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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of **Embedded - Microprocessors**

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

E·XFI

Product Status	Active
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	133MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (2)
SATA	-
USB	USB 2.0 (1)
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 95°C (TA)
Security Features	Cryptography
Package / Case	256-BBGA
Supplier Device Package	256-PBGA (23x23)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mpc870zt133

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



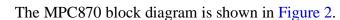
- Thirty-two address lines
- Memory controller (eight banks)
 - Contains complete dynamic RAM (DRAM) controller
 - Each bank can be a chip select or \overline{RAS} to support a DRAM bank
 - Up to 30 wait states programmable per memory bank
 - Glueless interface to DRAM, SIMMS, SRAM, EPROMs, Flash EPROMs, and other memory devices
 - DRAM controller programmable to support most size and speed memory interfaces
 - Four \overline{CAS} lines, four \overline{WE} lines, and one \overline{OE} line
 - Boot chip-select available at reset (options for 8-, 16-, or 32-bit memory)
 - Variable block sizes (32 Kbytes–256 Mbytes)
 - Selectable write protection
 - On-chip bus arbitration logic
- General-purpose timers
 - Four 16-bit timers or two 32-bit timers
 - Gate mode can enable/disable counting
 - Interrupt can be masked on reference match and event capture
- Two Fast Ethernet controllers (FEC)—Two 10/100 Mbps Ethernet/IEEE Std. 802.3® CDMA/CS that interface through MII and/or RMII interfaces
- System integration unit (SIU)
 - Bus monitor
 - Software watchdog
 - Periodic interrupt timer (PIT)
 - Clock synthesizer
 - Decrementer and time base
 - Reset controller
 - IEEE 1149.1[™] Std. test access port (JTAG)
- Security engine is optimized to handle all the algorithms associated with IPsec, SSL/TLS, SRTP, IEEE 802.11i® standard, and iSCSI processing. Available on the MPC875, the security engine contains a crypto-channel, a controller, and a set of crypto hardware accelerators (CHAs). The CHAs are:
 - Data encryption standard execution unit (DEU)
 - DES, 3DES
 - Two key (K1, K2, K1) or three key (K1, K2, K3)
 - ECB and CBC modes for both DES and 3DES
 - Advanced encryption standard unit (AESU)
 - Implements the Rijndael symmetric key cipher



Features

- ECB, CBC, and counter modes
- 128-, 192-, and 256-bit key lengths
- Message digest execution unit (MDEU)
 - SHA with 160- or 256-bit message digest
 - MD5 with 128-bit message digest
 - HMAC with either algorithm
- Master/slave logic, with DMA
 - 32-bit address/32-bit data
 - Operation at MPC8xx bus frequency
- Crypto-channel supporting multi-command descriptors
 - Integrated controller managing crypto-execution units
 - Buffer size of 256 bytes for each execution unit, with flow control for large data sizes
- Interrupts
 - Six external interrupt request (IRQ) lines
 - Twelve port pins with interrupt capability
 - Twenty-three internal interrupt sources
 - Programmable priority between SCCs
 - Programmable highest priority request
- Communications processor module (CPM)
 - RISC controller
 - Communication-specific commands (for example, GRACEFUL STOP TRANSMIT, ENTER HUNT MODE, and RESTART TRANSMIT)
 - Supports continuous mode transmission and reception on all serial channels
 - 8-Kbytes of dual-port RAM
 - Several serial DMA (SDMA) channels to support the CPM
 - Three parallel I/O registers with open-drain capability
- On-chip 16×16 multiply accumulate controller (MAC)
 - One operation per clock (two-clock latency, one-clock blockage)
 - MAC operates concurrently with other instructions
 - FIR loop—Four clocks per four multiplies
- Four baud-rate generators
 - Independent (can be connected to SCC or SMC)
 - Allows changes during operation
 - Autobaud support option
- SCC (serial communication controller)
 - Ethernet/IEEE 802.3® standard, supporting full 10-Mbps operation
 - HDLC/SDLC





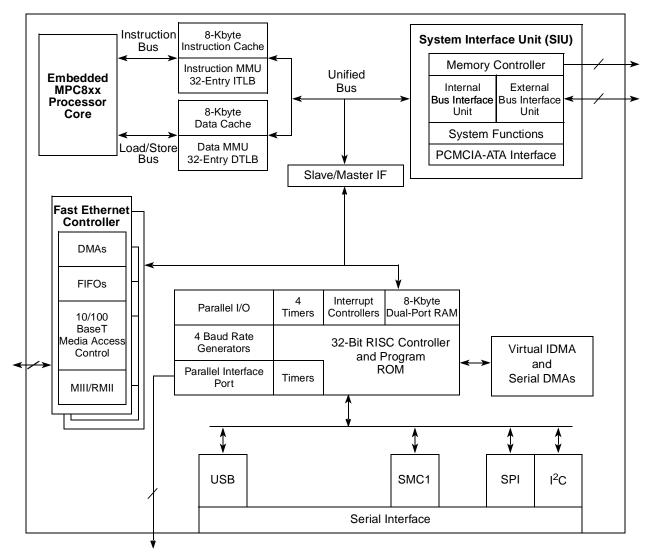


Figure 2. MPC870 Block Diagram





3 Maximum Tolerated Ratings

This section provides the maximum tolerated voltage and temperature ranges for the MPC875/MPC870. Table 2 displays the maximum tolerated ratings and Table 3 displays the operating temperatures.

