Alternate functions for Port A (continued)

Port & pin name	AF0 AF1 AF2 AF3 AF4 AF5 AF6 AF7 AF8 AF9 AF10 AF11 AF12 AF13 AF14 AF15															
	SYS_AF	TIM2/TIM15/TIM16/TIM17/EVENT	I2C3/TIM1/TIM2/TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/TIM16/TIM17	SPI2/I2S2/SPI3/I2S3/Infrared	SPI2/I2S2/SPI3/I2S3/Infrared	USART1/USART2/USART3/GPCOMP6	I2C3/GPCOMP2/GPCOMP4/GPCOMP6	TIM1/TIM15	TIM2/TIM17	TIM1	TIM1	-	-	EVENT
PA9	-	-	I2C3_SMBAL	TSC_G4_IO1	I2C2_SCL	I2S3_MCK	TIM1_CH2	USART1_TX	-	TIM15_BKIN	TIM2_CH3	-	-	-	-	EVENT OUT
PA10	-	TIM17_BKIN		TSC_G4_IO2	I2C2_SDA	SPI2_MISO/I2S2ext_SD	TIM1_CH3	USART1_RX	COMP6_OUT	-	TIM2_CH4	-	-	-	-	EVENT OUT
PA11	-	-	-	-	-	SPI2_MOSI/I2S2_SD	TIM1_CH1N	USART1_CTS	-	-	-	TIM1_CH4	TIM1_BKIN2	-	-	EVENT OUT
PA12	-	TIM16_CH1	-	-	-	I2SCKIN	TIM1_CH2N	USART1_RTS_DE	COMP2_OUT	-	-	TIM1_ETR	-	-	-	EVENT OUT
PA13	SWDAT-JTMS	TIM16_CH1N	-	TSC_G4_IO3	-	IR-OUT	-	USART3_CTS	-	-	-	-	-	-	-	EVENT OUT
PA14	SWCLK-JTCK		-	TSC_G4_IO4	I2C1_SDA	-	TIM1_BKIN	USART2_TX	-	-	-	-	-	-	-	EVENT OUT
PA15	JTDI	TIM2_CH1/TIM2_ETR	-	TSC_SYNC	I2C1_SCL	-	SPI3_NSS/I2S3_WS	USART2_RX	-	TIM1_BKIN	-	-	-	-	-	EVENT OUT

Table 16. Alternate functions for Port C

Port & pin name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
	SYS_AF	TIM2/TIM15/ TIM16/TIM17/ EVENT	I2C3/TIM1/TIM2 /TIM15	I2C3/TIM15/ TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3 Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/ Infrared	USART1/ USART2/ USART3/ GPCOMP6
PC0	-	EVENTOUT	TIM1_CH1	-	-	-	-	-
PC1	-	EVENTOUT	TIM1_CH2	-	-	-	-	-
PC2	-	EVENTOUT	TIM1_CH3	-	-	-	-	-
PC3	-	EVENTOUT	TIM1_CH4	-	-	-	TIM1_BKIN2	-
PC4	-	EVENTOUT	TIM1_ETR	-	-	-	-	USART1_TX
PC5	-	EVENTOUT	TIM15_BKIN	TSC_G3_IO1	-	-	-	USART1_RX
PC6	-	EVENTOUT	-	-	-	-	I2S2_MCK	COMP6_OUT
PC7	-	EVENTOUT	-	-	-	-	I2S3_MCK	-
PC8	-	EVENTOUT	-	-	-	-	-	-
PC9	-	EVENTOUT	-	I2C3_SDA	-	I2SCKIN	-	-
PC10	-	EVENTOUT	-	-	-	-	SPI3_SCK/ I2S3_CK	USART3_TX
PC11	-	EVENTOUT	-	-	-	-	SPI3_MISO/ I2S3ext_SD	USART3_RX
PC12	-	EVENTOUT	-	-	-	-	SPI3_MOSI/ I2S3_SD	USART3_CK
PC13	-	-	-	-	TIM1_CH1N	-	-	-
PC14	-	-	-	-	-	-	-	-
PC15	-	-	-	-	-	-	-	-



Table 17. Alternate functions for Port D

Port & pin name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
	SYS_AF	TIM2/TIM15/ TIM16/TIM17/ EVENT	I2C3/TIM1/TIM2/ TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3/ Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/ Infrared	USART1/ USART2/ USART3/ GPCOMP6
PD2	-	EVENTOUT	-	-	-	-	-	-

