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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	13
Program Memory Size	3.5KB (2K x 14)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 6V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c622-04-ss

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

		PIC16C620 ⁽³⁾	PIC16C620A ⁽¹⁾⁽⁴⁾	PIC16CR620A ⁽²⁾	PIC16C621 ⁽³⁾	PIC16C621A ⁽¹⁾⁽⁴⁾	PIC16C622 ⁽³⁾	PIC16C622A ⁽¹⁾⁽⁴⁾
Clock	Maximum Frequency of Operation (MHz)	20	40	20	20	40	20	40
Memory	EPROM Program Memory (x14 words)	512	512	512	1K	1K	2K	2K
	Data Memory (bytes)	80	96	96	80	96	128	128
Peripherals	Timer Module(s)	TMR0	TMR0	TMRO	TMR0	TMR0	TMR0	TMR0
	Comparators(s)	2	2	2	2	2	2	2
	Internal Reference Voltage	Yes						
Features	Interrupt Sources	4	4	4	4	4	4	4
	I/O Pins	13	13	13	13	13	13	13
	Voltage Range (Volts)	2.5-6.0	2.7-5.5	2.5-5.5	2.5-6.0	2.7-5.5	2.5-6.0	2.7-5.5
	Brown-out Reset	Yes						
	Packages	18-pin DIP, SOIC; 20-pin SSOP						

TABLE 1-1: PIC16C62X FAMILY OF DEVICES

All PICmicro[®] Family devices have Power-on Reset, selectable Watchdog Timer, selectable code protect and high I/O current capability. All PIC16C62X Family devices use serial programming with clock pin RB6 and data pin RB7.

Note 1: If you change from this device to another device, please verify oscillator characteristics in your application.

2: For ROM parts, operation from 2.0V - 2.5V will require the PIC16LCR62XA parts.

3: For OTP parts, operation from 2.5V - 3.0V will require the PIC16LC62X part.

4: For OTP parts, operation from 2.7V - 3.0V will require the PIC16LC62XA part.

FIGURE 3-1: BLOCK DIAGRAM



FIGURE 4-4: DATA MEMORY MAP FOR THE PIC16C620/621

File Address	3		File Address
00h	INDF ⁽¹⁾	INDF ⁽¹⁾	80h
01h	TMR0	OPTION	81h
02h	PCL	PCL	82h
03h	STATUS	STATUS	83h
04h	FSR	FSR	84h
05h	PORTA	TRISA	85h
06h	PORTB	TRISB	86h
07h			87h
08h			88h
09h			89h
0Ah	PCLATH	PCLATH	8Ah
0Bh	INTCON	INTCON	8Bh
0Ch	PIR1	PIE1	8Ch
0Dh			8Dh
0Eh		PCON	8Eh
0Fh			8Fh
10h			90h
11h			91h
12h			92h
13h			93h
14h			94h
15h			95h
16h			96h
17h			97h
18h			98h
19h			99h
1Ah			9Ah
1Bh			9Bh
1Ch			9Ch
1Dh			9Dh
1Eh			9Eh
1Fh	CMCON	VRCON	9Fh
20h	Osmanal		A0h
	Purpose		
6Eb	Register		
70n			
Į			_
7Fh	Donk 0	Dorld 1	FFh
	Dank U	Bank T	
Unimp	plemented data me	mory locations, r	ead as '0'.
Note 1:	Not a physical re	egister.	