Rating	Symbol	Value	Unit
Supply voltage ¹	V _{DDL} (core voltage)	-0.3 to 3.4	V
	V _{DDH} (I/O voltage)	-0.3 to 4	V
	V _{DDSYN}	-0.3 to 3.4	V
	Difference between V_{DDL} and V_{DDSYN}	<100	mV
Input voltage ²	V _{in}	$\ensuremath{GND}\xspace - 0.3$ to $\ensuremath{V}\xspace_{\ensuremath{DDH}\xspace}$	V
Storage temperature range	T _{stg}	–55 to +150	°C

Table 2. Maximum Tolerated Ratings

¹ The power supply of the device must start its ramp from 0.0 V.

² Functional operating conditions are provided with the DC electrical specifications in Table 6. Absolute maximum ratings are stress ratings only; functional operation at the maxima is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage to the device.

Caution: All inputs that tolerate 5 V cannot be more than 2.5 V greater than V_{DDH}. This restriction applies to power up and normal operation (that is, if the MPC875/MPC870 is unpowered, a voltage greater than 2.5 V must not be applied to its inputs).

Figure 3 shows the undershoot and overshoot voltages at the interfaces of the MPC875/MPC870.

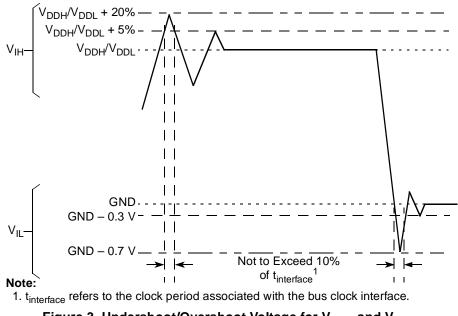


Figure 3. Undershoot/Overshoot Voltage for V_{DDH} and V_{DDL}



11 Bus Signal Timing

The maximum bus speed supported by the MPC875/MPC870 is 80 MHz. Higher-speed parts must be operated in half-speed bus mode (for example, an MPC875/MPC870 used at 133 MHz must be configured for a 66 MHz bus). Table 8 shows the frequency ranges for standard part frequencies in 1:1 bus mode, and Table 9 shows the frequency ranges for standard part frequencies in 2:1 bus mode.

Part Frequency	66 I	MHz	80 MHz		
Tart requency	Min	Мах	Min	Мах	
Core frequency	40	66.67	40	80	
Bus frequency	40	66.67	40	80	

Table 8. Frequency Ranges for Standard Part Frequencies (1:1 Bus Mode)

Table 9. Frequency Ranges for Standard Part Frequencies (2:1 Bus Mode)

Part Frequency	66 I	MHz	80	MHz	133 MHz	
Fait i requeitcy	Min	Max	Min	Мах	Min	Max
Core frequency	40	66.67	40	80	40	133
Bus frequency	20	33.33	20	40	20	66

Table 10 provides the bus operation timing for the MPC875/MPC870 at 33, 40, 66, and 80 MHz.

The timing for the MPC875/MPC870 bus shown Table 10, assumes a 50-pF load for maximum delays and a 0-pF load for minimum delays. CLKOUT assumes a 100-pF load maximum delay

Table 10. Bus Operation Timings

Num	Characteristic	33 MHz		40 MHz		66 MHz		80 MHz		Unit
Num	Characteristic	Min	Мах	Min	Max	Min	Max	Min	Max	Omt
B1	Bus period (CLKOUT), see Table 8	_	_	—	—	_		—	—	ns
B1a	EXTCLK to CLKOUT phase skew—If CLKOUT is an integer multiple of EXTCLK, then the rising edge of EXTCLK is aligned with the rising edge of CLKOUT. For a non-integer multiple of EXTCLK, this synchronization is lost, and the rising edges of EXTCLK and CLKOUT have a continuously varying phase skew.	-2	+2	-2	+2	-2	+2	-2	+2	ns
B1b	CLKOUT frequency jitter peak-to-peak	_	1	_	1		1	_	1	ns
B1c	Frequency jitter on EXTCLK	_	0.50	_	0.50	_	0.50	_	0.50	%
B1d	CLKOUT phase jitter peak-to-peak for OSCLK \ge 15 MHz		4	—	4		4	—	4	ns
	CLKOUT phase jitter peak-to-peak for OSCLK < 15 MHz		5		5		5		5	ns