Table 18. Alternate functions for Port F

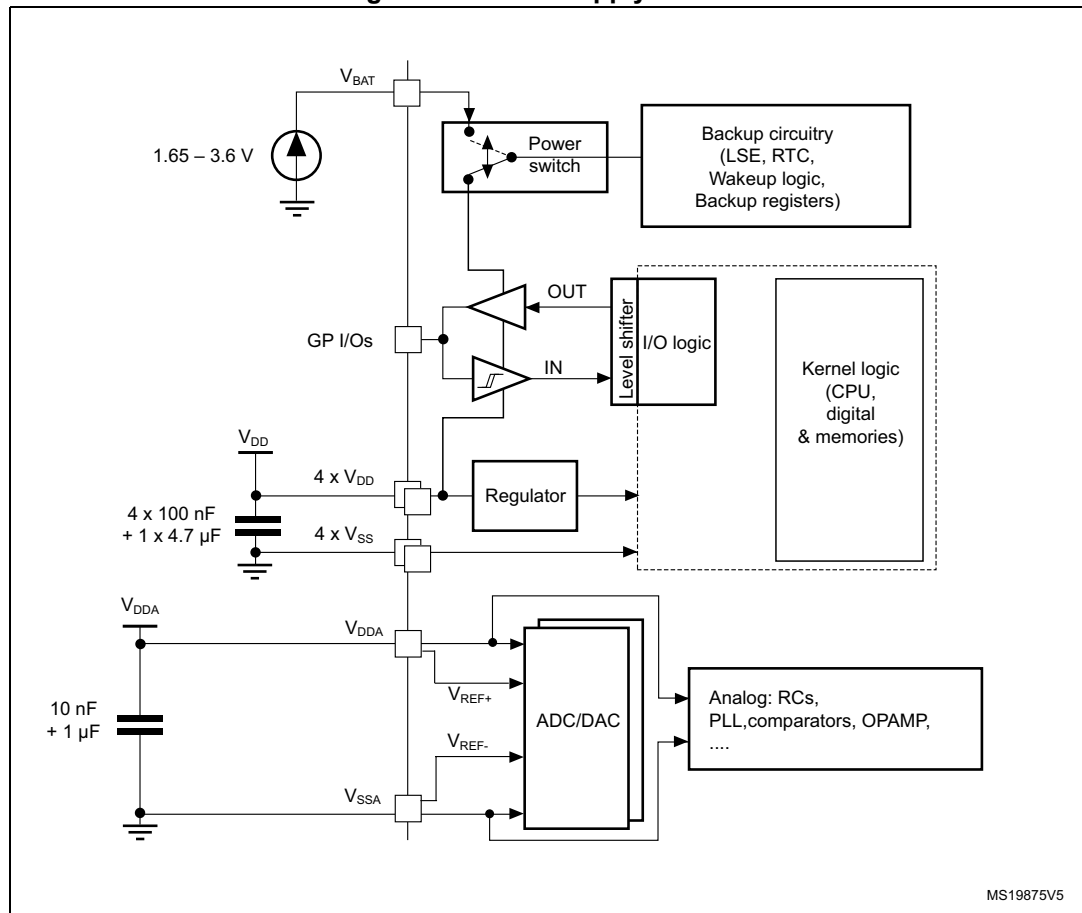
Port & pin name	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
	SYS_AF	TIM2/TIM15/ TIM16/TIM17/ EVENT	I2C3/TIM1/TIM2/ TIM15	I2C3/TIM15/TSC	I2C1/I2C2/TIM1/ TIM16/TIM17	SPI2/I2S2/ SPI3/I2S3/ Infrared	SPI2/I2S2/SPI3/ I2S3/TIM1/ Infrared	USART1/USAR T2/USART3/ GPCOMP6
PF0	-	-	-	-	I2C2_SDA	SPI2_NSS/ I2S2_WS	TIM1_CH3N	-
PF1	-	-	-	-	I2C2_SCL	SPI2_SCK/ I2S2_CK	-	-

Table 19. STM32F301x6 STM32F301x8 peripheral register boundary addresses ⁽¹⁾

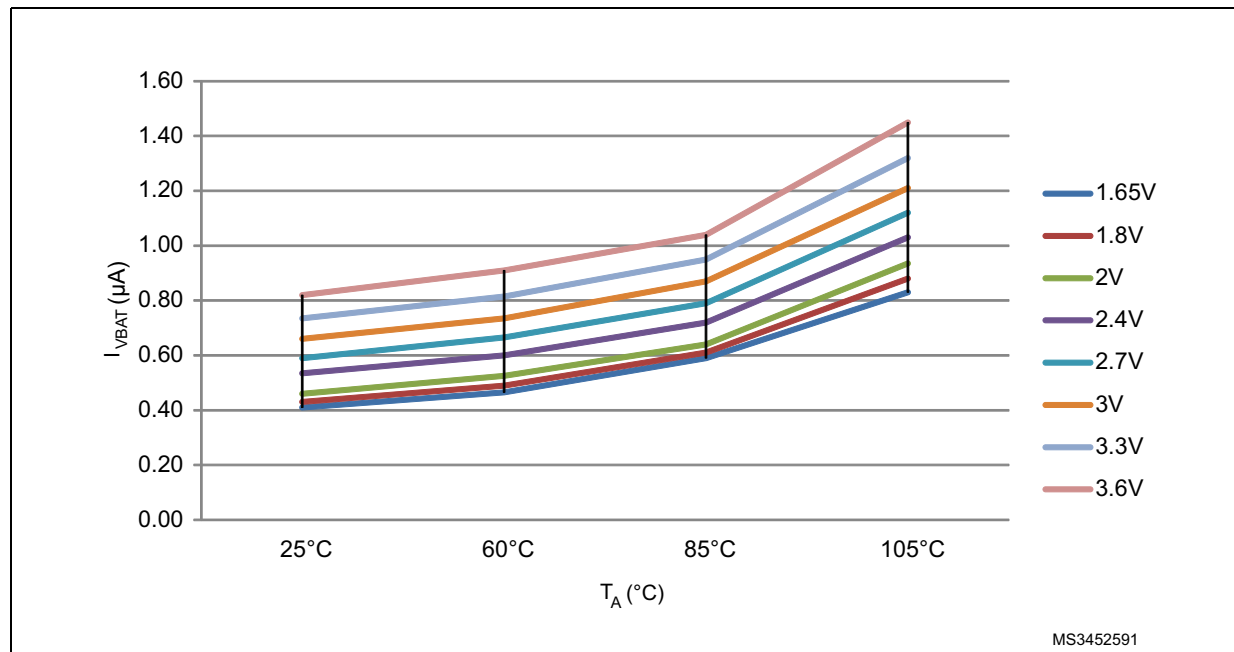
Bus	Boundary address	Size (bytes)	Peripheral
AHB3	0x5000 0000 - 0x5000 03FF	1 K	ADC1
	0x4800 1800 - 0x4FFF FFFF	~132 M	Reserved
AHB2	0x4800 1400 - 0x4800 17FF	1 K	GPIOF
	0x4800 1000 - 0x4800 13FF	1 K	Reserved
	0x4800 0C00 - 0x4800 0FFF	1 K	GPIOD
	0x4800 0800 - 0x4800 0BFF	1 K	GPIOC
	0x4800 0400 - 0x4800 07FF	1 K	GPIOB
	0x4800 0000 - 0x4800 03FF	1 K	GPIOA
	0x4002 4400 - 0x47FF FFFF	~128 M	Reserved
AHB1	0x4002 4000 - 0x4002 43FF	1 K	TSC
	0x4002 3400 - 0x4002 3FFF	3 K	Reserved
	0x4002 3000 - 0x4002 33FF	1 K	CRC
	0x4002 2400 - 0x4002 2FFF	3 K	Reserved
	0x4002 2000 - 0x4002 23FF	1 K	Flash interface
	0x4002 1400 - 0x4002 1FFF	3 K	Reserved
	0x4002 1000 - 0x4002 13FF	1 K	RCC
	0x4002 0400 - 0x4002 0FFF	3 K	Reserved
	0x4002 0000 - 0x4002 03FF	1 K	DMA1
	0x4001 8000 - 0x4001 FFFF	32 K	Reserved
APB2	0x4001 4C00 - 0x4001 7FFF	13 K	Reserved
	0x4001 4800 - 0x4001 4BFF	1 K	TIM17
	0x4001 4400 - 0x4001 47FF	1 K	TIM16
	0x4001 4000 - 0x4001 43FF	1 K	TIM15
	0x4001 3C00 - 0x4001 3FFF	1 K	Reserved
	0x4001 3800 - 0x4001 3BFF	1 K	USART1
	0x4001 3000 - 0x4001 37FF	2 K	Reserved
	0x4001 2C00 - 0x4001 2FFF	1 K	TIM1
	0x4001 0800 - 0x4001 2BFF	8 K	Reserved
	0x4001 0400 - 0x4001 07FF	1 K	EXTI
	0x4001 0000 - 0x4001 03FF	1 K	SYSCFG + COMP + OPAMP
	0x4000 9C00 - 0x4000 FFFF	25 K	Reserved