FIGURE 4-5:

DATA MEMORY MAP FOR THE PIC16C622

File Address	3		File Address
00h	INDF ⁽¹⁾	INDF ⁽¹⁾	80h
01h	TMR0	OPTION	81h
02h	PCL	PCL	82h
03h	STATUS	STATUS	83h
04h	FSR	FSR	84h
05h	PORTA	TRISA	85h
06h	PORTB	TRISB	86h
07h			87h
08h			88h
09h			89h
0Ah	PCLATH	PCLATH	8Ah
0Bh	INTCON	INTCON	8Bh
0Ch	PIR1	PIE1	8Ch
0Dh			8Dh
0Eh		PCON	8Eh
0Fh			8Fh
10h			90h
11h			91h
12h			92h
13h			93h
14h			94h
15h			95h
16h			96h
17h			97h
18h			98h
19h			99h
1Ah			9Ah
1Bh			9Bh
1Ch			9Ch
1Dh			9Dh
1Eh			9Eh
1Fh	CMCON	VRCON	9Fh
20h			A0h
	General	General	7.011
	Purpose Register	Purpose Register	
	rtogiotor	rtogiotor	BFh
			C0h
7Fh			FFh
,,,,,	Bank 0	Bank 1	
Unimp	plemented data me	mory locations, re	ead as '0'.
Note 1:	Not a physical m	aistor	
NOLE T:	not a physical re	ะษารเษา.	

4.2.2.3 INTCON Register

The INTCON register is a readable and writable register, which contains the various enable and flag bits for all interrupt sources except the comparator module. See Section 4.2.2.4 and Section 4.2.2.5 for a description of the comparator enable and flag bits.

Note: Interrupt flag bits get set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE (INTCON<7>).

	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF
	bit 7			<u>.</u>		<u>.</u>		bit 0
bit 7	GIE: Globa	I Interrupt E	nable bit					
	1 = Enables	s all un-mas	sked interrup	ots				
1.11.0		s all interru	pts					
0 110	PEIE: Perip		upt Enable i	DIT 	-			
	1 = Enables 0 = Disable	s all un-mas	sked periphe eral interrun	eral interrupt	S			
bit 5		0 Overflow	Interrunt En	able bit				
bit o	1 = Enables	s the TMR0	interrupt					
	0 = Disable	s the TMR) interrupt					
bit 4	INTE: RB0/	INT Externa	al Interrupt E	Enable bit				
	1 = Enables	s the RB0/I	NT external	interrupt				
	0 = Disable	s the RB0/I	NT external	interrupt				
bit 3	RBIE: RB F	ort Change	Interrupt E	nable bit				
	1 = Enables	s the RB po	rt change in	iterrupt				
L:4 0			oft change in	iterrupi				
DIL ∠		J OVernow i		g Dit	- ared in coff	+		
	1 = TMR0 r 0 = TMR0 r	register did	not overflow	(ที่มีประ มีฮ มีฮ /	aleu ili son	ware		
bit 1	INTF: RB0/	INT Externa	al Interrupt F	-lag bit				
	1 = The RB	30/INT exter	nal interrup	t occurred (n	nust be clea	ared in softw	are)	
	0 = The RB	30/INT exter	nal interrupt	t did not occ	ur			
bit 0	RBIF : RB F	ort Change	Interrupt Fl	lag bit				
	1 = When a	at least one	of the RB<7	':4> pins cha	anged state	(must be cle	ared in soft	ware)
	0 = None o	f the RB<1	4> pins nave	e changea s	tate			
	Larandi							
	Legend:							

REGISTER 4-3:	INTCON REGISTER (ADDRESS 0BH OR 8BH)	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented	bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

4.2.2.6 PCON Register

The PCON register contains flag bits to differentiate between a Power-on Reset, an external MCLR Reset, WDT Reset or a Brown-out Reset.

Note:	BOR is unknown on Power-on Reset. It
	must then be set by the user and checked
	on subsequent RESETS to see if BOR is
	cleared, indicating a brown-out has
	occurred. The $\overline{\text{BOR}}$ STATUS bit is a "don't
	care" and is not necessarily predictable if
	the brown-out circuit is disabled (by
	programming BODEN bit in the
	Configuration word).