Nivues	Characteristic	33 MHz 40		40) MHz 66		66 MHz 80		MHz	11
Num	Characteristic	Min	Max	Min	Мах	Min	Max	Min	Мах	Unit
B15	CLKOUT to $\overline{\text{TEA}}$ High-Z (MIN = 0.00 × B1 + 2.50)	2.50	15.00	2.50	15.00	2.50	15.00	2.50	15.00	ns
B16	$\overline{\text{TA}}$, $\overline{\text{BI}}$ valid to CLKOUT (setup time) (MIN = 0.00 × B1 + 6.00)	6.00		6.00	_	6.00	_	6	_	ns
B16a	TEA, $\overline{\text{KR}}$, $\overline{\text{RETRY}}$, $\overline{\text{CR}}$ valid to CLKOUT (setup time) (MIN = 0.00 × B1 + 4.5)	4.50	—	4.50	—	4.50	—	4.50	—	ns
B16b	\overline{BB} , \overline{BG} , \overline{BR} , valid to CLKOUT (setup time) ² (4MIN = 0.00 × B1 + 0.00)	4.00	—	4.00	—	4.00	—	4.00	—	ns
B17	CLKOUT to \overline{TA} , \overline{TEA} , \overline{BI} , \overline{BB} , \overline{BG} , \overline{BR} valid (hold time) (MIN = 0.00 × B1 + 1.00 ³)	1.00	—	1.00	—	2.00	—	2.00	—	ns
B17a	CLKOUT to $\overline{\text{KR}}$, $\overline{\text{RETRY}}$, $\overline{\text{CR}}$ valid (hold time) (MIN = 0.00 × B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns
B18	D(0:31) valid to CLKOUT rising edge (setup time) ⁴ (MIN = $0.00 \times B1 + 6.00$)	6.00	—	6.00	—	6.00	—	6.00	—	ns
B19	CLKOUT rising edge to D(0:31) valid (hold time) ⁴ (MIN = $0.00 \times B1 + 1.00^5$)	1.00		1.00	_	2.00	_	2.00	—	ns
B20	D(0:31) valid to CLKOUT falling edge (setup time) ⁶ (MIN = $0.00 \times B1 + 4.00$)	4.00	_	4.00	—	4.00	_	4.00	—	ns
B21	CLKOUT falling edge to D(0:31) valid (hold time) ⁶ (MIN = $0.00 \times B1 + 2.00$)	2.00	_	2.00	—	2.00	—	2.00	—	ns
B22	CLKOUT rising edge to \overline{CS} asserted GPCM ACS = 00 (MAX = 0.25 × B1 + 6.3)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.43	ns
B22a	CLKOUT falling edge to \overline{CS} asserted GPCM ACS = 10, TRLX = 0 (MAX = 0.00 × B1 + 8.00)	_	8.00	—	8.00		8.00	—	8.00	ns
B22b	CLKOUT falling edge to \overline{CS} asserted GPCM ACS = 11, TRLX = 0, EBDF = 0 (MAX = 0.25 × B1 + 6.3)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.43	ns
B22c	CLKOUT falling edge to \overline{CS} asserted GPCM ACS = 11, TRLX = 0, EBDF = 1 (MAX = 0.375 × B1 + 6.6)	10.90	18.00	10.90	16.00	5.20	12.30	4.69	10.93	ns
B23	CLKOUT rising edge to \overline{CS} negated GPCM read access, GPCM write access ACS = 00, TRLX = 0 and CSNT = 0 (MAX = 0.00 × B1 + 8.00)	2.00	8.00	2.00	8.00	2.00	8.00	2.00	8.00	ns
B24	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 10, TRLX = 0 (MIN = $0.25 \times B1 - 2.00$)	5.60	_	4.30	—	1.80	—	1.13	—	ns
B24a	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 11, TRLX = 0 (MIN = 0.50 × B1 - 2.00)	13.20		10.50	—	5.60	—	4.25	—	ns

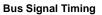
Table 10. Bus Operation Timings (continued)