6.1.6 Power supply scheme

Figure 11. Power supply scheme



Caution: Each power supply pair (for example V_{DD}/V_{SS} , V_{DDA}/V_{SSA}) must be decoupled with filtering ceramic capacitors as shown above. These capacitors must be placed as close as possible to, or below the appropriate pins on the underside of the PCB to ensure the good functionality of the device.

Figure 13. Typical V_{BAT} current consumption (LSE and RTC ON/LSEDRV[1:0] = '00')

Typical current consumption

The MCU is placed under the following conditions:

- $V_{DD} = V_{DDA} = 3.3$ V
- All I/O pins available on each package are in analog input configuration
- The Flash access time is adjusted to f_{HCLK} frequency (0 wait states from 0 to 24 MHz, 1 wait state from 24 to 48 MHz and 2 wait states from 48 MHz to 72 MHz), and Flash prefetch is ON
- When the peripherals are enabled, $f_{APB1} = f_{AHB}/2$, $f_{APB2} = f_{AHB}$
- PLL is used for frequencies greater than 8 MHz
- AHB prescaler of 2, 4, 8, 16 and 64 is used for the frequencies 4 MHz, 2 MHz, 1 MHz, 500 kHz and 125 kHz respectively.

6.3.8 Internal clock source characteristics

The parameters given in [Table 44](#) are derived from tests performed under ambient temperature and supply voltage conditions summarized in [Table 23](#).

High-speed internal (HSI) RC oscillator

Table 44. HSI oscillator characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI}	Frequency	-	-	8	-	MHz
TRIM	HSI user trimming step	-	-	-	1 ⁽²⁾	%
DuCy _(HSI)	Duty cycle	-	45 ⁽²⁾	-	55 ⁽²⁾	%
ACC _{HSI}	Accuracy of the HSI oscillator	$T_A = -40$ to 105°C	-2.8 ⁽³⁾	-	3.8 ⁽³⁾	%
		$T_A = -10$ to 85°C	-1.9 ⁽³⁾	-	2.3 ⁽³⁾	
		$T_A = 0$ to 85°C	-1.9 ⁽³⁾	-	2 ⁽³⁾	
		$T_A = 0$ to 70°C	-1.3 ⁽³⁾	-	2 ⁽³⁾	
		$T_A = 0$ to 55°C	-1 ⁽³⁾	-	2 ⁽³⁾	
		$T_A = 25^\circ\text{C}^{(4)}$	-1	-	1	
$t_{\text{su(HSI)}}$	HSI oscillator startup time	-	1 ⁽²⁾	-	2 ⁽²⁾	μs
$I_{\text{DDA(HSI)}}$	HSI oscillator power consumption	-	-	80	100 ⁽²⁾	μA