REGISTER 4-6: PCON REGISTER (ADDRESS 8Eh)

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	POR	BOR
bit 7							bit 0

bit 7-2 Unimplemented: Read as '0'

bit 1 **POR**: Power-on Reset STATUS bit

- 1 = No Power-on Reset occurred
- 0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

bit 0 **BOR**: Brown-out Reset STATUS bit

1 = No Brown-out Reset occurred

0 = A Brown-out Reset occurred (must be set in software after a Brown-out Reset occurs)

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented	bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

5.2 PORTB and TRISB Registers

PORTB is an 8-bit wide, bi-directional port. The corresponding data direction register is TRISB. A '1' in the TRISB register puts the corresponding output driver in a High Impedance mode. A '0' in the TRISB register puts the contents of the output latch on the selected pin(s).

Reading PORTB register reads the status of the pins, whereas writing to it will write to the port latch. All write operations are read-modify-write operations. So a write to a port implies that the port pins are first read, then this value is modified and written to the port data latch.

Each of the PORTB pins has a weak internal pull-up ($\approx 200 \ \mu A \ typical$). A single control bit can turn on all the pull-ups. This is done by clearing the RBPU (OPTION<7>) bit. The weak pull-up is automatically turned off when the port pin is configured as an output. The pull-ups are disabled on Power-on Reset.

Four of PORTB's pins, RB<7:4>, have an interrupt on change feature. Only pins configured as inputs can cause this interrupt to occur (e.g., any RB<7:4> pin configured as an output is excluded from the interrupt on change comparison). The input pins (of RB<7:4>) are compared with the old value latched on the last read of PORTB. The "mismatch" outputs of RB<7:4> are OR'ed together to generate the RBIF interrupt (flag latched in INTCON<0>).

FIGURE 5-5: BLOCK DIAGRAM OF RB<7:4> PINS



This interrupt can wake the device from SLEEP. The user, in the interrupt service routine, can clear the interrupt in the following manner:

- a) Any read or write of PORTB. This will end the mismatch condition.
- b) Clear flag bit RBIF.

A mismatch condition will continue to set flag bit RBIF. Reading PORTB will end the mismatch condition and allow flag bit RBIF to be cleared.

This interrupt on mismatch feature, together with software configurable pull-ups on these four pins allow easy interface to a key pad and make it possible for wake-up on key-depression. (See AN552, "Implementing Wake-Up on Key Strokes.)

Note:	If a change on the I/O pin should occur
	when the read operation is being executed
	(start of the Q2 cycle), then the RBIF inter-
	rupt flag may not get set.

The interrupt-on-change feature is recommended for wake-up on key depression operation and operations where PORTB is only used for the interrupt on change feature. Polling of PORTB is not recommended while using the interrupt-on-change feature.





6.0 TIMER0 MODULE

The Timer0 module timer/counter has the following features:

- 8-bit timer/counter
- Readable and writable
- 8-bit software programmable prescaler
- · Internal or external clock select
- · Interrupt on overflow from FFh to 00h
- · Edge select for external clock

Figure 6-1 is a simplified block diagram of the Timer0 module.

Timer mode is selected by clearing the T0CS bit (OPTION<5>). In Timer mode, the TMR0 will increment every instruction cycle (without prescaler). If Timer0 is written, the increment is inhibited for the following two cycles (Figure 6-2 and Figure 6-3). The user can work around this by writing an adjusted value to TMR0.

Counter mode is selected by setting the T0CS bit. In this mode, Timer0 will increment either on every rising or falling edge of pin RA4/T0CKI. The incrementing edge is determined by the source edge (T0SE) control bit (OPTION<4>). Clearing the T0SE bit selects the rising edge. Restrictions on the external clock input are discussed in detail in Section 6.2.

The prescaler is shared between the Timer0 module and the Watchdog Timer. The prescaler assignment is controlled in software by the control bit PSA (OPTION<3>). Clearing the PSA bit will assign the prescaler to Timer0. The prescaler is not readable or writable. When the prescaler is assigned to the Timer0 module, prescale value of 1:2, 1:4, ..., 1:256 are selectable. Section 6.3 details the operation of the prescaler.