Bus Signal Timing

Num	Characteristic	33	MHz	40 1	MHz	66 I	MHz	80	MHz	Unit
NUM	Characteristic	Min	Max	Min	Мах	Min	Max	Min	Мах	Unit
B25	CLKOUT rising edge to \overline{OE} , $\overline{WE}(0:3)/BS_B[0:3]$ asserted (MAX = 0.00 × B1 + 9.00)		9.00		9.00		9.00	—	9.00	ns
B26	CLKOUT rising edge to \overline{OE} negated (MAX = 0.00 × B1 + 9.00)	2.00	9.00	2.00	9.00	2.00	9.00	2.00	9.00	ns
B27	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 10, TRLX = 1 (MIN = 1.25 × B1 - 2.00)	35.90	_	29.30		16.90	_	13.60		ns
B27a	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 11, TRLX = 1 (MIN = 1.50 × B1 – 2.00)	43.50	—	35.50	—	20.70	—	16.75		ns
B28	CLKOUT rising edge to $\overline{WE}(0:3)/BS_B[0:3]$ negated GPCM write access CSNT = 0 (MAX = 0.00 × B1 + 9.00)		9.00		9.00	—	9.00		9.00	ns
B28a	CLKOUT falling edge to $\overline{WE}(0:3)/BS_B[0:3]$ negated GPCM write access TRLX = 0, CSNT = 1, EBDF = 0 (MAX = 0.25 × B1 + 6.80)	7.60	14.30	6.30	13.00	3.80	10.50	3.13	9.93	ns
B28b	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0, CSNT = 1 ACS = 10 or ACS = 11, EBDF = 0 (MAX = 0.25 × B1 + 6.80)	_	14.30	_	13.00	_	10.50	_	9.93	ns
B28c	CLKOUT falling edge to $\overline{WE}(0:3)/BS_B[0:3]$ negated GPCM write access TRLX = 0, CSNT = 1 write access TRLX = 0, CSNT = 1, EBDF = 1 (MAX = 0.375 × B1 + 6.6)	10.90	18.00	10.90	18.00	5.20	12.30	4.69	11.29	ns
B28d	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1 (MAX = 0.375 × B1 + 6.6)	_	18.00	_	18.00	_	12.30	_	11.30	ns
B29	$\overline{WE}(0:3)/BS_B[0:3]$ negated to D(0:31) High-Z GPCM write access, CSNT = 0, EBDF = 0 (MIN = 0.25 × B1 - 2.00)	5.60	—	4.30	—	1.80	_	1.13		ns
B29a	$\label{eq:weighted_states} \hline \hline WE(0:3)/BS_B[0:3] \mbox{ negated to } D(0:31) \mbox{ High-Z} \\ GPCM \mbox{ write access, } TRLX = 0, \mbox{ CSNT = 1,} \\ EBDF = 0 \mbox{ (MIN = } 0.50 \times B1 - 2.00) \\ \hline \hline \end{array}$	13.20	_	10.50	_	5.60	_	4.25	—	ns
B29b	\overline{CS} negated to D(0:31) High-Z GPCM write access, ACS = 00, TRLX = 0 and CSNT = 0 (MIN = 0.25 × B1 - 2.00)	5.60		4.30		1.80		1.13		ns
B29c	$\overline{\text{CS}}$ negated to D(0:31) High-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0 (MIN = 0.50 × B1 - 2.00)	13.20	_	10.50		5.60	_	4.25	—	ns

Table 10. Bus Operation Timings (continued)





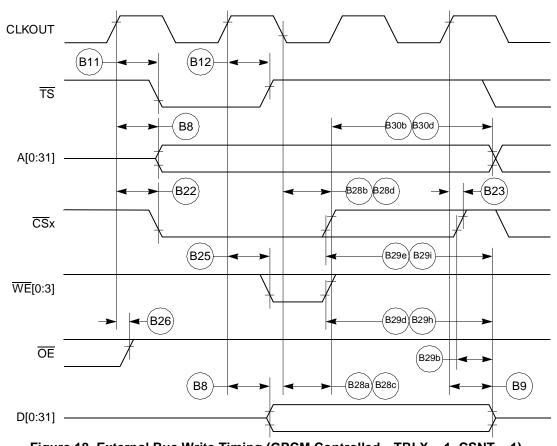


Figure 18. External Bus Write Timing (GPCM Controlled—TRLX = 1, CSNT = 1)



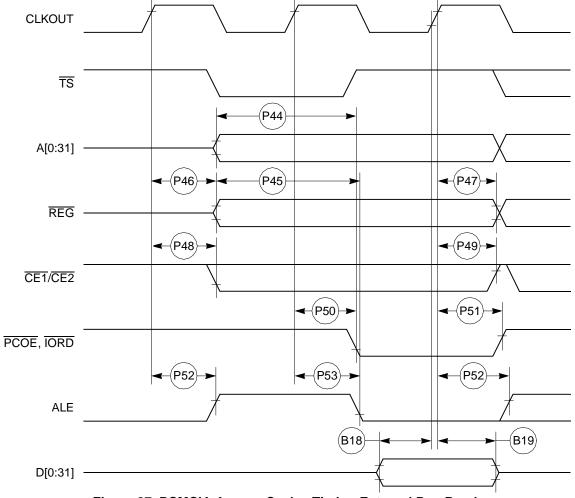


Figure 27 provides the PCMCIA access cycle timing for the external bus read.

Figure 27. PCMCIA Access Cycles Timing External Bus Read



Table 15 shows the reset timing for the MPC875/MPC870.