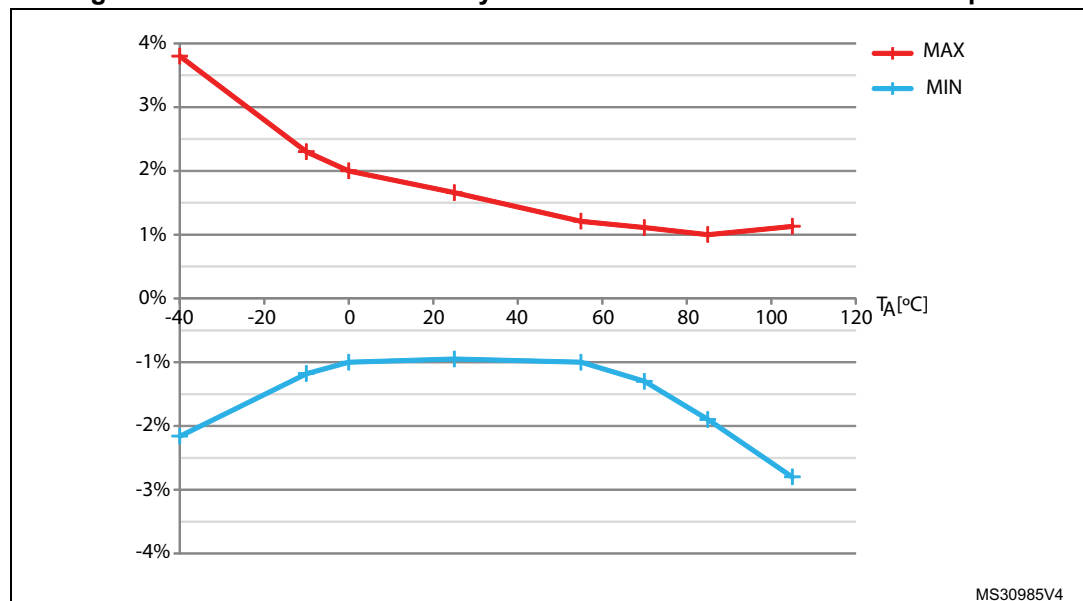
1. $V_{\text{DDA}} = 3.3\text{ V}$, $T_A = -40$ to 105°C unless otherwise specified.

2. Guaranteed by design.

3. Guaranteed by characterization results.

4. Factory calibrated, parts not soldered.

Figure 18. HSI oscillator accuracy characterization results for soldered parts



Low-speed internal (LSI) RC oscillator

Table 45. LSI oscillator characteristics⁽¹⁾

Symbol	Parameter	Min	Typ	Max	Unit
f_{LSI}	Frequency	30	40	50	kHz
$t_{\text{su(LSI)}}^{(2)}$	LSI oscillator startup time	-	-	85	μs
$I_{\text{DD(LSI)}}^{(2)}$	LSI oscillator power consumption	-	0.75	1.2	μA

1. $V_{\text{DDA}} = 3.3 \text{ V}$, $T_{\text{A}} = -40$ to $105 \text{ }^{\circ}\text{C}$ unless otherwise specified.

2. Guaranteed by design.

6.3.9 PLL characteristics

The parameters given in [Table 46](#) are derived from tests performed under ambient temperature and supply voltage conditions summarized in [Table 23](#).

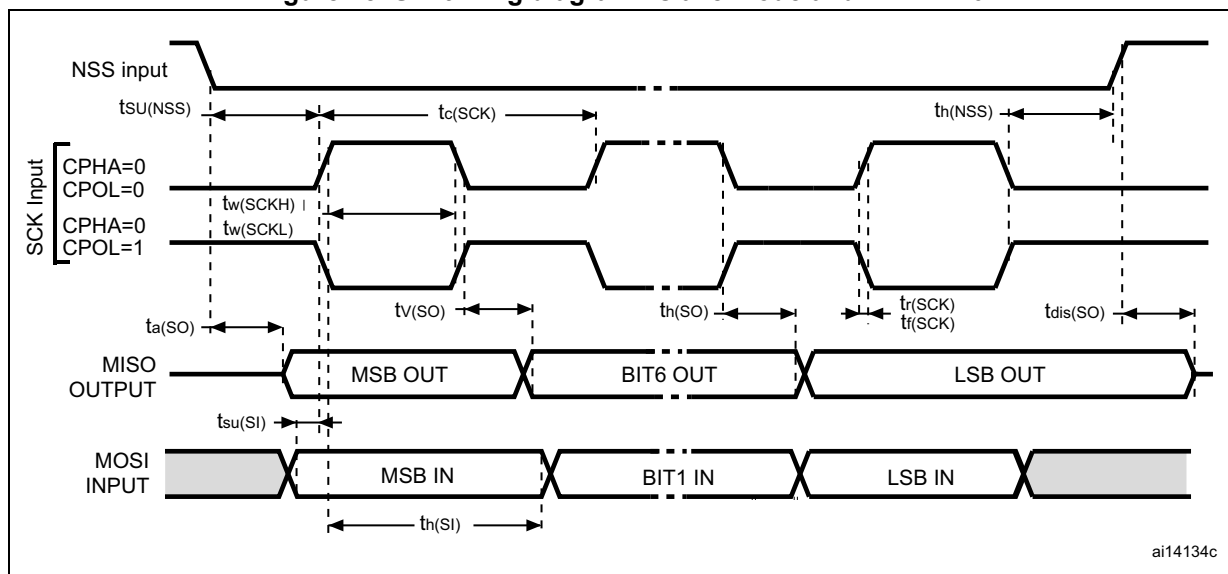
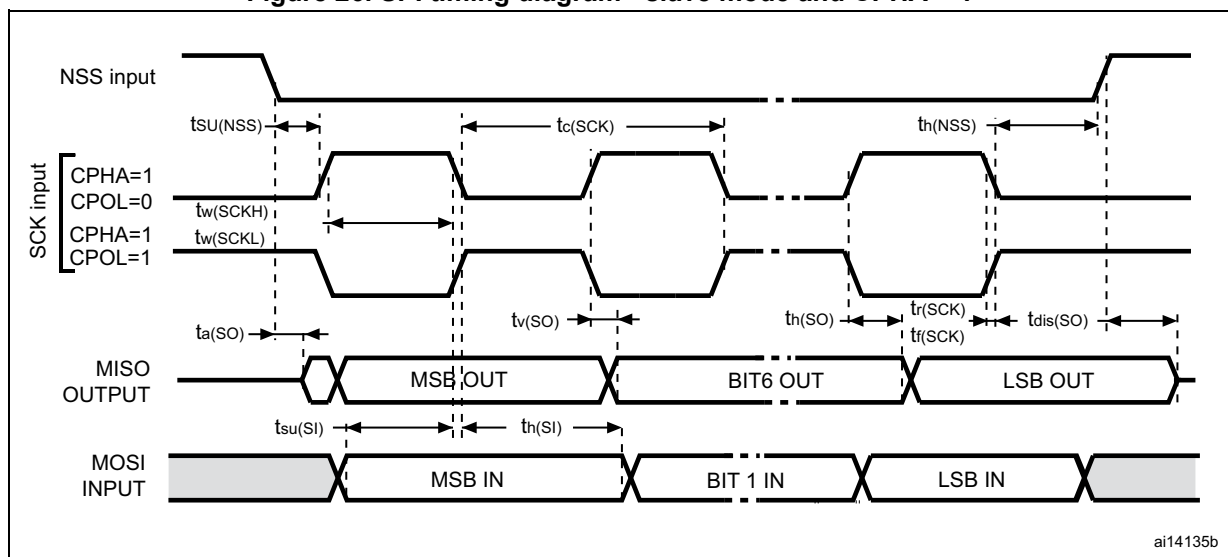
Table 46. PLL characteristics