6.1 TIMER0 Interrupt

Timer0 interrupt is generated when the TMR0 register timer/counter overflows from FFh to 00h. This overflow sets the T0IF bit. The interrupt can be masked by clearing the T0IE bit (INTCON<5>). The T0IF bit (INTCON<2>) must be cleared in software by the Timer0 module interrupt service routine before reenabling this interrupt. The Timer0 interrupt cannot wake the processor from SLEEP, since the timer is shut off during SLEEP. See Figure 6-4 for Timer0 interrupt timing.



FIGURE 6-2: TIMER0 (TMR0) TIMING: INTERNAL CLOCK/NO PRESCALER

Counter)	(PC-1	X PC	(PC+1)	PC+2	PC+3	PC+4	<u>PC+5</u> χ	PC+6
Instruction Fetch	1 1 1	MOVWF TMR	0MOVF TMR0,V	MOVF TMR0,V	MOVF TMR0,W	MOVF TMR0,V	MOVF TMR0,W	I
TMR0	T0 X	T0+1)	T0+2	I	NT0		NT0+1 \	NT0+2 \
Instruction	1 1 1	1 1 1	≜	≜	1	≜	↑	≜
Executed	1	1	Write TMR0	Read TMR0	Read TMR0	Read TMR0	Read TMR0	Read TMR0

6.3 Prescaler

An 8-bit counter is available as a prescaler for the Timer0 module, or as a postscaler for the Watchdog Timer, respectively (Figure 6-6). For simplicity, this counter is being referred to as "prescaler" throughout this data sheet. Note that there is only one prescaler available which is mutually exclusive between the Timer0 module and the Watchdog Timer. Thus, a prescaler assignment for the Timer0 module means that there is no prescaler for the Watchdog Timer and vice-versa.

The PSA and PS<2:0> bits (OPTION<3:0>) determine the prescaler assignment and prescale ratio.

When assigned to the Timer0 module, all instructions writing to the TMR0 register (e.g., CLRF 1, MOVWF 1, BSF 1, x....etc.) will clear the prescaler. When assigned to WDT, a CLRWDT instruction will clear the prescaler along with the Watchdog Timer. The prescaler is not readable or writable.



FIGURE 6-6: BLOCK DIAGRAM OF THE TIMER0/WDT PRESCALER

9.3 RESET

The PIC16C62X differentiates between various kinds of RESET:

- a) Power-on Reset (POR)
- b) MCLR Reset during normal operation
- c) MCLR Reset during SLEEP
- d) WDT Reset (normal operation)
- e) WDT wake-up (SLEEP)
- f) Brown-out Reset (BOR)

Some registers are not affected in any RESET condition Their status is unknown on POR and unchanged in any other RESET. Most other registers are reset to a "RESET state" on Power-on Reset,

MCLR Reset, WDT Reset and MCLR Reset during SLEEP. They are not affected by a WDT wake-up, since this is viewed as the resumption of normal operation. TO and PD bits are set or cleared differently in different RESET situations as indicated in Table 9-2. These bits are used in software to determine the nature of the RESET. See Table 9-5 for a full description of RESET states of all registers.

A simplified block diagram of the on-chip RESET circuit is shown in Figure 9-6.

The $\overline{\text{MCLR}}$ Reset path has a noise filter to detect and ignore small pulses. See Table 12-5 for pulse width specification.





PIC16C62X

NOTES:

11.14 PICDEM 1 PICmicro Demonstration Board

The PICDEM 1 demonstration board demonstrates the capabilities of the PIC16C5X (PIC16C54 to PIC16C58A), PIC16C61, PIC16C62X, PIC16C71, PIC16C8X, PIC17C42, PIC17C43 and PIC17C44. All necessary hardware and software is included to run basic demo programs. The sample microcontrollers provided with the PICDEM 1 demonstration board can be programmed with a PRO MATE II device programmer, or a PICSTART Plus development programmer. The PICDEM 1 demonstration board can be connected to the MPLAB ICE in-circuit emulator for testing. A prototype area extends the circuitry for additional application components. Features include analog input, push button switches and eight LEDs.