Table 15. Reset Timing

Nissia	Okenesterietie	33	MHz	40 1	MHz	66	MHz	80 MHz		Unit
Num	Characteristic	Min	Max	Min	Мах	Min	Max	Min	Max	Unit
R69	CLKOUT to $\overline{\text{HRESET}}$ high impedance (MAX = 0.00 × B1 + 20.00)	—	20.00	—	20.00	-	20.00	—	20.00	ns
R70	CLKOUT to $\overline{\text{SRESET}}$ high impedance (MAX = 0.00 × B1 + 20.00)	—	20.00	—	20.00	—	20.00	—	20.00	ns
R71	RSTCONF pulse width (MIN = 17.00 × B1)	515.20	—	425.00	—	257.60	—	212.50	_	ns
R72	_	_		_	_	—		_	_	—
R73	Configuration data to $\overline{\text{HRESET}}$ rising edge setup time (MIN = 15.00 × B1 + 50.00)	504.50	—	425.00	—	277.30	_	237.50	—	ns
R74	Configuration data to $\overrightarrow{\text{RSTCONF}}$ rising edge setup time (MIN = 0.00 × B1 + 350.00)	350.00	_	350.00	_	350.00	_	350.00	_	ns
R75	Configuration data hold time after $\overrightarrow{\text{RSTCONF}}$ negation (MIN = 0.00 × B1 + 0.00)	0.00		0.00		0.00		0.00	_	ns
R76	Configuration data hold time after HRESET negation (MIN = $0.00 \times B1 + 0.00$)	0.00	_	0.00	_	0.00		0.00		ns
R77	HRESET and RSTCONF asserted to data out drive (MAX = $0.00 \times B1 + 25.00$)	—	25.00	_	25.00	_	25.00	_	25.00	ns
R78	$\frac{RSTCONF}{RSTCONF} \text{ negated to data out high}$ impedance (MAX = 0.00 × B1 + 25.00)	—	25.00	-	25.00	-	25.00	-	25.00	ns
R79	CLKOUT of last rising edge before chip three-states $\overrightarrow{\text{HRESET}}$ to data out high impedance (MAX = 0.00 × B1 + 25.00)	—	25.00	—	25.00	—	25.00	—	25.00	ns
R80	DSDI, DSCK setup (MIN = $3.00 \times B1$)	90.90	_	75.00	_	45.50	—	37.50	_	ns
R81	DSDI, DSCK hold time (MIN = $0.00 \times B1 + 0.00$)	0.00	_	0.00	_	0.00		0.00	_	ns
R82	SRESET negated to CLKOUT rising edge for DSDI and DSCK sample (MIN = $8.00 \times B1$)	242.40	—	200.00	—	121.20	—	100.00	—	ns



Bus Signal Timing

Figure 34 shows the reset timing for the data bus configuration.

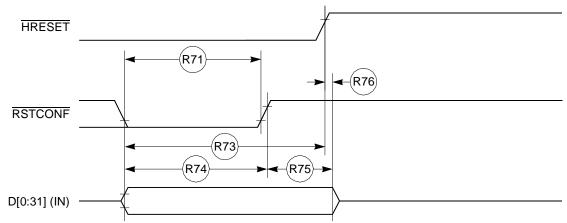
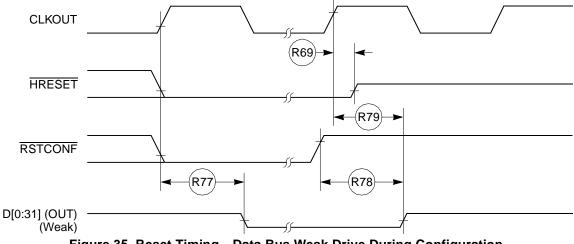




Figure 35 provides the reset timing for the data bus weak drive during configuration.



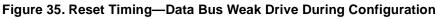
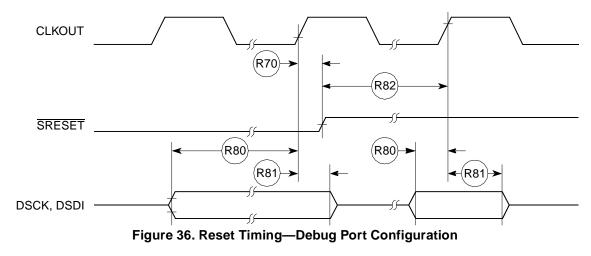


Figure 36 provides the reset timing for the debug port configuration.