Symbol	Parameter	Value			Unit
		Min	Typ	Max	
$f_{\text{PLL_IN}}$	PLL input clock ⁽¹⁾	1 ⁽²⁾	-	24 ⁽²⁾	MHz
	PLL input clock duty cycle	40 ⁽²⁾	-	60 ⁽²⁾	%
$f_{\text{PLL_OUT}}$	PLL multiplier output clock	16 ⁽²⁾	-	72	MHz
t_{LOCK}	PLL lock time	-	-	200 ⁽²⁾	μs
Jitter	Cycle-to-cycle jitter	-	-	300 ⁽²⁾	ps

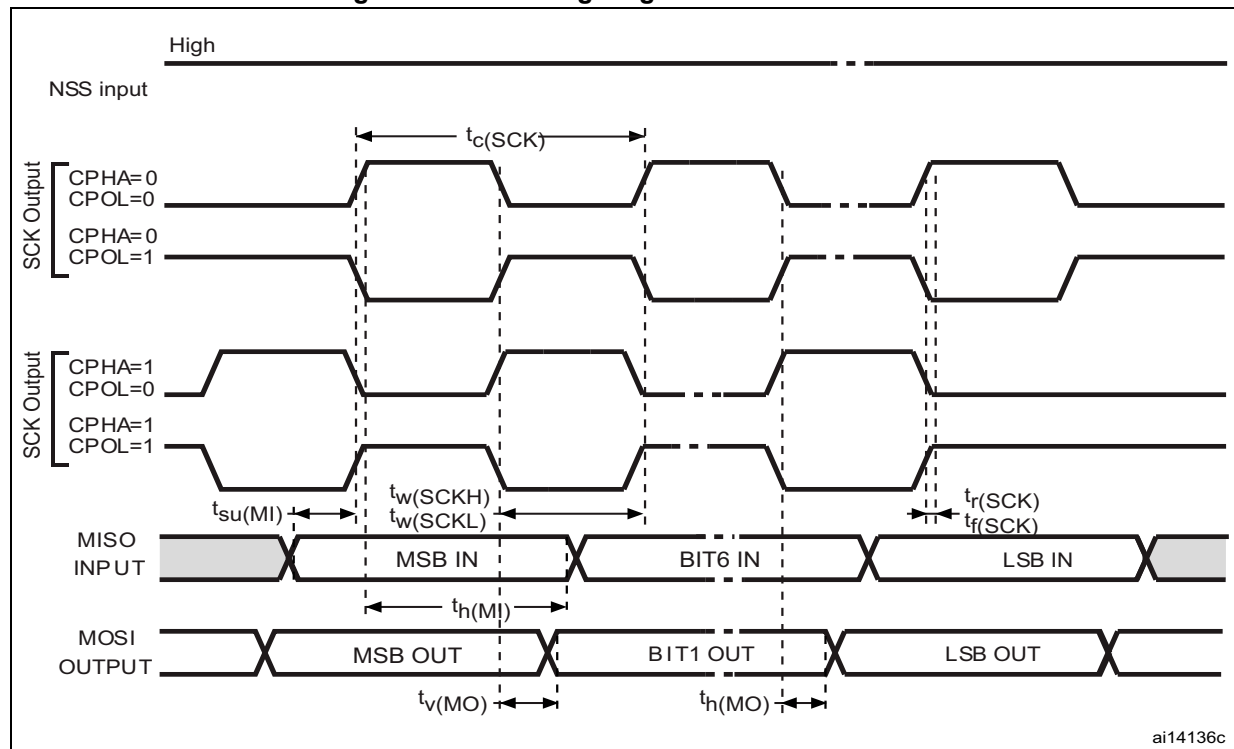
1. Take care of using the appropriate multiplier factors so as to have PLL input clock values compatible with the range defined by $f_{\text{PLL_OUT}}$.