11.15 PICDEM.net Internet/Ethernet Demonstration Board

The PICDEM.net demonstration board is an Internet/ Ethernet demonstration board using the PIC18F452 microcontroller and TCP/IP firmware. The board supports any 40-pin DIP device that conforms to the standard pinout used by the PIC16F877 or PIC18C452. This kit features a user friendly TCP/IP stack, web server with HTML, a 24L256 Serial EEPROM for Xmodem download to web pages into Serial EEPROM, ICSP/MPLAB ICD 2 interface connector, an Ethernet interface, RS-232 interface, and a 16 x 2 LCD display. Also included is the book and CD-ROM *"TCP/IP Lean, Web Servers for Embedded Systems,"* by Jeremy Bentham

11.16 PICDEM 2 Plus Demonstration Board

The PICDEM 2 Plus demonstration board supports many 18-, 28-, and 40-pin microcontrollers, including PIC16F87X and PIC18FXX2 devices. All the necessary hardware and software is included to run the demonstration programs. The sample microcontrollers provided with the PICDEM 2 demonstration board can be programmed with a PRO MATE II device programmer, PICSTART Plus development programmer, or MPLAB ICD 2 with a Universal Programmer Adapter. The MPLAB ICD 2 and MPLAB ICE in-circuit emulators may also be used with the PICDEM 2 demonstration board to test firmware. A prototype area extends the circuitry for additional application components. Some of the features include an RS-232 interface, a 2 x 16 LCD display, a piezo speaker, an on-board temperature sensor, four LEDs, and sample PIC18F452 and PIC16F877 FLASH microcontrollers.

11.17 PICDEM 3 PIC16C92X Demonstration Board

The PICDEM 3 demonstration board supports the PIC16C923 and PIC16C924 in the PLCC package. All the necessary hardware and software is included to run the demonstration programs.

11.18 PICDEM 4 8/14/18-Pin Demonstration Board

The PICDEM 4 can be used to demonstrate the capabilities of the 8-, 14-, and 18-pin PIC16XXXX and PIC18XXXX MCUs, including the PIC16F818/819, PIC16F87/88, PIC16F62XA and the PIC18F1320 family of microcontrollers. PICDEM 4 is intended to showcase the many features of these low pin count parts, including LIN and Motor Control using ECCP. Special provisions are made for low power operation with the supercapacitor circuit, and jumpers allow onboard hardware to be disabled to eliminate current draw in this mode. Included on the demo board are provisions for Crystal, RC or Canned Oscillator modes, a five volt regulator for use with a nine volt wall adapter or battery, DB-9 RS-232 interface, ICD connector for programming via ICSP and development with MPLAB ICD 2, 2x16 liquid crystal display, PCB footprints for H-Bridge motor driver, LIN transceiver and EEPROM. Also included are: header for expansion, eight LEDs, four potentiometers, three push buttons and a prototyping area. Included with the kit is a PIC16F627A and a PIC18F1320. Tutorial firmware is included along with the User's Guide.

11.19 PICDEM 17 Demonstration Board

The PICDEM 17 demonstration board is an evaluation board that demonstrates the capabilities of several Microchip microcontrollers, including PIC17C752, PIC17C756A, PIC17C762 and PIC17C766. A programmed sample is included. The PRO MATE II device programmer, or the PICSTART Plus development programmer, can be used to reprogram the device for user tailored application development. The PICDEM 17 demonstration board supports program download and execution from external on-board FLASH memory. A generous prototype area is available for user hardware expansion.

PIC16C62X





2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.