CPM Electrical Characteristics

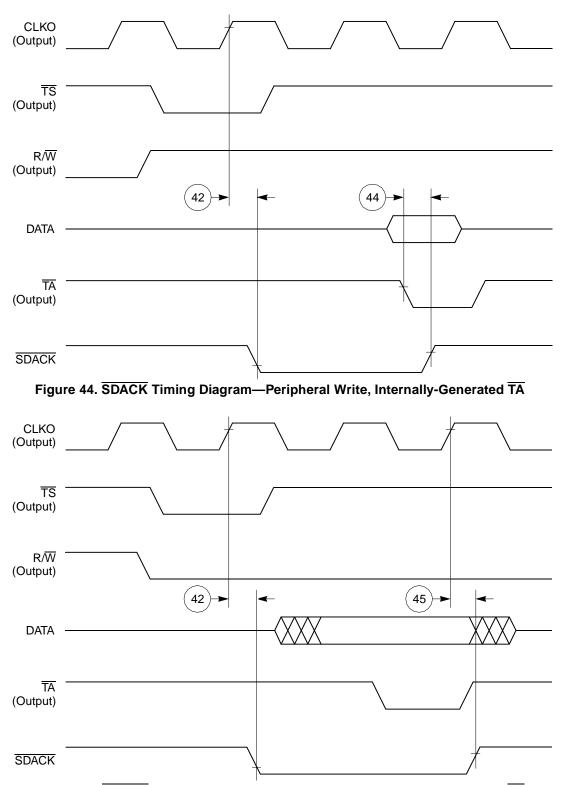
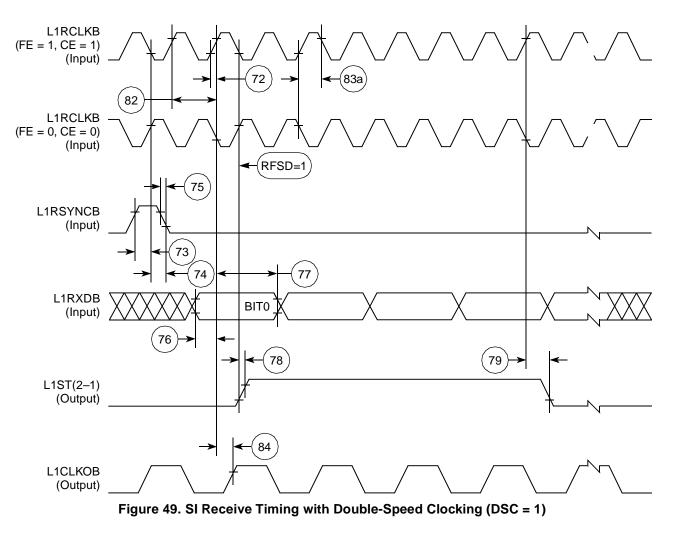


Figure 45. SDACK Timing Diagram—Peripheral Read, Internally-Generated TA

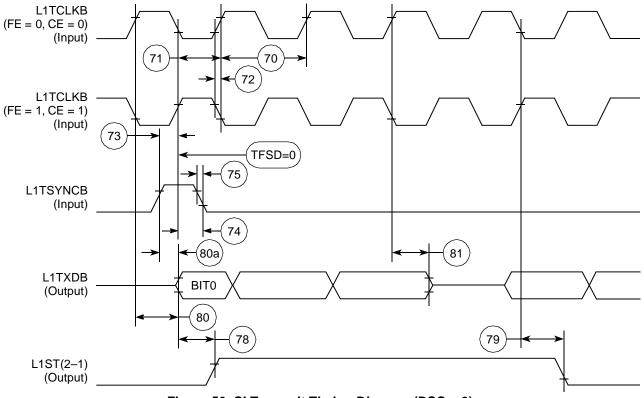


CPM Electrical Characteristics





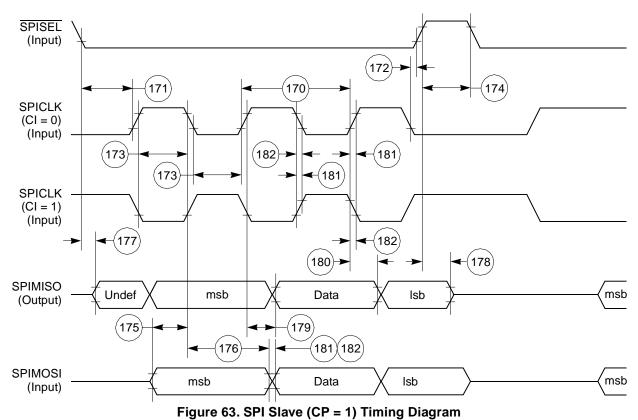
CPM Electrical Characteristics







CPM Electrical Characteristics



13.11 I²C AC Electrical Specifications

Table 28 provides the I^2C (SCL < 100 kHz) timings.