2. Guaranteed by design.

Figure 25. SPI timing diagram - slave mode and CPHA = 0

Figure 26. SPI timing diagram - slave mode and CPHA = 1⁽¹⁾

1. Measurement points are done at $0.5V_{DD}$ and with external $C_L = 30$ pF.

Figure 27. SPI timing diagram - master mode⁽¹⁾

1. Measurement points are done at $0.5V_{DD}$ and with external $C_L = 30 \text{ pF}$.

Table 63. I2S characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MCK}	I2S Main clock output	-	256 x 8K	256x F_s ⁽²⁾	MHz
f_{CK}	I2S clock frequency	Master data: 32 bits	-	64x F_s	MHz
		Slave data: 32 bits	-	64x F_s	
D_{CK}	I2S clock frequency duty cycle	Slave receiver	30	70	%

Table 63. I2S characteristics⁽¹⁾ (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{v(WS)}$	WS valid time	Master mode	-	20	ns
$t_{h(WS)}$	WS hold time	Master mode	2	-	
$t_{su(WS)}$	WS setup time	Slave mode	0	-	
$t_{h(WS)}$	WS hold time	Slave mode	4	-	
$t_{su(SD_MR)}$	Data input setup time	Master receiver	1	-	
$t_{su(SD_SR)}$		Slave receiver	1	-	
$t_{h(SD_MR)}$	Data input hold time	Master receiver	8	-	
$t_{h(SD_SR)}$		Slave receiver	2.5	-	
$t_{v(SD_ST)}$	Data output valid time	Slave transmitter (after enable edge)	-	50	
$t_{v(SD_MT)}$		Master transmitter (after enable edge)	-	22	
$t_{h(SD_ST)}$	Data output hold time	Slave transmitter (after enable edge)	8	-	
$t_{h(SD_MT)}$		Master transmitter (after enable edge)	1	-	

1. Guaranteed by characterization results.

2. 256x F_s maximum is 36 MHz (APB1 Maximum frequency)

Note: Refer to RM0366 Reference Manual I2S Section for more details about the sampling frequency (F_s), f_{MCK} , f_{CK} , DCK values reflect only the digital peripheral behavior, source clock precision might slightly change the values DCK depends mainly on ODD bit value. Digital contribution leads to a min of $(I2SDIV/(2*I2SDIV+ODD))$ and a max $(I2SDIV+ODD)/(2*I2SDIV+ODD)$ and F_s max supported for each mode/condition.

Table 66. ADC accuracy - limited test conditions⁽¹⁾⁽²⁾

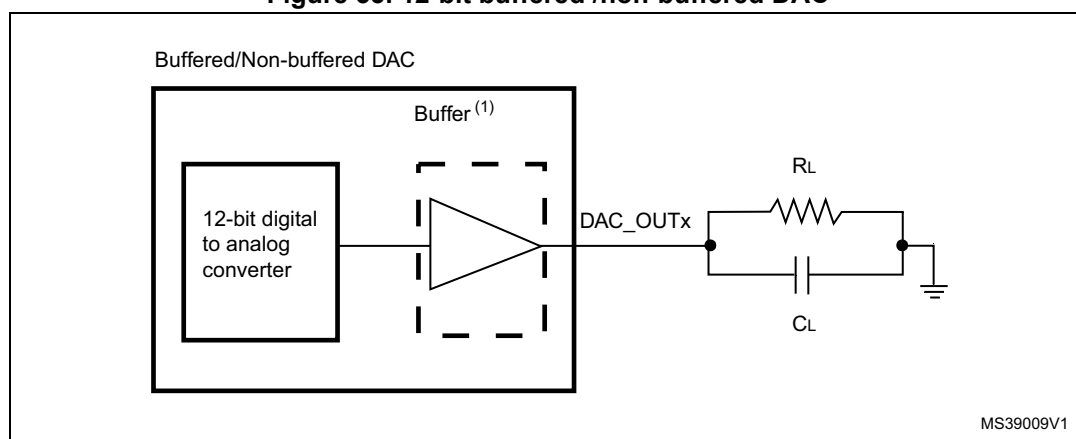
Symbol	Parameter	Conditions			Min (3)	Typ	Max (3)	Unit
ET	Total unadjusted error	ADC clock freq. ≤ 72 MHz Sampling freq. ≤ 5 Msps V _{DDA} = 3.3 V 25°C	Single ended	Fast channel 5.1 Ms	-	±4	±4.5	LSB
				Slow channel 4.8 Ms	-	±5.5	±6	
Differential	Fast channel 5.1 Ms		-	±3.5	±4			
	Slow channel 4.8 Ms		-	±3.5	±4			
EO	Offset error		Single ended	Fast channel 5.1 Ms	-	±2	±2	
				Slow channel 4.8 Ms	-	±1.5	±2	
			Differential	Fast channel 5.1 Ms	-	±1.5	±2	
				Slow channel 4.8 Ms	-	±1.5	±2	
EG	Gain error		Single ended	Fast channel 5.1 Ms	-	±3	±4	
				Slow channel 4.8 Ms	-	±5	±5.5	
			Differential	Fast channel 5.1 Ms	-	±3	±3	
				Slow channel 4.8 Ms	-	±3	±3.5	
ED	Differential linearity error	Single ended	Fast channel 5.1 Ms	-	±1	±1		
			Slow channel 4.8 Ms	-	±1	±1		
		Differential	Fast channel 5.1 Ms	-	±1	±1		
			Slow channel 4.8 Ms	-	±1	±1		
EL	Integral linearity error	Single ended	Fast channel 5.1 Ms	-	±1.5	±2		
			Slow channel 4.8 Ms	-	±2	±3		
		Differential	Fast channel 5.1 Ms	-	±1.5	±1.5		
			Slow channel 4.8 Ms	-	±1.5	±2		
ENOB ⁽⁴⁾	Effective number of bits		Single ended	Fast channel 5.1 Ms	10.8	10.8	-	bit
				Slow channel 4.8 Ms	10.8	10.8	-	
			Differential	Fast channel 5.1 Ms	11.2	11.3	-	
				Slow channel 4.8 Ms	11.2	11.3	-	
SINAD ⁽⁴⁾	Signal-to-noise and distortion ratio		Single ended	Fast channel 5.1 Ms	66	67	-	dB
				Slow channel 4.8 Ms	66	67	-	
			Differential	Fast channel 5.1 Ms	69	70	-	
				Slow channel 4.8 Ms	69	70	-	