PIC16C62X





TABLE 12-1: COMPARATOR SPECIFICATIONS

Operating Conditions: VDD range as described in Table 12-1, -40°C<TA<+125°C. Current consumption is specified in Table 12-1.

Characteristics	Sym	Min	Тур	Мах	Units	Comments
Input offset voltage			± 5.0	± 10	mV	
Input common mode voltage		0		Vdd - 1.5	V	
CMRR		+55*			δβ	
Response Time ⁽¹⁾			150*	400* 600*	ns ns	PIC16C62X(A) PIC16LC62X
Comparator mode change to output valid				10*	μS	

* These parameters are characterized but not tested.

Note 1: Response time measured with one comparator input at (VDD - 1.5)/2, while the other input transitions from Vss to VDD.

TABLE 12-2: VOLTAGE REFERENCE SPECIFICATIONS

Operating Conditions:VDD range as described in Table 12-1, -40°C<TA<+125°C. Current consumption is specified in Table 12-1.

Characteristics	Sym	Min	Тур	Мах	Units	Comments		
Resolution			VDD/24 VDD/32		LSB LSB	Low Range (VRR=1) High Range (VRR=0)		
Absolute Accuracy				<u>+</u> 1/4 <u>+</u> 1/2	LSB LSB	Low Range (VRR=1) High Range (VRR=0)		
Unit Resistor Value (R)			2K*		Ω	Figure 8-1		
Settling Time ⁽¹⁾				10*	μs			
* These parameters are characterized but not tested. Note 1: Settling time measured while VRR = 1 and VR<3:0> transitions from 0000 to 1111.								

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13.0 DEVICE CHARACTERIZATION INFORMATION

The graphs and tables provided in this section are for design guidance and are not tested. In some graphs or tables, the data presented is outside specified operating range (e.g., outside specified VDD range). This is for information only and devices will operate properly only within the specified range.

The data presented in this section is a statistical summary of data collected on units from different lots over a period of time. "Typical" represents the mean of the distribution, while "max" or "min" represents (mean + 3σ) and (mean - 3σ) respectively, where σ is standard deviation.



FIGURE 13-1: IDD VS. FREQUENCY (XT MODE, VDD = 5.5V)

FIGURE 13-2: PIC16C622A IPD VS. VDD (WDT DISABLE)



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14.0 PACKAGING INFORMATION

18-Lead Ceramic Dual In-line with Window (JW) – 300 mil (CERDIP)



	Units		INCHES*		MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX	MIN	NOM	MAX	
Number of Pins	n		18			18		
Pitch	р		.100			2.54		
Top to Seating Plane	А	.170	.183	.195	4.32	4.64	4.95	
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19	
Standoff	A1	.015	.023	.030	0.38	0.57	0.76	
Shoulder to Shoulder Width	E	.300	.313	.325	7.62	7.94	8.26	
Ceramic Pkg. Width	E1	.285	.290	.295	7.24	7.37	7.49	
Overall Length	D	.880	.900	.920	22.35	22.86	23.37	
Tip to Seating Plane	L	.125	.138	.150	3.18	3.49	3.81	
Lead Thickness	С	.008	.010	.012	0.20	0.25	0.30	
Upper Lead Width	B1	.050	.055	.060	1.27	1.40	1.52	
Lower Lead Width	В	.016	.019	.021	0.41	0.47	0.53	
Overall Row Spacing §	eB	.345	.385	.425	8.76	9.78	10.80	
Window Width	W1	.130	.140	.150	3.30	3.56	3.81	
Window Length	W2	.190	.200	.210	4.83	5.08	5.33	

* Controlling Parameter
 § Significant Characteristic
 JEDEC Equivalent: MO-036
 Drawing No. C04-010

18-Lead Plastic Dual In-line (P) – 300 mil (PDIP)