Table 28	. I ² C Timin	g (SCL < 100) kHz)
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Num	Characteristic	All Freq	uencies	Unit
Num	Characteristic	Min	Max	Onit
200	SCL clock frequency (slave)	0	100	kHz
200	SCL clock frequency (master) ¹	1.5	100	kHz
202	Bus free time between transmissions	4.7	_	μs
203	Low period of SCL	4.7	_	μs
204	High period of SCL	4.0	-	μs
205	Start condition setup time	4.7	-	μs
206	Start condition hold time	4.0		μs
207	Data hold time	0		μs
208	Data setup time	250	_	ns
209	SDL/SCL rise time	_	1	μs



14 USB Electrical Characteristics

This section provides the AC timings for the USB interface.

14.1 USB Interface AC Timing Specifications

The USB Port uses the transmit clock on SCC1. Table 30 lists the USB interface timings.

Table 30. USB Interface AC Timing Specifications

Name	Characteristic	All Freq	Unit	
Name		Min	Max	onne
US1	USBCLK frequency of operation ¹ Low speed Full speed	6	6 8	MHz
US4	USBCLK duty cycle (measured at 1.5 V)	45	55	%

¹ USBCLK accuracy should be ±500 ppm or better. USBCLK may be stopped to conserve power.

15 FEC Electrical Characteristics

This section provides the AC electrical specifications for the Fast Ethernet controller (FEC). Note that the timing specifications for the MII signals are independent of system clock frequency (part speed designation). Also, MII signals use TTL signal levels compatible with devices operating at either 5.0 or 3.3 V.

15.1 MII and Reduced MII Receive Signal Timing

The receiver functions correctly up to a MII_RX_CLK maximum frequency of 25 MHz + 1%. The reduced MII (RMII) receiver functions correctly up to a RMII_REFCLK maximum frequency of 50 MHz + 1%. There is no minimum frequency requirement. In addition, the processor clock frequency must exceed the MII_RX_CLK frequency -1%.

Table 31 provides information on the MII receive signal timing.

Num	Characteristic	Min	Мах	Unit
M1	MII_RXD[3:0], MII_RX_DV, MII_RX_ER to MII_RX_CLK setup	5	_	ns
M2	MII_RX_CLK to MII_RXD[3:0], MII_RX_DV, MII_RX_ER hold	5	_	ns
M3	MII_RX_CLK pulse width high	35%	65%	MII_RX_CLK period
M4	MII_RX_CLK pulse width low	35%	65%	MII_RX_CLK period
M1_RMII	RMII_RXD[1:0], RMII_CRS_DV, RMII_RX_ERR to RMII_REFCLK setup	4		ns
M2_RMII	RMII_REFCLK to RMII_RXD[1:0], RMII_CRS_DV, RMII_RX_ERR hold	2		ns

Table 31. MII Receive Signal Timing



Name	Pin Number	Туре
IP_A6	F4	Input (3.3 V only)
IP_A7	C2	Input (3.3 V only)
ALE_B, DSCK	C8	Bidirectional Three-state (3.3 V only)
IP_B[0:1], IWP[0:1], VFLS[0:1]	B8, D9	Bidirectional (3.3 V only)
OP0	B6	Bidirectional (3.3 V only)
OP1	C6	Output
OP2, MODCK1, STS	B5	Bidirectional (3.3 V only)
OP3, MODCK2, DSDO	B2	Bidirectional (3.3 V only)
BADDR[28:29]	E8, C5	Output
BADDR30, REG	D8	Output
ĀS	C7	Input (3.3 V only)
PA15, USBRXD	P14	Bidirectional
PA14, USBOE	U16	Bidirectional (Optional: open-drain)
PA11, RXD4, MII1-TXD0, RMII1-TXD0	R9	Bidirectional (Optional: open-drain) (5-V tolerant)
PA10, MII1-TXERR, TIN4, CLK7	R12	Bidirectional (Optional: open-drain) (5-V tolerant)
PA7, CLK1, BRGO1, TIN1	R11	Bidirectional
PA6, CLK2, TOUT1	P11	Bidirectional
PA4, CTS4, MII1-TXD1, RMII-TXD1	P7	Bidirectional
PA3, MII1-RXER, RMII1-RXER, BRGO3	R5	Bidirectional (5-V tolerant)
PA2, MII1-RXDV, RMII1-CRS_DV, TXD4	N6	Bidirectional (5-V tolerant)
PA1, MII1-RXD0, RMII1-RXD0, BRGO4	Τ4	Bidirectional (5-V tolerant)
PA0, MII1-RXD1, RMII1-RXD1, TOUT4	P6	Bidirectional (5-V tolerant)
PB31, <u>SPISEL</u> , MII1-TXCLK, RMII1-REFCLK	Т5	Bidirectional (Optional: open-drain) (5-V tolerant)

Table 36. Pin Assignments—JEDEC Standard (continued)