Table 69. DAC characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Update rate ⁽³⁾	Max frequency for a correct DAC_OUT change when small variation in the input code (from code i to i+1LSB)	$C_{LOAD} \leq 50$ pF, $R_{LOAD} \geq 5$ k Ω	-	-	1	MS/s
$t_{WAKEUP}^{(3)}$	Wakeup time from off state (Setting the ENx bit in the DAC Control register)	$C_{LOAD} \leq 50$ pF, $R_{LOAD} \geq 5$ k Ω	-	6.5	10	μ s
PSRR+ ⁽¹⁾	Power supply rejection ratio (to V_{DDA}) (static DC measurement)	$C_{LOAD} = 50$ pF, No $R_{LOAD} \geq 5$ k Ω	-	-67	-40	dB

1. Guaranteed by design.
2. Quiescent mode refers to the state of the DAC a keeping steady value on the output, so no dynamic consumption is involved.
3. Guaranteed by characterization results.

Figure 33. 12-bit buffered /non-buffered DAC



1. The DAC integrates an output buffer that can be used to reduce the output impedance and to drive external loads directly without the use of an external operational amplifier. The buffer can be bypassed by configuring the BOFFx bit in the DAC_CR register.

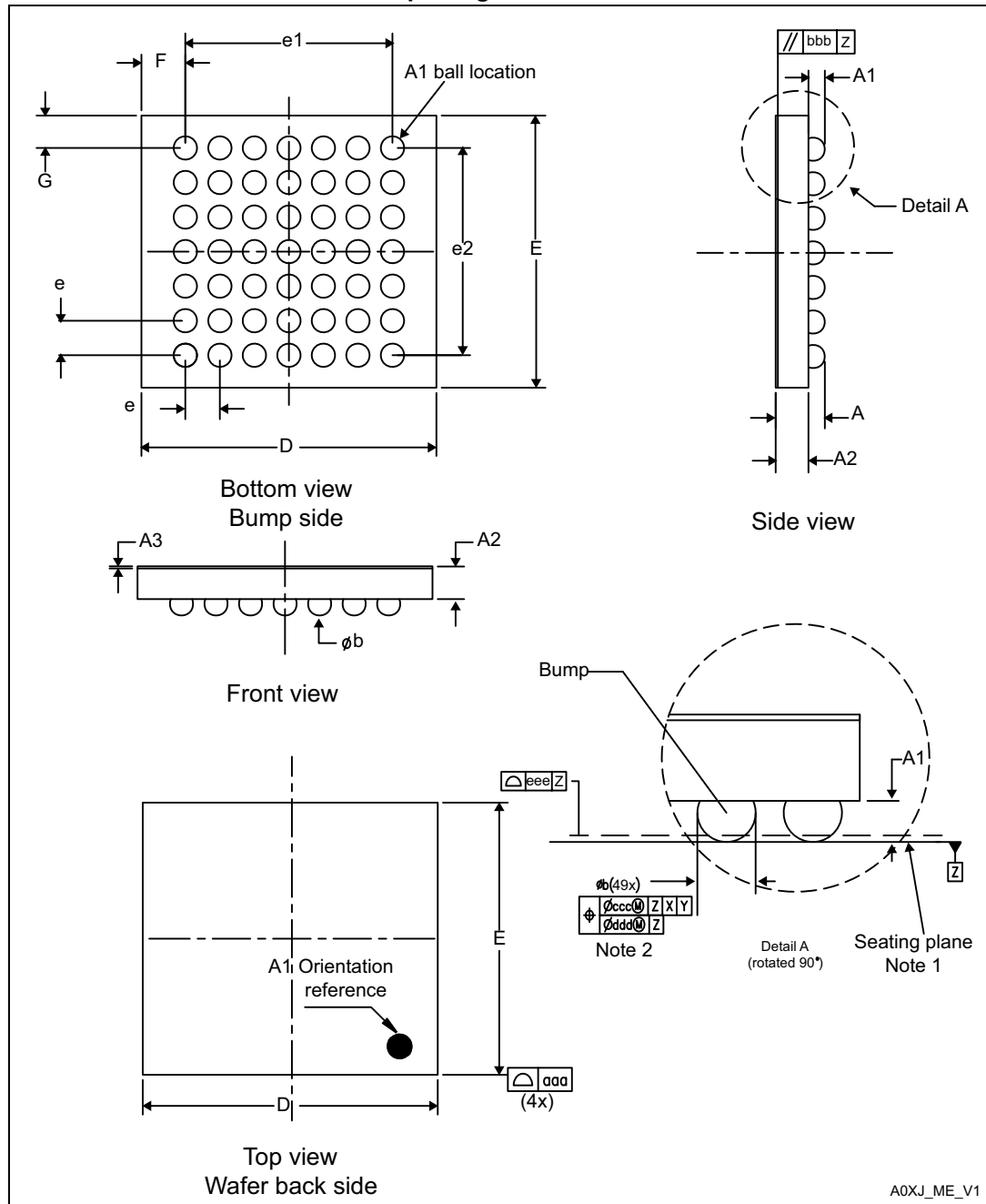
6.3.20 Comparator characteristics

Table 70. Comparator characteristics⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
V_{DDA}	Analog supply voltage	-	2	-	3.6	V
V_{IN}	Comparator input voltage range	-	0	-	V_{DDA}	V
V_{BG}	Scaler input voltage	-	-	$V_{REFINIT}$	-	
V_{SC}	Scaler offset voltage	-	-	± 5	± 10	mV