	Units	INCHES*			MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX	MIN	NOM	MAX	
Number of Pins	n		18			18		
Pitch	р		.100			2.54		
Top to Seating Plane	Α	.140	.155	.170	3.56	3.94	4.32	
Molded Package Thickness	A2	.115	.130	.145	2.92	3.30	3.68	
Base to Seating Plane	A1	.015			0.38			
Shoulder to Shoulder Width	E	.300	.313	.325	7.62	7.94	8.26	
Molded Package Width	E1	.240	.250	.260	6.10	6.35	6.60	
Overall Length	D	.890	.898	.905	22.61	22.80	22.99	
Tip to Seating Plane	L	.125	.130	.135	3.18	3.30	3.43	
Lead Thickness	С	.008	.012	.015	0.20	0.29	0.38	
Upper Lead Width	B1	.045	.058	.070	1.14	1.46	1.78	
Lower Lead Width	В	.014	.018	.022	0.36	0.46	0.56	
Overall Row Spacing §	eB	.310	.370	.430	7.87	9.40	10.92	
Mold Draft Angle Top	α	5	10	15	5	10	15	
Mold Draft Angle Bottom	β	5	10	15	5	10	15	

* Controlling Parameter § Significant Characteristic

Notes:

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side. JEDEC Equivalent: MS-001 Drawing No. C04-007

PIC16C62X

NOTES:

APPENDIX A: ENHANCEMENTS

The following are the list of enhancements over the PIC16C5X microcontroller family:

- Instruction word length is increased to 14 bits. This allows larger page sizes both in program memory (4K now as opposed to 512 before) and register file (up to 128 bytes now versus 32 bytes before).
- 2. A PC high latch register (PCLATH) is added to handle program memory paging. PA2, PA1, PA0 bits are removed from STATUS register.
- 3. Data memory paging is slightly redefined. STATUS register is modified.
- Four new instructions have been added: RETURN, RETFIE, ADDLW, and SUBLW.
 Two instructions TRIS and OPTION are being phased out, although they are kept for compatibility with PIC16C5X.
- 5. OPTION and TRIS registers are made addressable.
- 6. Interrupt capability is added. Interrupt vector is at 0004h.
- 7. Stack size is increased to 8 deep.
- 8. RESET vector is changed to 0000h.
- RESET of all registers is revisited. Five different RESET (and wake-up) types are recognized. Registers are reset differently.
- 10. Wake-up from SLEEP through interrupt is added.
- 11. Two separate timers, Oscillator Start-up Timer (OST) and Power-up Timer (PWRT) are included for more reliable power-up. These timers are invoked selectively to avoid unnecessary delays on power-up and wake-up.
- 12. PORTB has weak pull-ups and interrupt-onchange feature.
- 13. Timer0 clock input, T0CKI pin is also a port pin (RA4/T0CKI) and has a TRIS bit.
- 14. FSR is made a full 8-bit register.
- 15. "In-circuit programming" is made possible. The user can program PIC16CXX devices using only five pins: VDD, VSS, VPP, RB6 (clock) and RB7 (data in/out).
- PCON STATUS register is added with a Poweron-Reset (POR) STATUS bit and a Brown-out Reset STATUS bit (BOD).
- 17. Code protection scheme is enhanced such that portions of the program memory can be protected, while the remainder is unprotected.
- 18. PORTA inputs are now Schmitt Trigger inputs.
- 19. Brown-out Reset reset has been added.
- 20. Common RAM registers F0h-FFh implemented in bank1.

APPENDIX B: COMPATIBILITY

To convert code written for PIC16C5X to PIC16CXX, the user should take the following steps:

- 1. Remove any program memory page select operations (PA2, PA1, PA0 bits) for CALL, GOTO.
- 2. Revisit any computed jump operations (write to PC or add to PC, etc.) to make sure page bits are set properly under the new scheme.
- 3. Eliminate any data memory page switching. Redefine data variables to reallocate them.
- 4. Verify all writes to STATUS, OPTION, and FSR registers since these have changed.
- 5. Change RESET vector to 0000h.



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