Name	Pin Number	Туре
PB30, SPICLK	T17	Bidirectional (Optional: open-drain) (5-V tolerant)
PB29, SPIMOSI	R17	Bidirectional (Optional: open-drain) (5-V tolerant)
PB28, SPIMISO, BRGO4	R14	Bidirectional (Optional: open-drain) (5-V tolerant)
PB27, I2CSDA, BRGO1	N13	Bidirectional (Optional: open-drain)
PB26, I2CSCL, BRGO2	N12	Bidirectional (Optional: open-drain)
PB25, SMTXD1	U13	Bidirectional (Optional: open-drain) (5-V tolerant)
PB24, SMRXD1	T12	Bidirectional (Optional: open-drain) (5-V tolerant)
PB23, SDACK1, SMSYN1	U12	Bidirectional (Optional: open-drain)
PB19, MII1-RXD3, RTS4	T11	Bidirectional (Optional: open-drain)
PC15, DREQ0, L1ST1	R15	Bidirectional (5-V tolerant)
PC13, MII1-TXD3, SDACK1	U9	Bidirectional (5-V tolerant)
PC12, MII1-TXD2, TOUT1	T15	Bidirectional (5-V tolerant)
PC11, USBRXP	P12	Bidirectional
PC10, USBRXN, TGATE1	U11	Bidirectional
PC7, <u>CTS4</u> , L1TSYNCB, USBTXP	T10	Bidirectional (5-V tolerant)
PC6, CD4 , L1RSYNCB, USBTXN	P10	Bidirectional (5-V tolerant)
PD8, RXD4, MII-MDC, RMII-MDC	Т3	Bidirectional (5-V tolerant)
PE31, CLK8, L1TCLKB, MII1-RXCLK	P9	Bidirectional (Optional: open-drain)
PE30, L1RXDB, MII1-RXD2	R8	Bidirectional (Optional: open-drain)

Table 36. Pin Assignments—JEDEC Standard (continued)



Name	Pin Number	Туре
TDO, DSDO	P13	Output (5-V tolerant)
MII1_CRS	U10	Input
MII_MDIO	M13	Bidirectional (5-V tolerant)
MII1_TX_EN, RMII1_TX_EN	U5	Output (5-V tolerant)
MII1_COL	R10	Input
V _{SSSYN}	E5	PLL analog GND
V _{SSSYN1}	F6	PLL analog GND
V _{DDSYN}	E6	PLL analog V _{DD}
GND	H8, H9, H10, H11, J8, J9, J10, J11, K8, K9, K10, K11, L8, L9, L10, L11, U15	Power
V _{DDL}	F7, F8, F9, F10, F11, H6, H13, J6, J13, K6, K13, L6, L13, N7, N8, N9, N10, N11	Power
V _{DDH}	G7, G8, G9, G10, G11, G12, H7, H12, J7, J12, K7, K12, L7, L12, M7, M8, M9, M10, M11, M12	Power
N/C	B17, T16, U2, U17	No connect

Table 36. Pin Assignments—JEDEC Standard (continued)



Document Revision History

17 Document Revision History

Table 37 lists significant changes between revisions of this hardware specification.

Table 37. Document Revision History

Revision Number	Date	Changes
0	2/2003	Initial release.
0.1	3/2003	Took out the time-slot assigner and changed the SCC for SCC3 to SCC4.
0.2	5/2003	Changed the package drawing, removed all references to Data Parity. Changed the SPI Master Timing Specs. 162 and 164. Added the RMII and USB timing. Added the 80-MHz timing.
0.3	5/2003	Made sure the pin types were correct. Changed the Features list to agree with the MPC885.
0.4	5/2003	Corrected the signals that had overlines on them. Made corrections on two pins that were typos.
0.5	5/2003	Changed the pin descriptions for PD8 and PD9.
0.6	5/2003	Changed a few typos. Put back the I ² C. Put in the new reset configuration, corrected the USB timing.
0.7	6/2003	Changed the pin descriptions per the June 22 spec, removed Utopia from the pin descriptions, changed PADIR, PBDIR, PCDIR and PDDIR to be 0 in the Mandatory Reset Config.
0.8	8/2003	Added the reference to USB 2.0 to the Features list and removed 1.1 from USB on the block diagrams.
0.9	8/2003	Changed the USB description to full-/low-speed compatible.
1.0	9/2003	Added the DSP information in the Features list. Put a new sentence under Mechanical Dimensions. Fixed table formatting. Nontechnical edits. Released to the external web.
1.1	10/2003	Added TDMb to the MPC875 Features list, the MPC875 Block Diagram, added 13.5 Serial Interface AC Electrical Specifications, and removed TDMa from the pin descriptions.
2.0	12/2003	Changed DBGC in the Mandatory Reset Configuration to X1. Changed the maximum operating frequency to 133 MHz. Put the timing in the 80 MHz column. Put in the orderable part numbers. Rounded the timings to hundredths in the 80 MHz column. Put the pin numbers in footnotes by the maximum currents in Table 6. Changed 22 and 41 in the Timing. Put TBD in the Thermal table.