7.1 WLCSP49 package information

Figure 36. WLCSP49 - 49-pin, 3.417 x 3.151 mm, 0.4 mm pitch wafer level chip scale package outline



1. Drawing is not to scale.

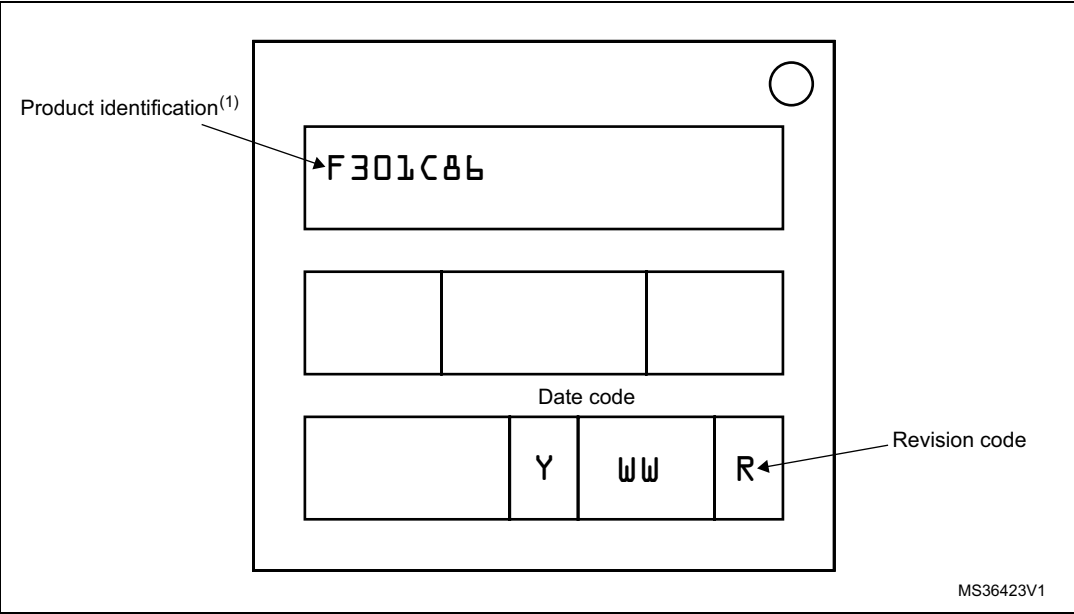
Table 76. WLCSP49 recommended PCB design rules (0.4 mm pitch)

Dimension	Recommended values
Pitch	0.4
Dpad	260 µm max. (circular) 220 µm recommended
Dsm	300 µm min. (for 260 µm diameter pad)
PCB pad design	Non-solder mask defined via underbump allowed.

Device marking

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

Figure 38. WLCSP49 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

**Table 78. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package
mechanical data**

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	8.800	9.000	9.200	0.3465	0.3543	0.3622
D1	6.800	7.000	7.200	0.2677	0.2756	0.2835
D3	-	5.500	-	-	0.2165	-
E	8.800	9.000	9.200	0.3465	0.3543	0.3622
E1	6.800	7.000	7.200	0.2677	0.2756	0.2835
E3	-	5.500	-	-	0.2165	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Example 2: High-temperature application

Using the same rules, it is possible to address applications that run at high ambient temperatures with a low dissipation, as long as junction temperature T_J remains within the specified range.

Assuming the following application conditions:

Maximum ambient temperature $T_{Amax} = 115\text{ °C}$ (measured according to JESD51-2),
 $I_{DDmax} = 20\text{ mA}$, $V_{DD} = 3.5\text{ V}$, maximum 9 I/Os used at the same time in output at low level with $I_{OL} = 8\text{ mA}$, $V_{OL} = 0.4\text{ V}$

$$P_{INTmax} = 20\text{ mA} \times 3.5\text{ V} = 70\text{ mW}$$

$$P_{IOmax} = 9 \times 8\text{ mA} \times 0.4\text{ V} = 28.8\text{ mW}$$

This gives: $P_{INTmax} = 70\text{ mW}$ and $P_{IOmax} = 28.8\text{ mW}$:

$$P_{Dmax} = 70 + 28.8 = 98.8\text{ mW}$$

Thus: $P_{Dmax} = 98.8\text{ mW}$

Using the values obtained in [Table 80](#) T_{Jmax} is calculated as follows:

– For LQFP100, 45 °C/W

$$T_{Jmax} = 115\text{ °C} + (45\text{ °C/W} \times 98.8\text{ mW}) = 115\text{ °C} + 4.44\text{ °C} = 119.44\text{ °C}$$

This is within the range of the suffix 7 version parts ($-40 < T_J < 125\text{ °C}$).

In this case, parts must be ordered at least with the temperature range suffix 7 (see [Section 8: Ordering information](#)).